Attention, Transformers, BERT, and ViLBERT

Arjun Majumdar

Georgia Tech

Slide Credits: Andrej Karpathy, Justin Johnson, Dhruv Batra

Recall: Recurrent Neural Networks

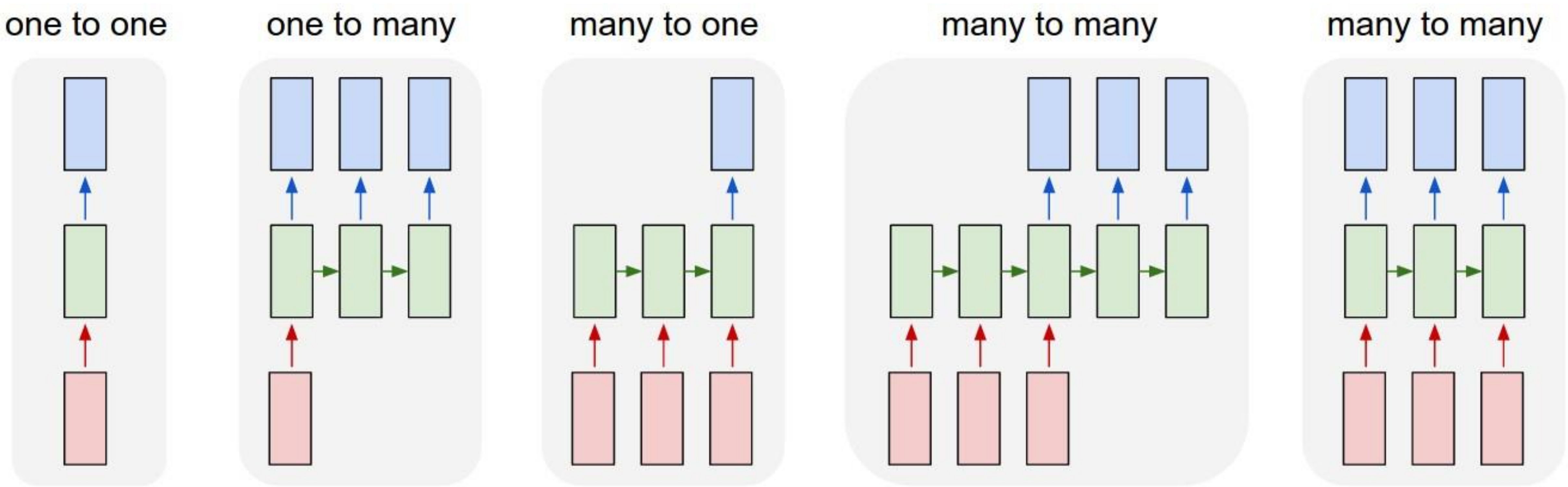
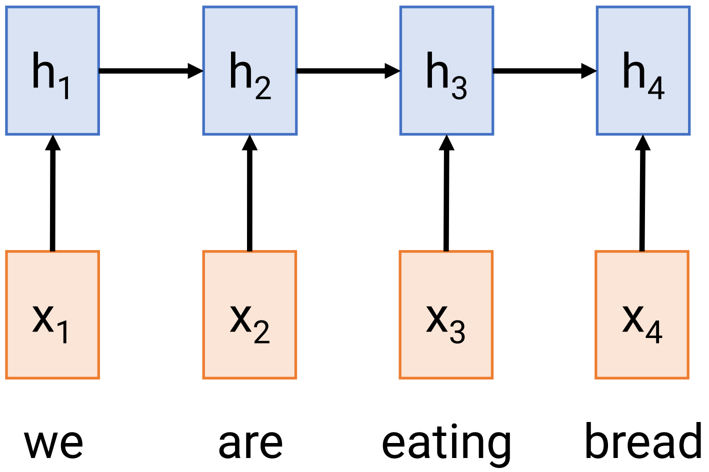


