## CS 4803 / 7643: Deep Learning

Topics:

- Regularization
- Neural Networks

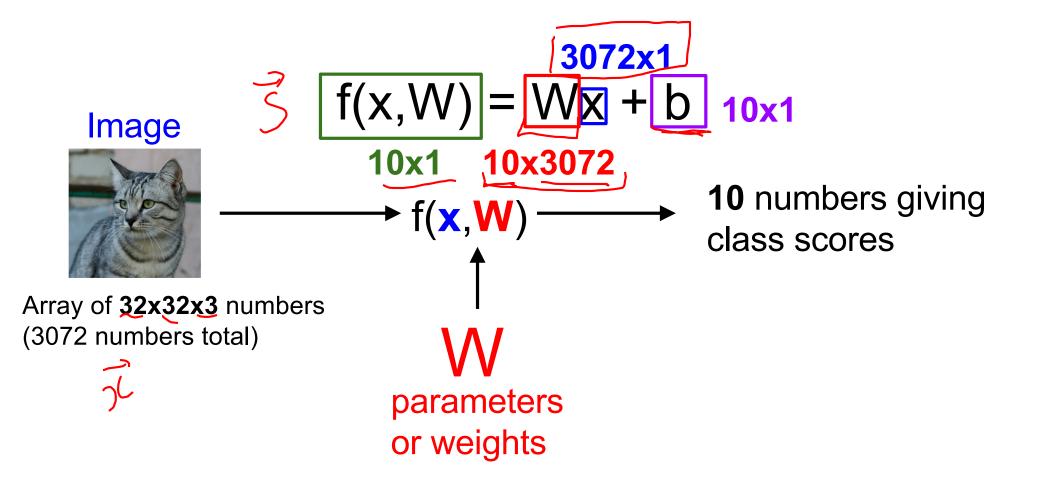
Dhruv Batra Georgia Tech

## Administrativia

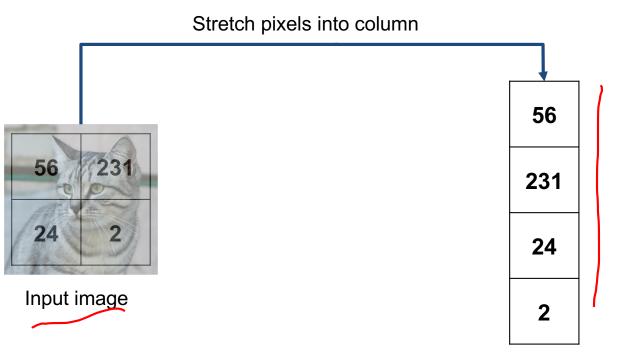
- PS1/HW1 out
  - Available later today on Canvas
  - Due in 4 weeks
  - Asks about topics coming in the next couple of weeks
  - Please please please start early
  - More details next class

## Recap from last time

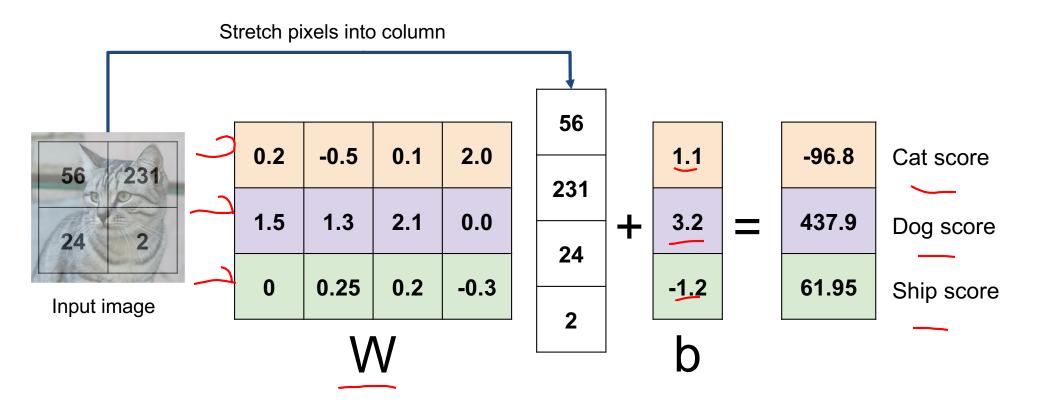
## Parametric Approach: Linear Classifier

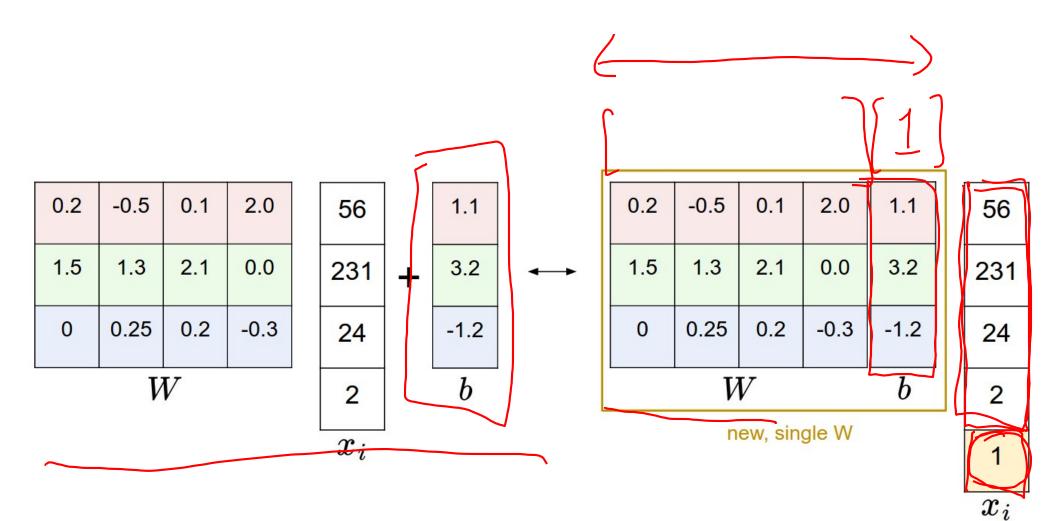


#### Example with an image with 4 pixels, and 3 classes (cat/dog/ship)

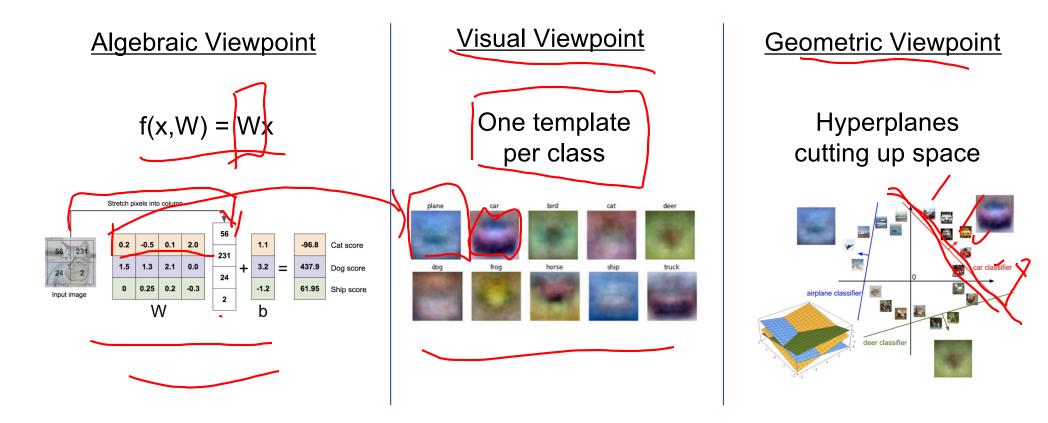


Example with an image with 4 pixels, and 3 classes (cat/dog/ship)





## Linear Classifier: Three Viewpoints



## **Recall from last time:** Linear Classifier



automobile	0.07	0.04	4.64
bird	0.09	5.31	2.65
cat	2.9	-4.22	5.1
deer	4.48	-4.19	2.64
dog	8.02	3.58	5.55
frog	3.78	4.49	-4.34
horse	1.06	-4.37	-1.5
ship	-0.36	-2.09	-4.79
truck	-0.72	-2.93	6.14

airplane

Nikita is licensed under CC-BY 2.0; Car image is CC0 1.0 public domain; Erog image is in the public domair

