## CS 4803 / 7643: Deep Learning

Topics:

- Regularization
- Neural Networks
- Optimization
- Computing Gradients

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## Recap from last time

## Parametric Approach: Linear Classifier



## Error Decomposition



### Example with an image with 4 pixels, and 3 classes (cat/dog/ship)



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## Linear Classifier: Three Viewpoints

 $f(x,W) = Wx$ 



One template per class



Algebraic Viewpoint | Visual Viewpoint | Geometric Viewpoint

**Hyperplanes** cutting up space



### **Recall from last time**: Linear Classifier





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### TODO:

- 1. Define a **loss function** that quantifies our unhappiness with the scores across the training data.
- 1. Come up with a way of efficiently finding the parameters that minimize the loss function. **(optimization)**

### Softmax vs. SVM

$$
L_i = -\log(\tfrac{e^{s_{y_i}}}{\sum_j e^{s_j}}) \hspace{1cm} L_i = \textstyle \sum_{j \neq y_i} \max(0, s_j - s_{y_i} + 1)
$$

Suppose: 3 training examples, 3 classes. With some W the scores  $f(x, W) = Wx$  are:







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$$

 $s = f(x_i;$ 



Want to interpret raw classifier scores as **probabilities**

$$
\boxed{W]} \qquad \boxed{P(Y=k|X=x_i) = \frac{e^{s_k}}{\sum_j e^{s_j}} \begin{array}{l} \text{Softmax} \\ \text{Function} \end{array}}
$$



 $s = f(x_i;W)$ 



cat car

frog



Want to interpret raw classifier scores as **probabilities**

$$
\left| P(Y=k|X=x_i) = \tfrac{e^{s_k}}{\sum_j e^{s_j}} \right| \text{ Softmax}_{\text{Function}}
$$

cat

car



Want to interpret raw classifier scores as **probabilities**



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Log-Likelihood// KL-Divergence //Cross-Entropy  $D = \{ (x_i, y_i) \}$ mox P<br>mox log  $\sum$ log P (yi) xi)  $\equiv m\omega$  $\mathcal{L}$ 









## Plan for Today

- Regularization
- Neural Networks
- Optimization
- Computing Gradients

$$
L(W) = \frac{1}{N} \sum_{i=1}^{N} L_i(f(x_i, W), y_i)
$$

**Data loss**: Model predictions should match training data



from doing *too* well on training data

 $\lambda$  = regularization strength



**Data loss**: Model predictions should match training data

**Regularization**: Prevent the model from doing *too* well on training data

## Regularization: Prefer Simpler Models



Polynomial Regression  $y' = w_0 + w_1 x$  $W_0 + W_1 \times + W_2 \times^2 + \cdots$ =  $W_0 + W_1 X + W_2 X + \cdots$  $=2(x,y)$  $y_i - \hat{y}_i$  $w^* = \frac{m m}{2}$ 

## Polynomial Regression



## Polynomial Regression

- Demo:
	- https://arachnoid.com/polysolve/
- Data:
	- 10 6
	- $-159$
	- $-2011$
	- $-2512$
	- $-2913$
	- $-4011$
	- $-5010$
	- 60 9

 $\lambda$  = regularization strength



**Data loss**: Model predictions should match training data

**Regularization**: Prevent the model from doing *too* well on training data



**Data loss**: Model predictions should match training data

**Regularization**: Prevent the model from doing *too* well on training data

**Simple examples** L2 regularization:  $R(W) = \sum_{k} \sum_{k} W_{k,k}^2$ L1 regularization:  $R(W) = \sum_k \sum_l [\widetilde{W_{k,l}}]$ Elastic net (L1 + L2):  $R(W) = \sum_k \sum_l \beta W_{k,l}^2 + |W_{k,l}|$ 

 $\lambda$  = regularization strength (hyperparameter)

$$
L(W) = \frac{1}{N} \sum_{i=1}^{N} L_i(f(x_i, W), y_i) + \lambda R(W)
$$

**Data loss**: Model predictions should match training data

**Regularization**: Prevent the model from doing *too* well on training data

#### **Simple examples**

L2 regularization:  $R(W) = \sum_k \sum_l W_{k,l}^2$ L1 regularization:  $R(W) = \sum_k \sum_l |W_{k,l}|$ Elastic net (L1 + L2):  $\overline{R(W)} = \sum_k \sum_l \beta W_{k,l}^2 + |W_{k,l}|$ 

**More complex**: Dropout \ Batch normalization \ Stochastic depth, fracti<u>onal pooling, e</u>tq

 $\lambda$  = regularization strength (hyperparameter)

$$
L(W) = \frac{1}{N} \sum_{i=1}^{N} L_i(f(x_i, W), y_i) + \lambda R(W)
$$

**Data loss**: Model predictions should match training data

 $\overline{N}$ 

**Regularization**: Prevent the model from doing *too* well on training data

 $\mathbf{1}^{\mathcal{N}}$ 

Why regularize?