Image Credit: Andrej Karpathy

Sequence-to-Sequence with RNNs

Input: Sequence $x_1, \ldots x_T$
Output: Sequence $y_1, \ldots, y_{T'}$

Encoder: $h_t = f_W(x_t, h_{t-1})$



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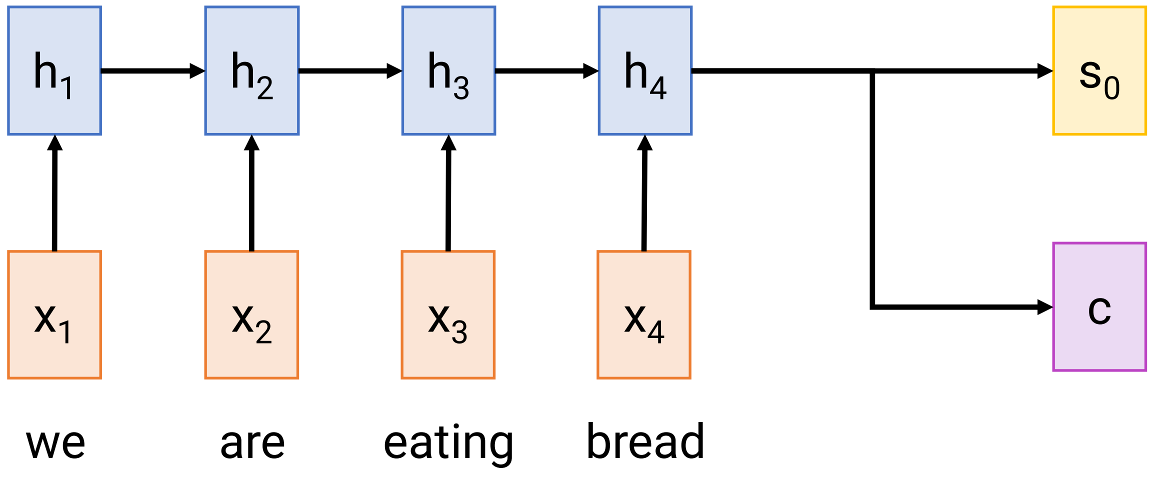
From final hidden state predict:
Initial decoder state s_0
Context vector c (often $c=h_T$)



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Sequence-to-Sequence with RNNs