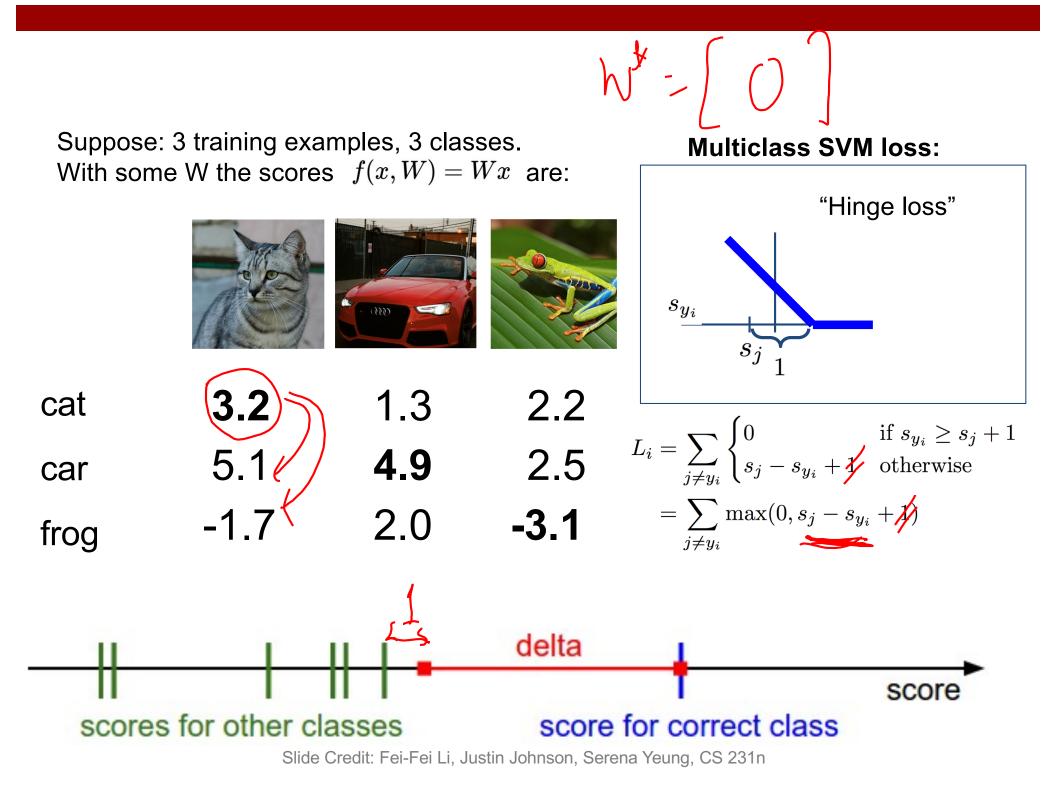
#### TODO:

Define a loss function that quantifies our unhappiness with the scores across the training data.

Come up with a way of efficiently finding the parameters that minimize the loss function. (optimization)

## Softmax vs. SVM

$$L_i = -\log(rac{e^{sy_i}}{\sum_j e^{s_j}}) \qquad \qquad L_i = \sum_{j 
eq y_i} \max(0, s_j - s_{y_i} + 1)$$



## Softmax vs. SVM

# $L_i = -\log(rac{e^{sy_i}}{\sum_j e^{s_j}})$

$$L_i = \sum_{j 
eq y_i} \max(0, s_j - s_{y_i} + 1)$$



Want to interpret raw classifier scores as **probabilities** 

$$s=f(x_i;W)$$
  $P(Y=k|X=x_i)=rac{e^{s_k}}{\sum_j e^{s_j}}$  Softmax Function

car frog

cat



cat car

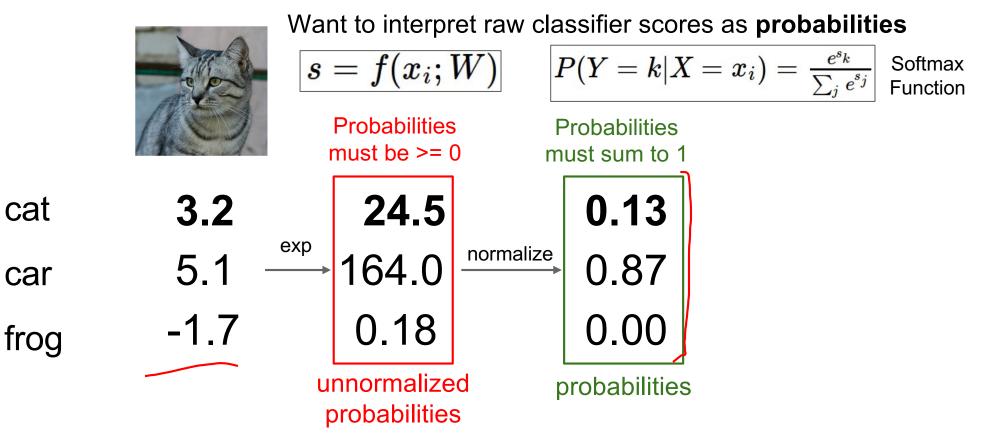
frog

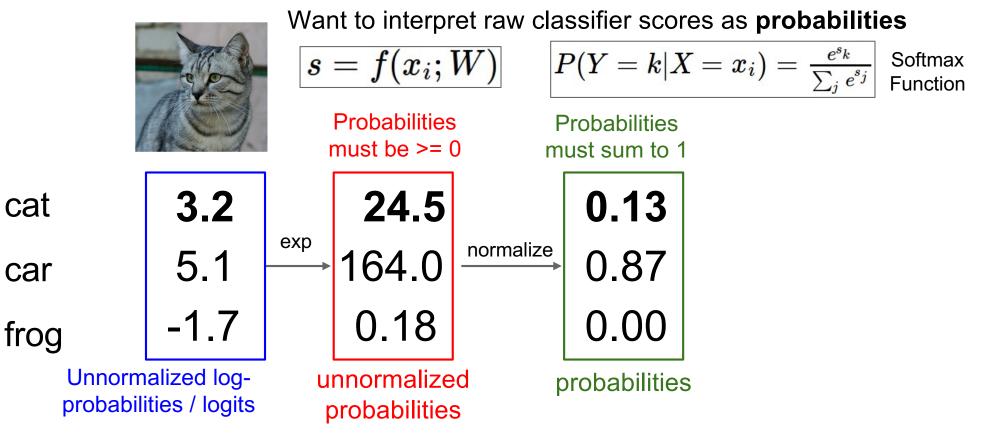


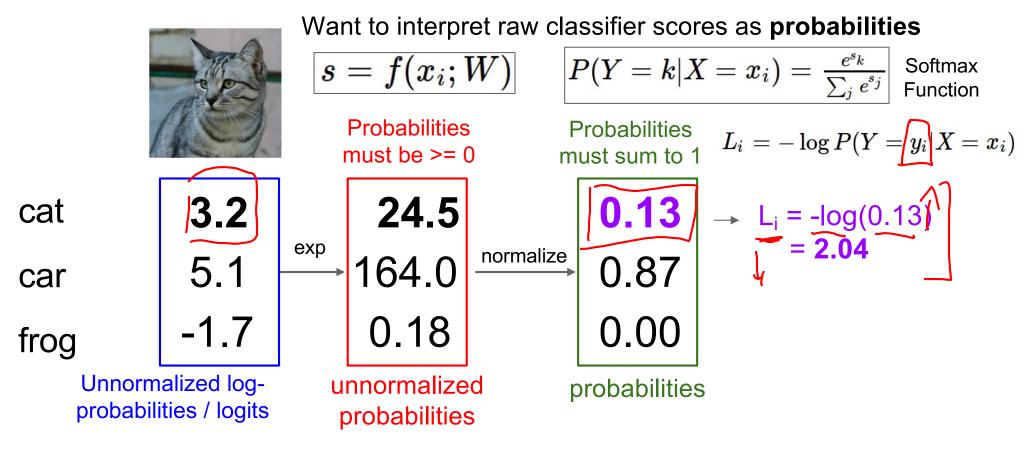
$$s = f(x_i; W)$$

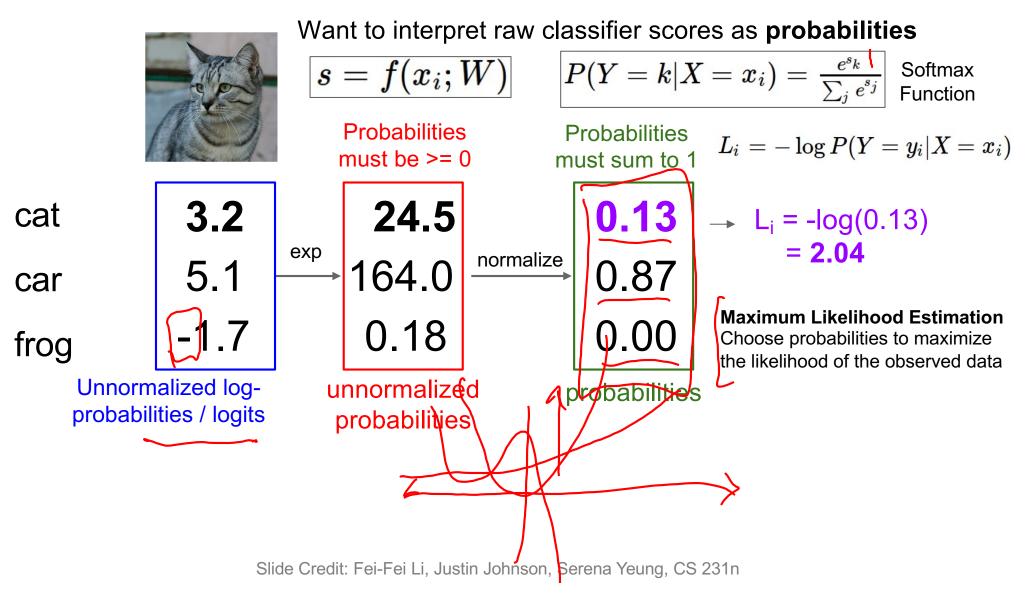
Probabilities must be >= 0

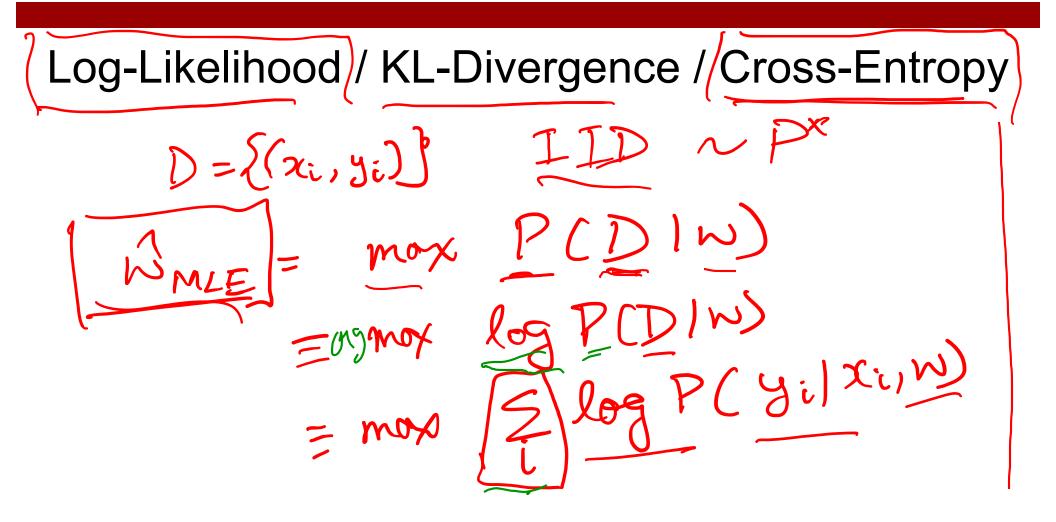
$$P(Y=k|X=x_i)=rac{e^{s_k}}{\sum_j e^{s_j}}$$
 Softmax Function