- **Express preferences over weights**
- Make the model *simple* so it works on test data
- Improve optimization by adding curvature

Slide Credit: Fei-Fei Li, Justin Johnson, Serena Yeung, CS 231n

### Recap

- We have some dataset of  $(x,y)$
- We have a **score function:**

$$
s=f(x;W)\overset{\mathtt{e.g.}}{=}Wx
$$

- We have a **loss function**:





### Recap

How do we find the best W?

- We have some dataset of  $(x,y)$
- We have a **score function:**

$$
s=f(x;W)\overset{\mathtt{e.g.}}{=} Wx
$$

- We have a **loss function**:





## Error Decomposition



### Next: Neural Networks

(**Before**) Linear score function:  $f = \underline{Wx}$ 

 $f = W_2 W_1 x$ 

(**Before**) Linear score function:

(**Now**) 2-layer Neural Network

$$
f = Wx
$$
  

$$
f = W_2 \underbrace{\overbrace{\max} (0, \overline{W_1x})}_{W_2}
$$



Slide Credit: Fei-Fei Li, Justin Johnson, Serena Yeung, CS 231n



(**Before**) Linear score function:  $f = Wx$ (Now) 2-layer Neural Network  $f = W_2 \max(0, W_1 x)$ or 3-layer Neural Network  $f = W_3 \max(0, W_2 \max(0, W_1 x))$ 

### Full implementation of training a 2-layer Neural Network needs ~20 lines:

```
import numpy as np
 \mathbf{1}from numpy.random import randn
 \overline{2}3
    N, D_in, H, D_out = 64, 1000, 100, 10
 \overline{4}x, y = \text{randn}(N, D_in), \text{randn}(N, D.out)5
    w1, w2 = \text{randn}(D_in, H), randn(H, D_out)
 6
 \overline{7}for t in range(2000):
8
       h = 1 / (1 + np.exp(-x.dot(w1)))9
      y pred = h.dot(w2)
10
      loss = np.sqrt(y_pred - y).sum()11print(t, loss)
1213
14
       grad_y_pred = 2.0 * (y_pred - y)grad_w2 = h.T.dot(grad_y pred)15<sub>1</sub>grad_h = grad_y pred.dot(w2.T)
16
       grad_w1 = x.T.dot(grad_h * h * (1 - h))17
18
      w1 - 1e-4 * grad_w119
20
      w2 = 1e-4 * grad_w2
```


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Impulses carried toward cell body



 $f(a) = a$  $f = \vec{k}$  $f(\alpha) = m\alpha x(0,\alpha)$ 



### Be very careful with your brain analogies!

#### **Biological Neurons:**

- Many different types
- Dendrites can perform complex non-linear computations
- Synapses are not a single weight but a complex non-linear dynamical system
- Rate code may not be adequate

[Dendritic Computation. London and Hausser]

## Activation functions





## A quick note



Fig. 4. (a) Not recommended: the standard logistic function,  $f(x) = 1/(1 + e^{-x})$ . (b) Hyperbolic tangent,  $f(x) = 1.7159 \tanh(\frac{2}{3}x)$ .

## Rectified Linear Units (ReLU)



## Limitation

- A single "neuron" is still a linear decision boundary
- What to do?
- Idea: Stack a bunch of them together!

## Multilayer Networks

- Cascade Neurons together
- The output from one layer is the input to the next
- Each Layer has its own sets of weights



## Neural networks: Architectures



## Demo Time

• https://playground.tensorflow.org

# Optimization





### Strategy: **Follow the slope**

In 1-dimension, the derivative of a function;

$$
\frac{df(x)}{dx} = \lim_{h \to 0} \frac{f(x+h) - f(x)}{h}
$$



In multiple dimensions, the **gradient** is the vector of (partial derivatives) along each dimension

The slope in any direction is the **dot product** of the direction with the gradient The direction of steepest descent is the **negative gradient**



While True:<br>

While True:<br>
(weights\_grad = evaluate\_gradient(loss\_fun, data, weights)<br>
weights += - step\_size \* weights\_grad # perform parameter update # Vanilla Gradient Descent while True:

 $J^{(o)}$  = init  $A = mv$ <br> $f = t = 1 - \frac{1}{2}$ 