Input: Sequence $x_1, \ldots x_T$
Output: Sequence $y_1, \ldots, y_{T'}$

Decoder: $s_t = g_U(y_{t-1}, h_{t-1}, c)$

Encoder: $h_t = f_W(x_t, h_{t-1})$

From final hidden state predict:
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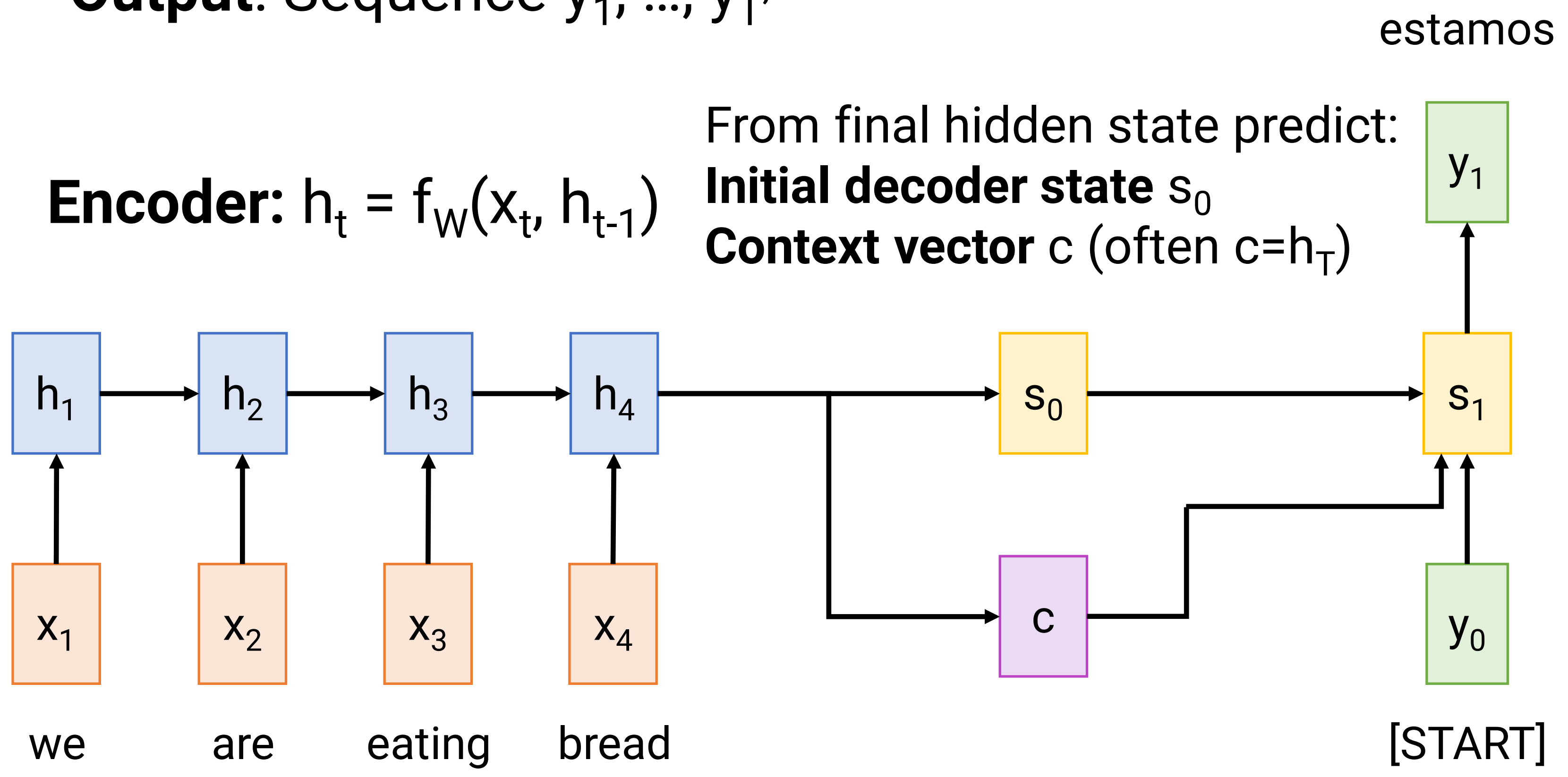
Context vector c (often $c=h_T$)