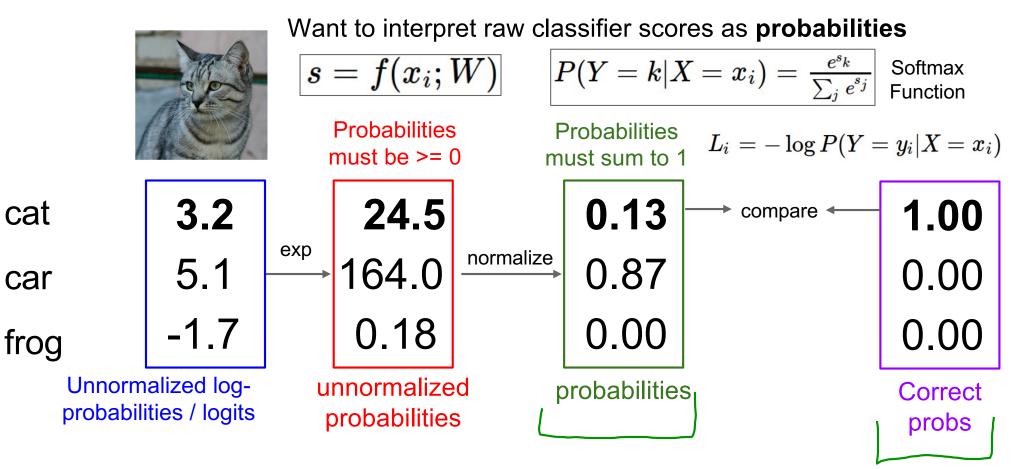


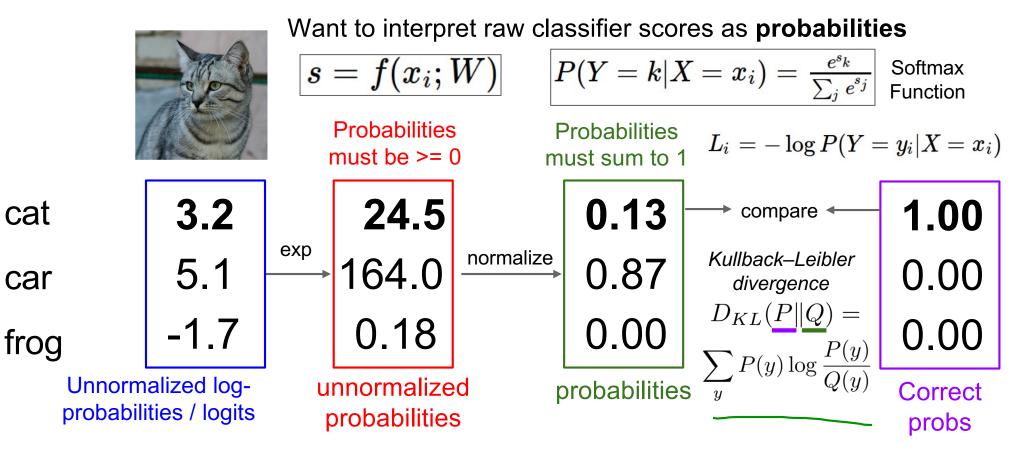


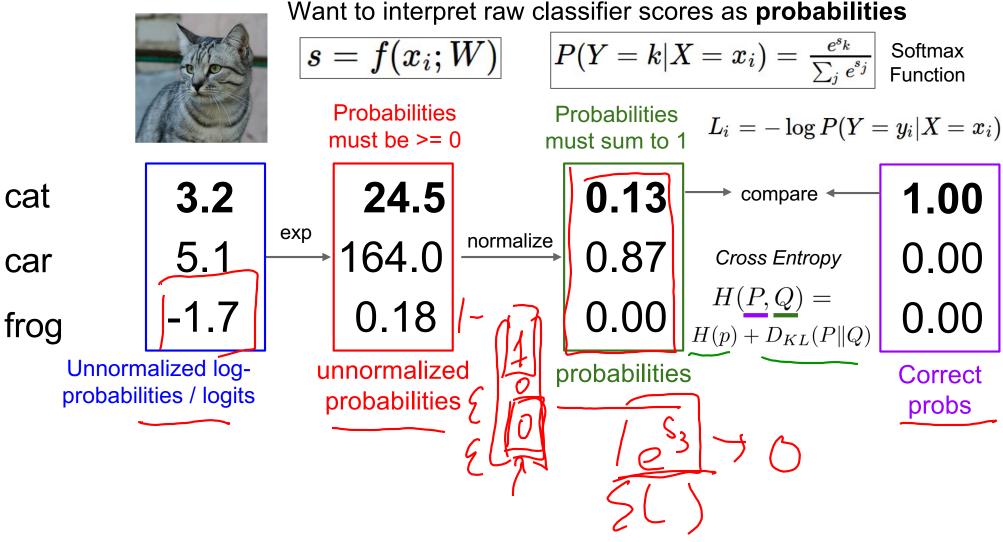












# Plan for Today

- (Finish) Loss Functions
- Regularization
- Neural Networks



cat

car

frog

Want to interpret raw classifier scores as probabilities

$$s=f(x_i;W)$$

$$P(Y=k|X=x_i)=rac{e^{s_k}}{\sum_j e^{s_j}}$$
 Softmax Function

Maximize probability of correct classPutting it all together: $L_i = -\log P(Y = y_i | X = x_i)$  $L_i = -\log((\sum_{j=0}^{e^{sy}} (x_j - 1)))$ 5.1<br/>possible loss L\_i?Q: What is the min/max<br/>possible loss L\_i?



3.2

5.1

-1.7

Want to interpret raw classifier scores as **probabilities** 

$$s = f(x_i; W)$$

 $ig| P(Y=k|X=x_i) = rac{e^{s_k}}{\sum_i e^{s_j}}$ 

Maximize probability of correct class

$$L_i = -\log P(Y = y_i | X = x_i)$$

$$L_i = -\log(\frac{e^{sy_i}}{\sum_j e^{s_j}})$$

Dutting it all together

Softmax **Function** 

car

cat

frog

Q: What is the min/max possible loss L i? A: min 0, max infinity



Want to interpret raw classifier scores as **probabilities** 

$$s = f(x_i; W)$$
  $P(Y = k | X = x_i) = rac{e^{s_k}}{\sum_j e^{s_j}}$  Softmax Function

Maximize probability of correct class  $L_i = -\log P(Y = y_i | X = x_i)$   $L_i = -\log(\frac{\int e^{sy_i}}{\sum_j | e^{sy_j}})$ Q2: At initialization all s will be approximately equal; what is the loss?

cat  $\frac{1}{2} 0$  **3.2** car  $\frac{1}{2} 0$  **5.1** frog  $\frac{1}{2} 0$  **-1.7** 



3.2

5.1

Want to interpret raw classifier scores as **probabilities** 

$$s = f(x_i; W)$$
  $P(Y = k | X = x_i) = rac{e^{s_k}}{\sum_j e^{s_j}}$  Softmax Function

Maximize probability of correct class Putting it all together:  $L_i = -\log(rac{e^{sy_i}}{\sum_i e^{s_j}})$  $L_i = -\log P(Y = y_i | X = x_i)$ 

Q2: At initialization all s will be approximately equal; what is the loss? A:  $\log(C)$ , eg  $\log(10) \approx 2.3$ 

car

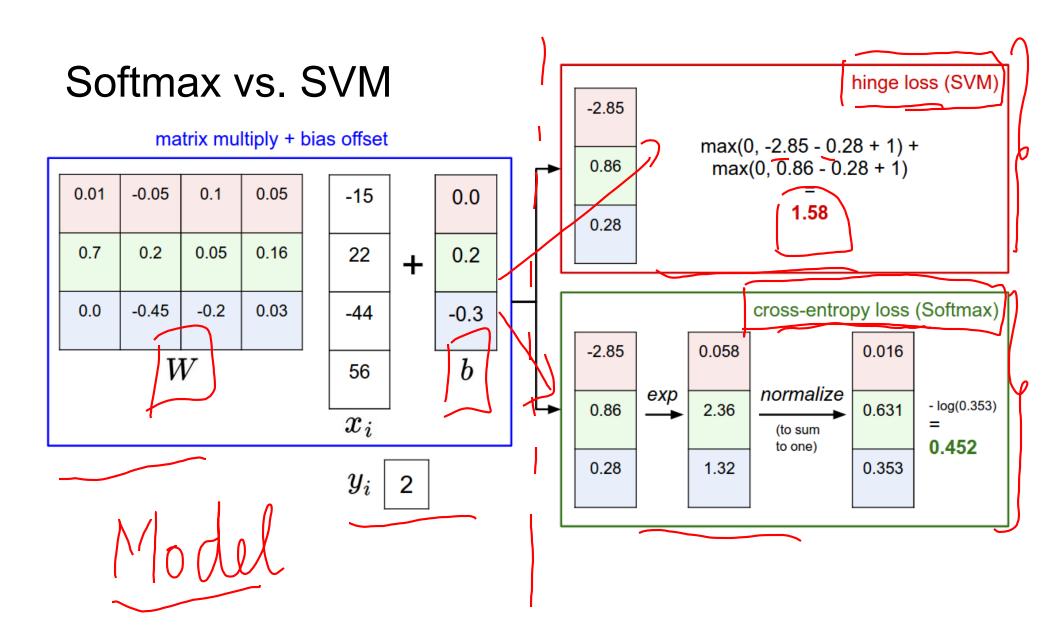
frog

cat

-1.7

## Softmax vs. SVM

$$L_i = -\log(rac{e^{sy_i}}{\sum_j e^{s_j}}) \qquad \qquad L_i = \sum_{j 
eq y_i} \max(0, s_j - s_{y_i} + 1)$$



Softmax vs. SVM
$$L_i = -\log(\frac{e^{sy_i + i}}{\sum_j e^{s_j + i}})$$
 is  $L_i = \sum_{j \neq y_i} \max(0, s_j - s_{y_i} + 1)$ 

assume scores:  

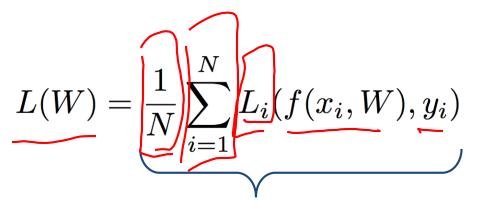
$$[10, -2, 3] \neq \{\xi, \xi\}$$
  
 $[10, 9, 9]$   
 $[10, -100, -100]$   
and  $y_i = 0$ 

Q: Suppose I take a datapoint and I jiggle a bit (changing its score slightly). What happens to the loss in both cases?

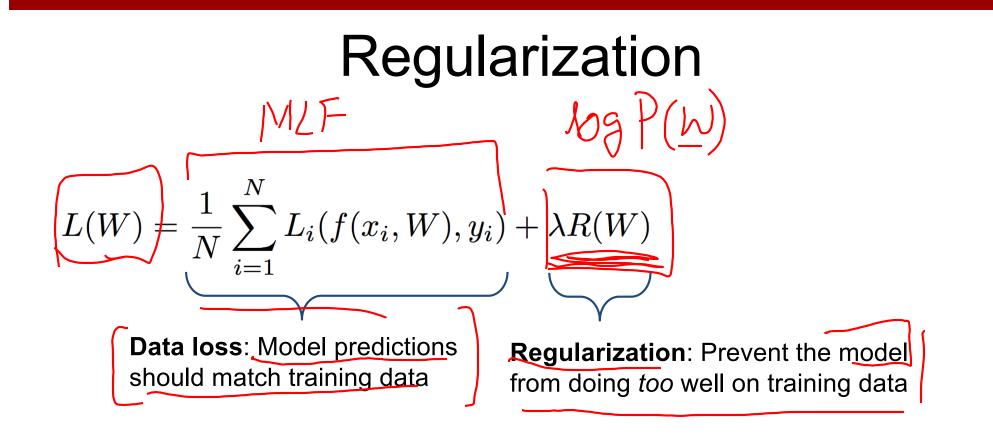
# Plan for Today

- (Finish) Loss Functions
- Regularization
- Neural Networks

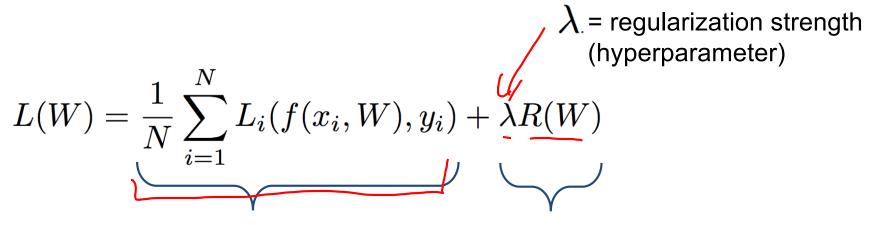
## Regularization



**Data loss**: Model predictions should match training data

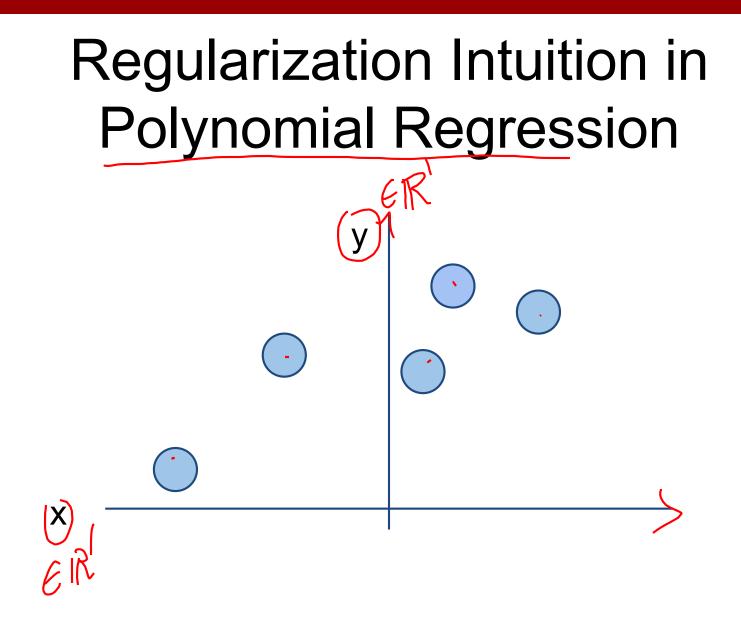


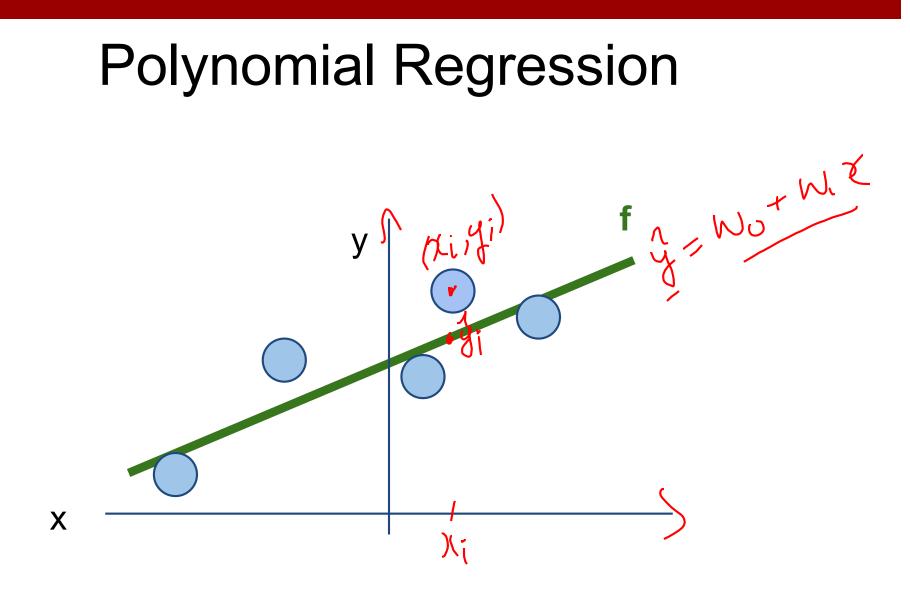
## Regularization



**Data loss**: Model predictions should match training data

**Regularization**: Prevent the model from doing *too* well on training data

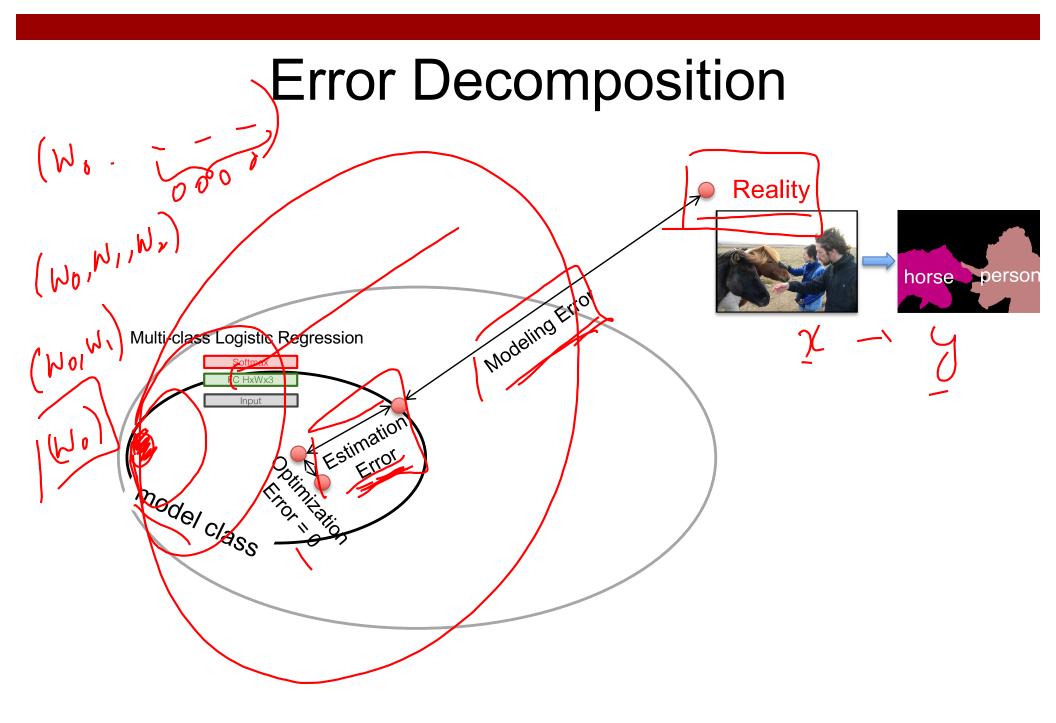




Polynomial Regression  

$$\dot{y} = W_0 + W_1 \chi \qquad 1$$
  
 $= W_0 + W_1 + H W_2 \chi^2$   
 $= W_0 + \dots + H W_2 \chi^2$   
 $= W_0 + \dots + H W_2 \chi^2$   
 $= [W_0 \dots M_d] \begin{pmatrix} 1 \\ x_1^2 \\ y_d \end{pmatrix} = \tilde{W}^T \tilde{\psi}(\chi)$ 

# **Polynomial Regression**



# **Polynomial Regression**

- Demo: <u>https://arachnoid.com/polysolve/</u>
- You are a scientist studying runners.
  - You measure average speeds of the best runners at different ages.
- Data: Age (years), Speed (mph)
  - <u>10 6</u>
  - 159
  - 20 11
  - 25 12
  - 29 13
  - 40 11
  - 50 10

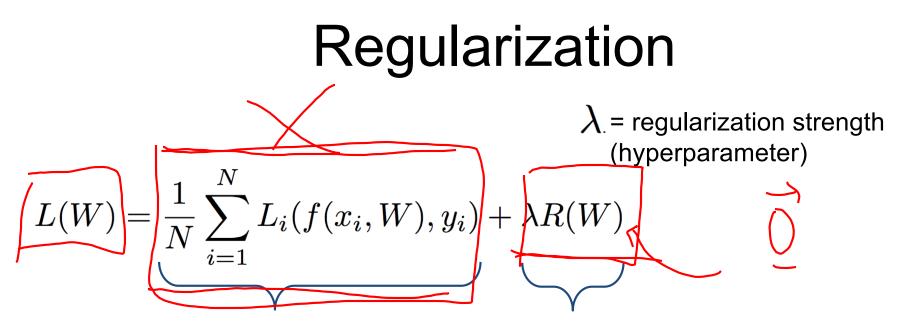
# Regularization

 $\lambda$  = regularization strength (hyperparameter)

$$L(W) = \frac{1}{N} \sum_{i=1}^{N} L_i(f(x_i, W), y_i) + \lambda R(W)$$

**Data loss**: Model predictions should match training data

**Regularization**: Prevent the model from doing *too* well on training data

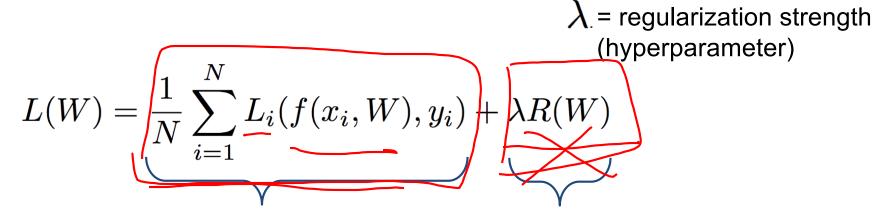


**Data loss**: Model predictions should match training data

**Regularization**: Prevent the model from doing *too* well on training data

Simple examples  
L2 regularization: 
$$R(W) = \sum_{k} \sum_{k} W_{k,l}^2$$
  
L1 regularization:  $R(W) = \sum_{k} \sum_{l} |W_{k,l}|$   
Elastic net (L1 + L2):  $R(W) = \sum_{k} \sum_{l} \beta W_{k,l}^2 + |W_{k,l}|$ 

# Regularization



**Data loss**: Model predictions should match training data

**Regularization**: Prevent the model from doing *too* well on training data

#### **Simple examples**

L2 regularization:  $R(W) = \sum_k \sum_l W_{k,l}^2$ L1 regularization:  $R(W) = \sum_k \sum_l |W_{k,l}|$ Elastic net (L1 + L2):  $R(W) = \sum_k \sum_l \beta W_{k,l}^2 + |W_{k,l}|$ 

More complex: Dropout Batch normalization Stochastic depth, fractional pooling, etc

# Regularization

 $\lambda$  = regularization strength (hyperparameter)

$$L(W) = \frac{1}{N} \sum_{i=1}^{N} L_i(f(x_i, W), y_i) + \lambda R(W)$$

Data loss: Model predictions should match training data

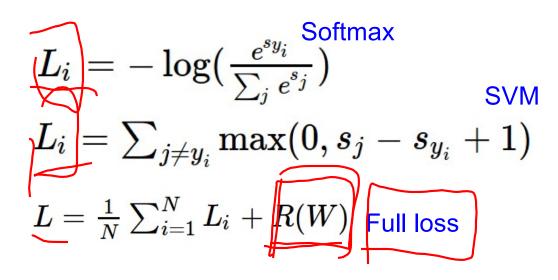
**Regularization**: Prevent the model from doing too well on training data

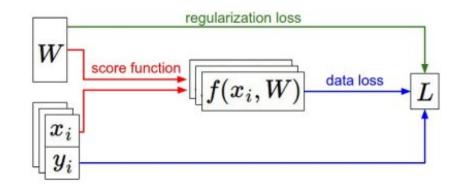
Why regularize?

- Express preferences over weights Make the model *simple* so it works on test data Improve optimization by adding curvature

# Recap

- We have some dataset of (x,y)
- We have a score function:  $s = f(x; W) \stackrel{\text{e.g}}{=} Wx$
- We have a **loss function**:





#### Recap

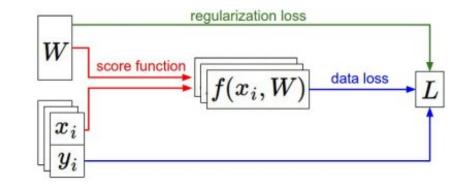
#### How do we find the best W?

- We have some dataset of (x,y)
- We have a score function:

$$s = f(x;W) \stackrel{ ext{e.g.}}{=} Wx$$

- We have a loss function:

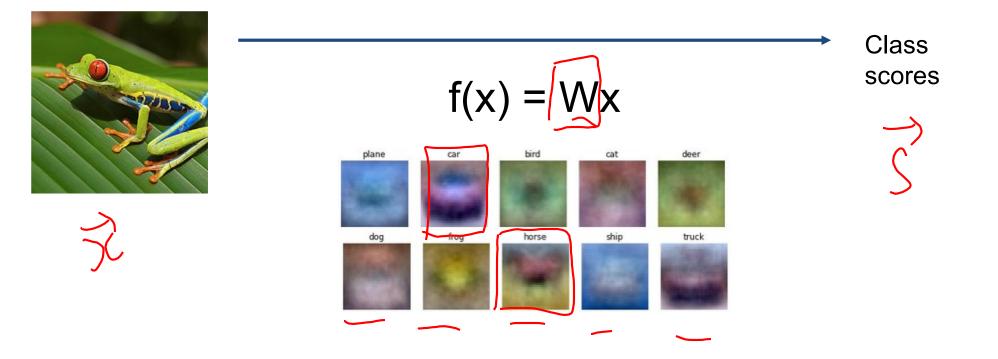
$$L_i = -\log(rac{e^{sy_i}}{\sum_j e^{s_j}})$$
 SVM $L_i = \sum_{j 
eq y_i} \max(0, s_j - s_{y_i} + 1)$  $L = rac{1}{N} \sum_{i=1}^N L_i + R(W)$  Full loss



#### Next: Neural Networks

Slide Credit: Fei-Fei Li, Justin Johnson, Serena Yeung, CS 231n

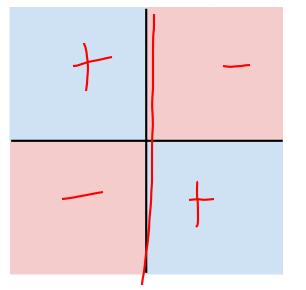
# So far: Linear Classifiers



# Hard cases for a linear classifier

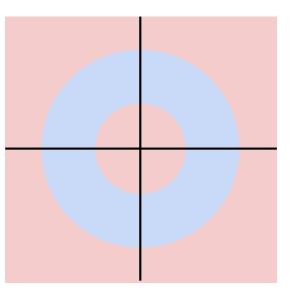
**Class 1**: First and third quadrants

**Class 2**: Second and fourth quadrants



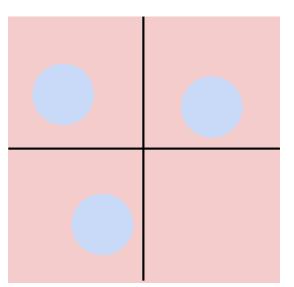
Class 1: 1 <= L2 norm <= 2

Class 2: Everything else



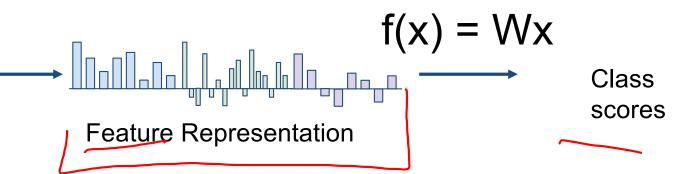
Class 1: Three modes

Class 2: Everything else

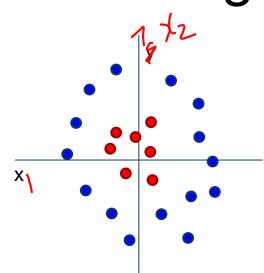


## Aside: Image Features

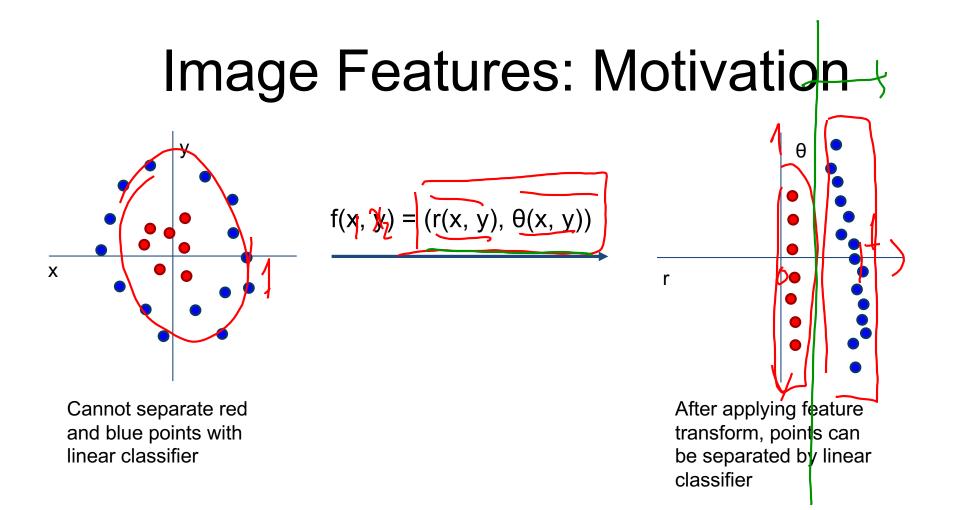




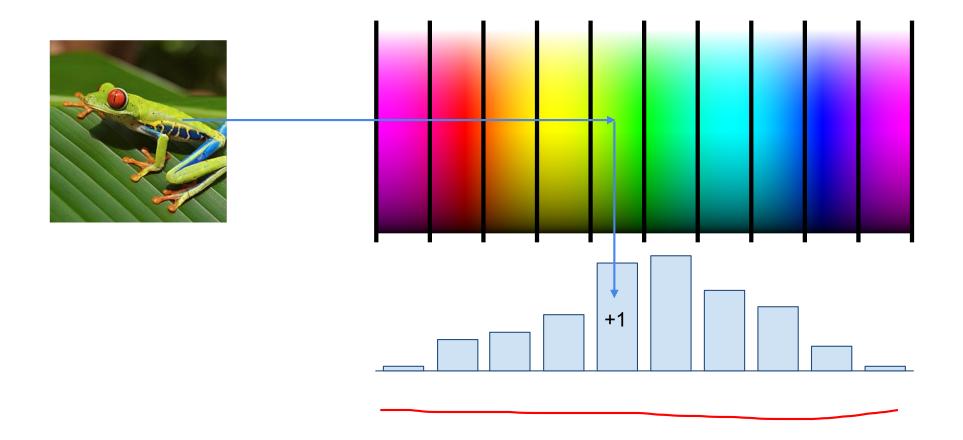
#### **Image Features: Motivation**



Cannot separate red and blue points with linear classifier



# **Example: Color Histogram**

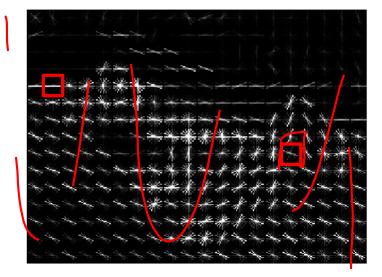


# Example: Histogram of Oriented Gradients (HoG)

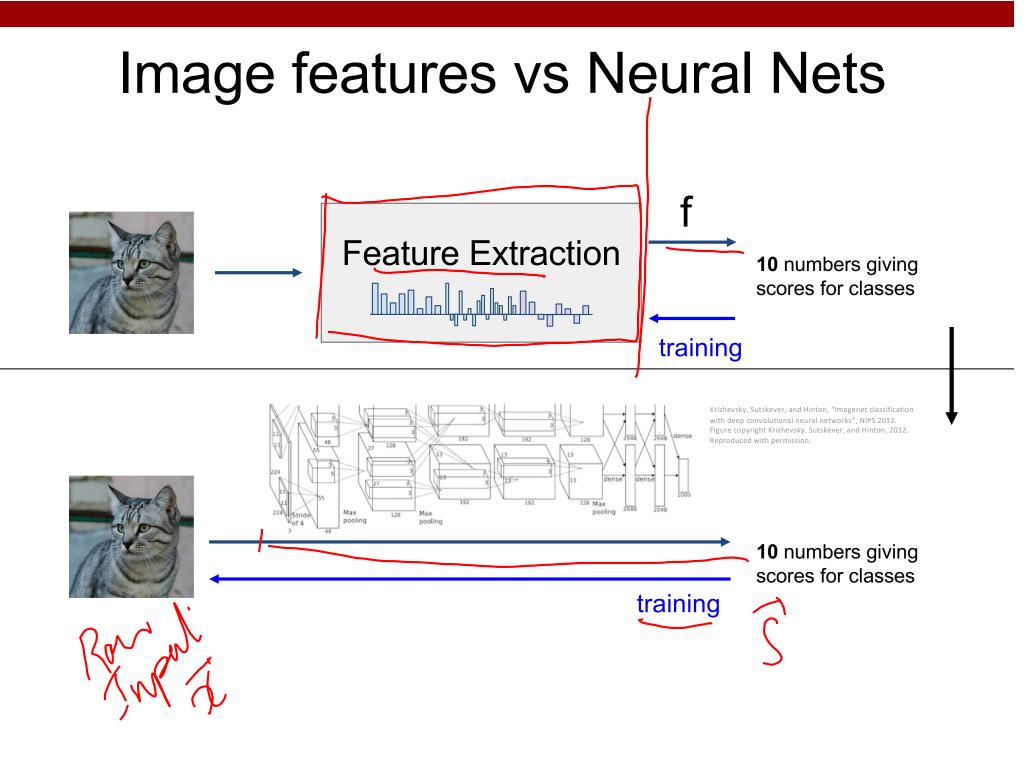


Divide image into 8x8 pixel regions Within each region quantize edge direction into 9 bins

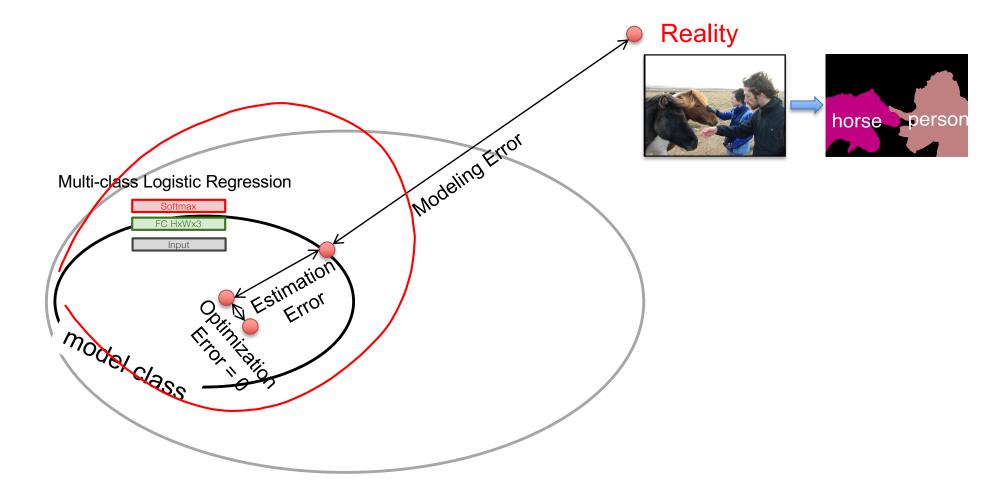
Lowe, "Object recognition from local scale-invariant features", ICCV 1999 Dalal and Triggs, "Histograms of oriented gradients for human detection," CVPR 2005



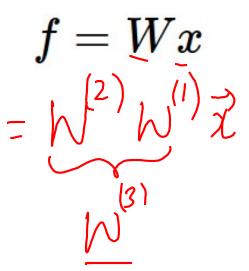
Example: 320x240 image gets divided into 40x30 bins; in each bin there are 9 numbers so feature vector has 30\*40\*9 = 10,800 numbers



# **Error Decomposition**



(**Before**) Linear score function:



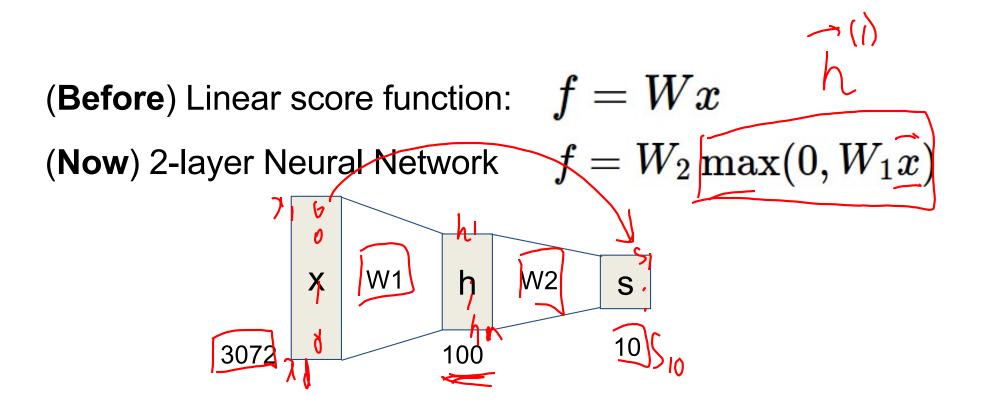
(Before) Linear score function:

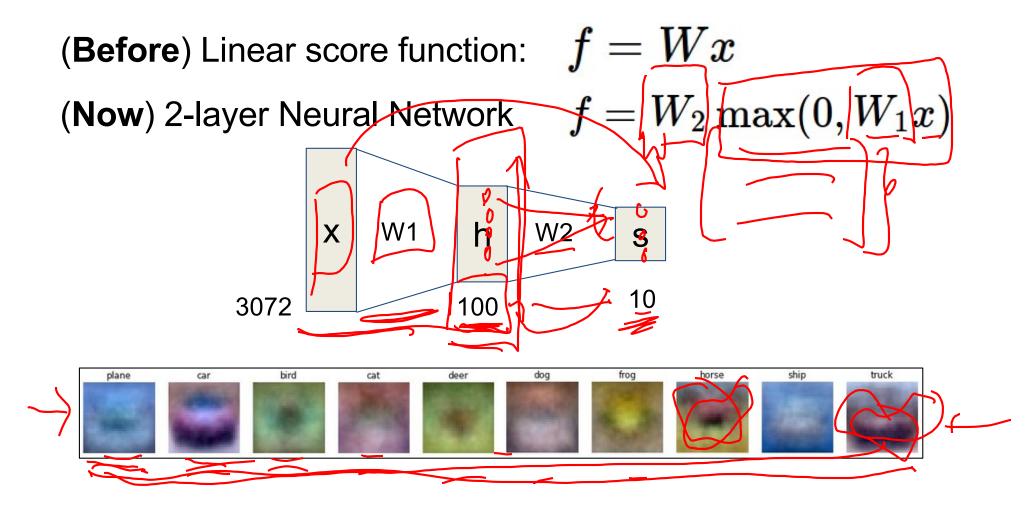
(Now) 2-layer Neural Network

$$f = Wx \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 \\ 0 & 0 \end{pmatrix}$$

$$f = W_2 \max(0, W_1 x)$$

$$(3) \chi$$



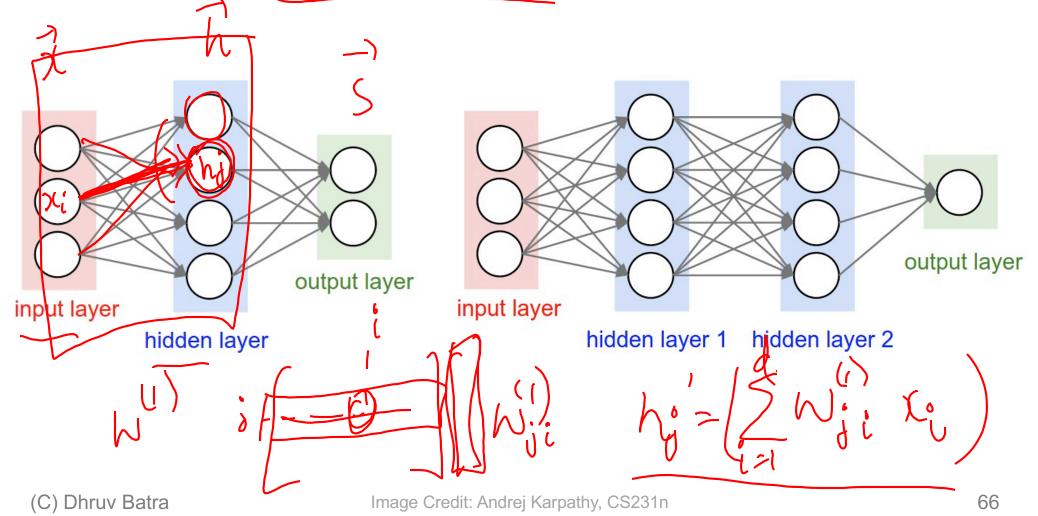


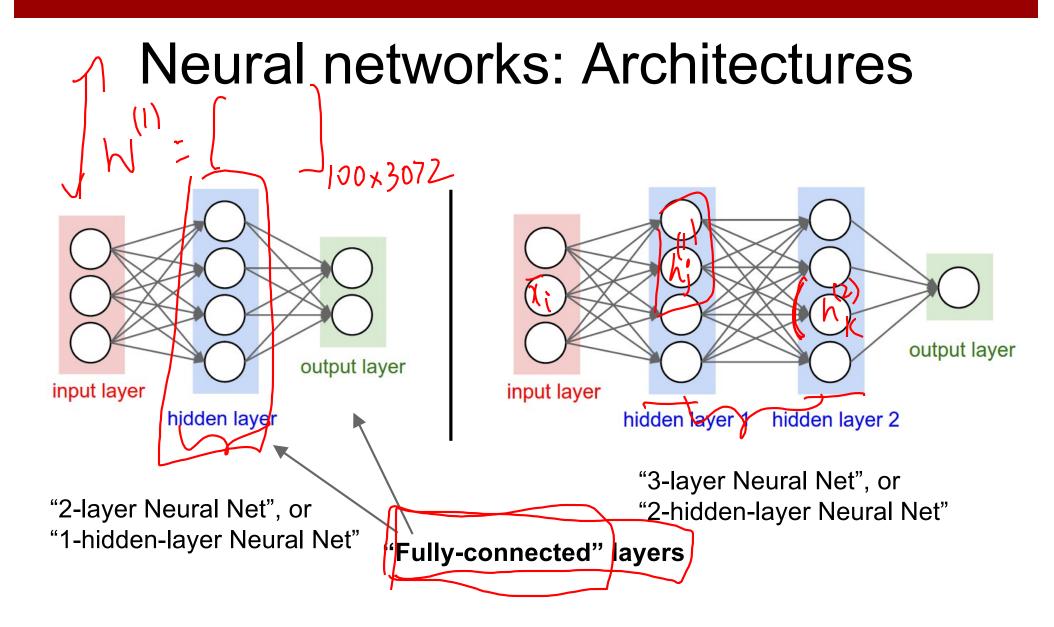
Slide Credit: Fei-Fei Li, Justin Johnson, Serena Yeung, CS 231n

# Neural networks: without the brain stuff (**Before**) Linear score function: f = Wx(Now) 2-layer Neural Network $f = W_2 \max(0, W_1 x)$ or 3-layer Neural Network $f = W_3 \max(0, W_2 \max(0, W_1 x))$ Non-lineauty

# Multilayer Networks

- Cascaded "neurons"
- The output from one layer is the input to the next
- · Each layer has its own sets of weights

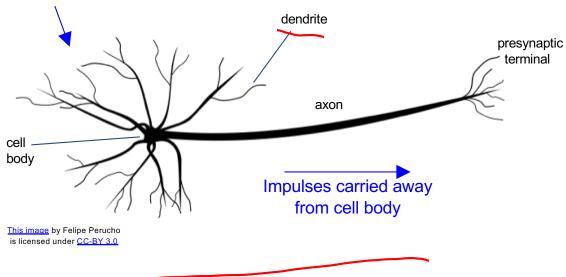




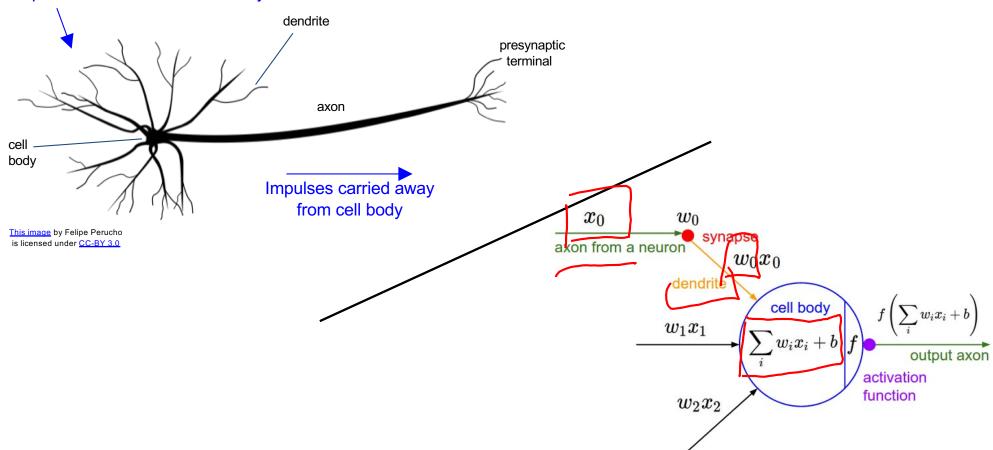


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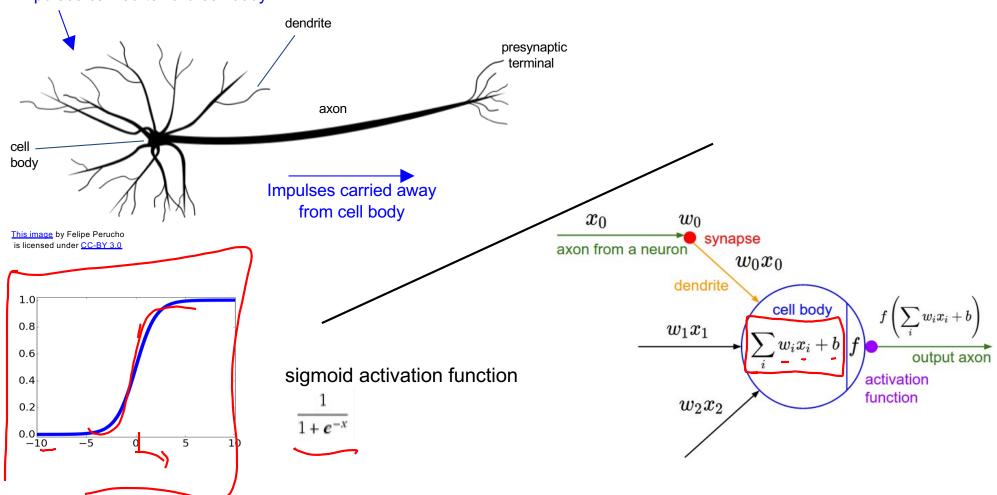
Slide Credit: Fei-Fei Li, Justin Johnson, Serena Yeung, CS 231n



Impulses carried toward cell body



Impulses carried toward cell body



Impulses carried toward cell body

Slide Credit: Fei-Fei Li, Justin Johnson, Serena Yeung, CS 231n

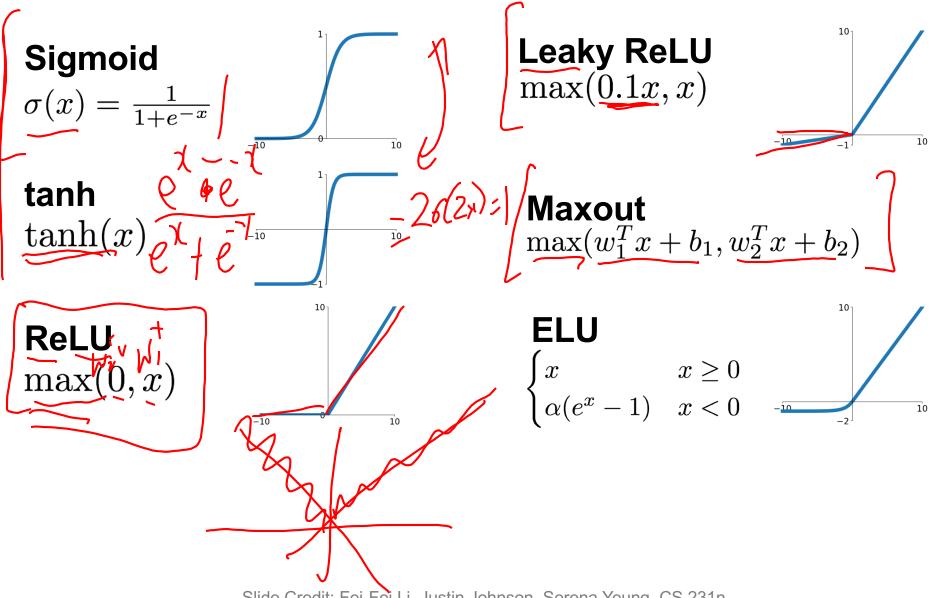
#### Be very careful with your brain analogies!

#### **Biological Neurons:**

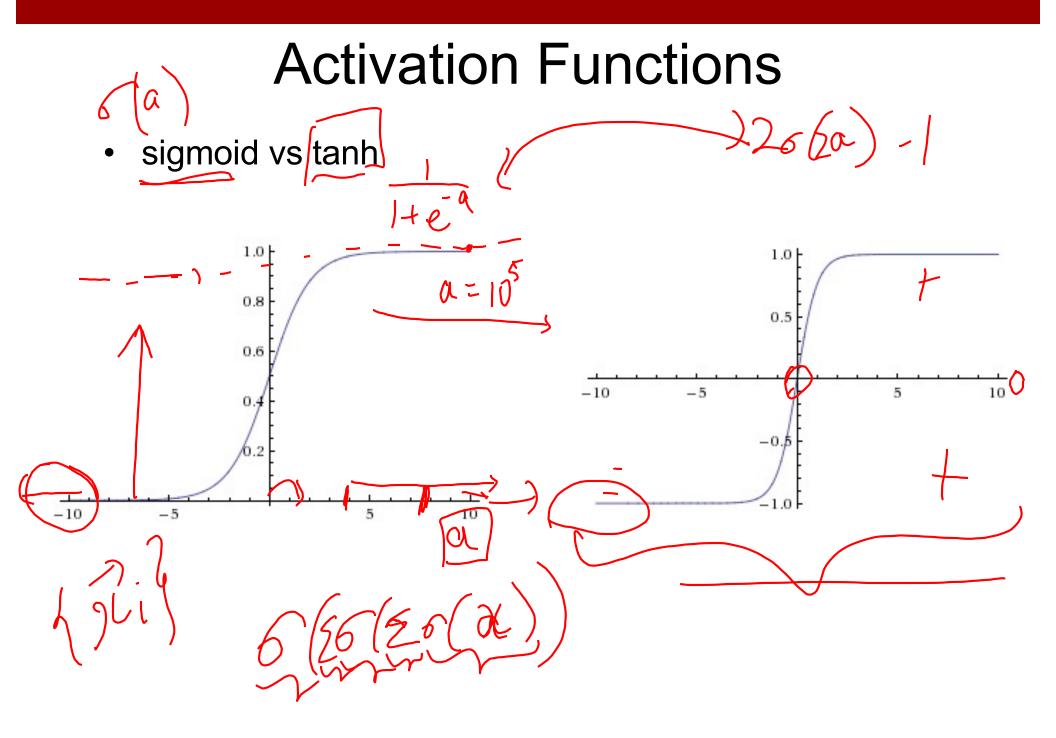
- Many different types
- Dendrites can perform complex non-linear computations
- Synapses are not a single weight but a complex non-linear dynamical system
- Rate code may not be adequate

[Dendritic Computation. London and Hausser]

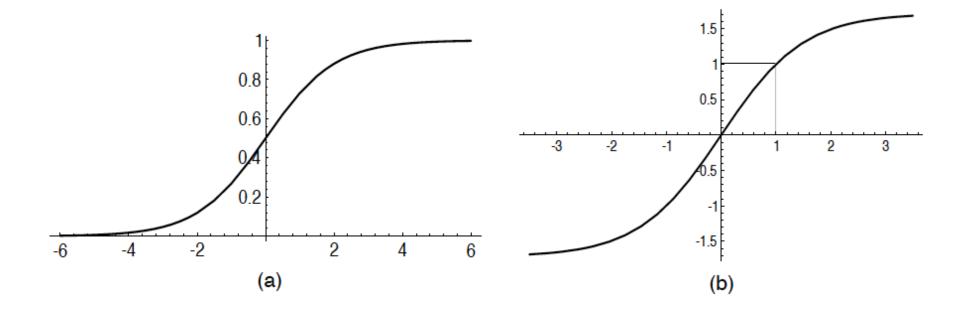
# Activation functions



Slide Credit: Fei-Fei Li, Justin Johnson, Serena Yeung, CS 231n

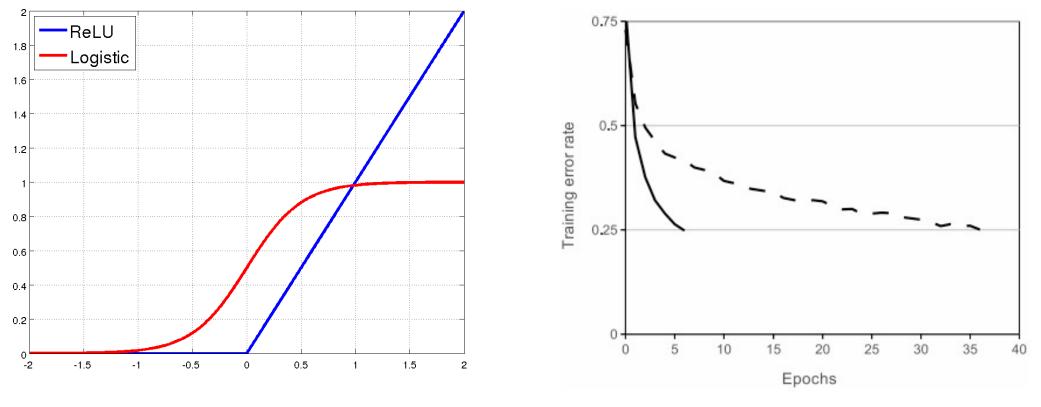


## A quick note



**Fig. 4.** (a) Not recommended: the standard logistic function,  $f(x) = 1/(1 + e^{-x})$ . (b) Hyperbolic tangent,  $f(x) = 1.7159 \tanh\left(\frac{2}{3}x\right)$ .

# Rectified Linear Units (ReLU)



[Krizhevsky et al., NIPS12]

# Demo Time

• <u>https://playground.tensorflow.org</u>