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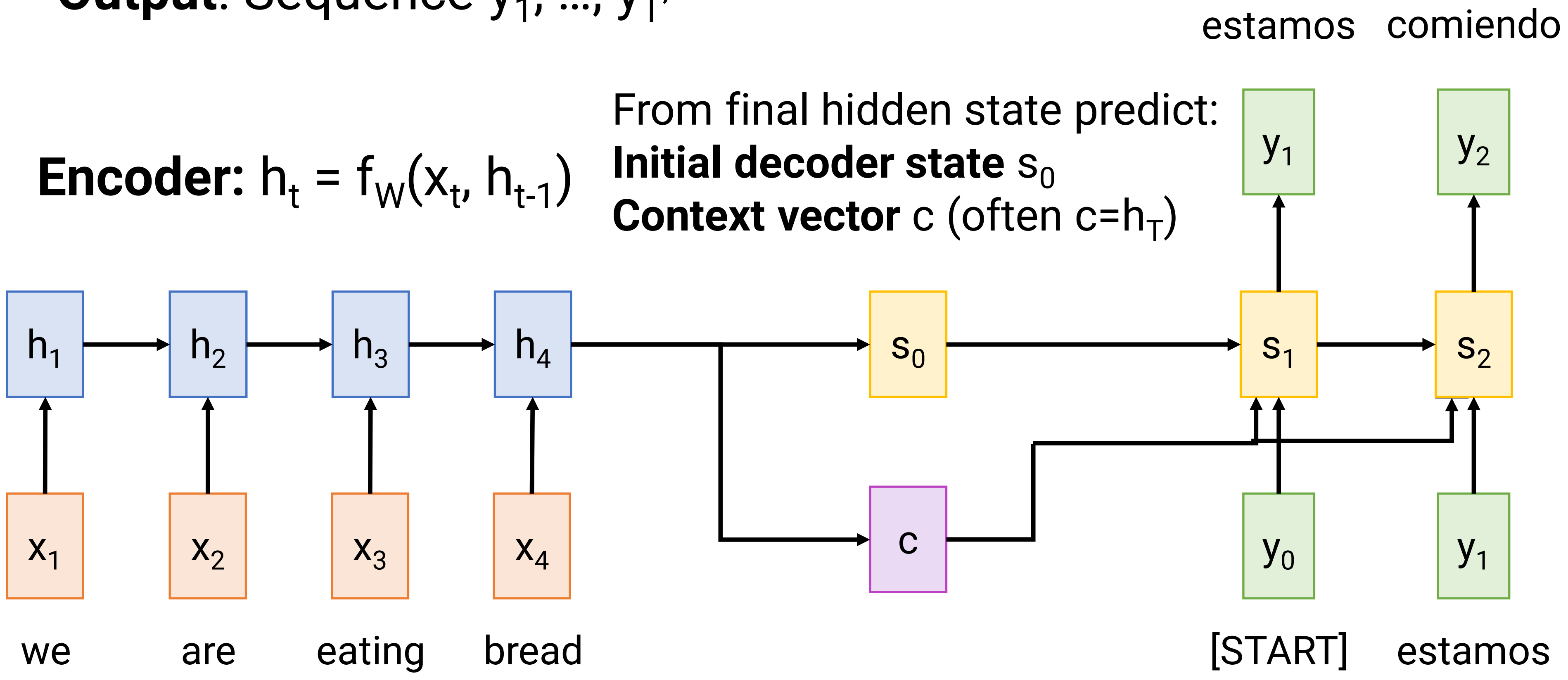

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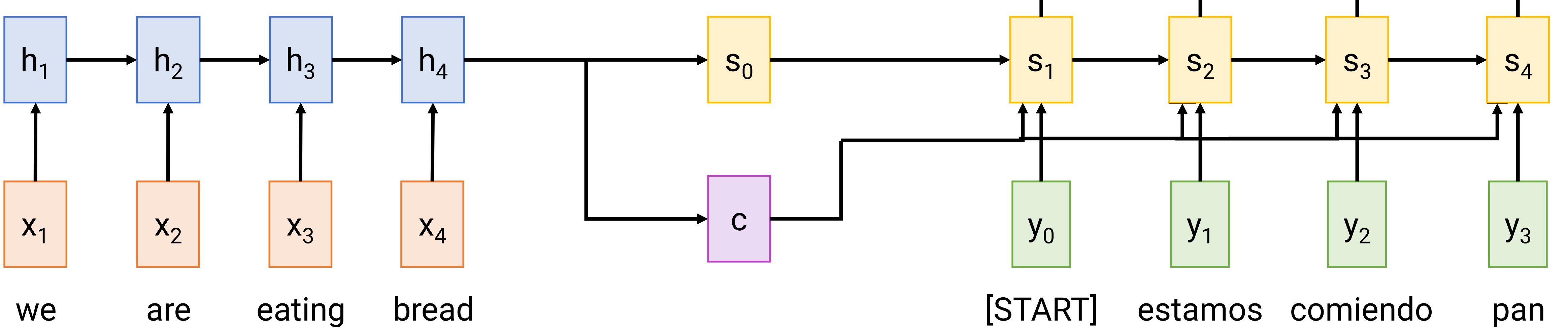

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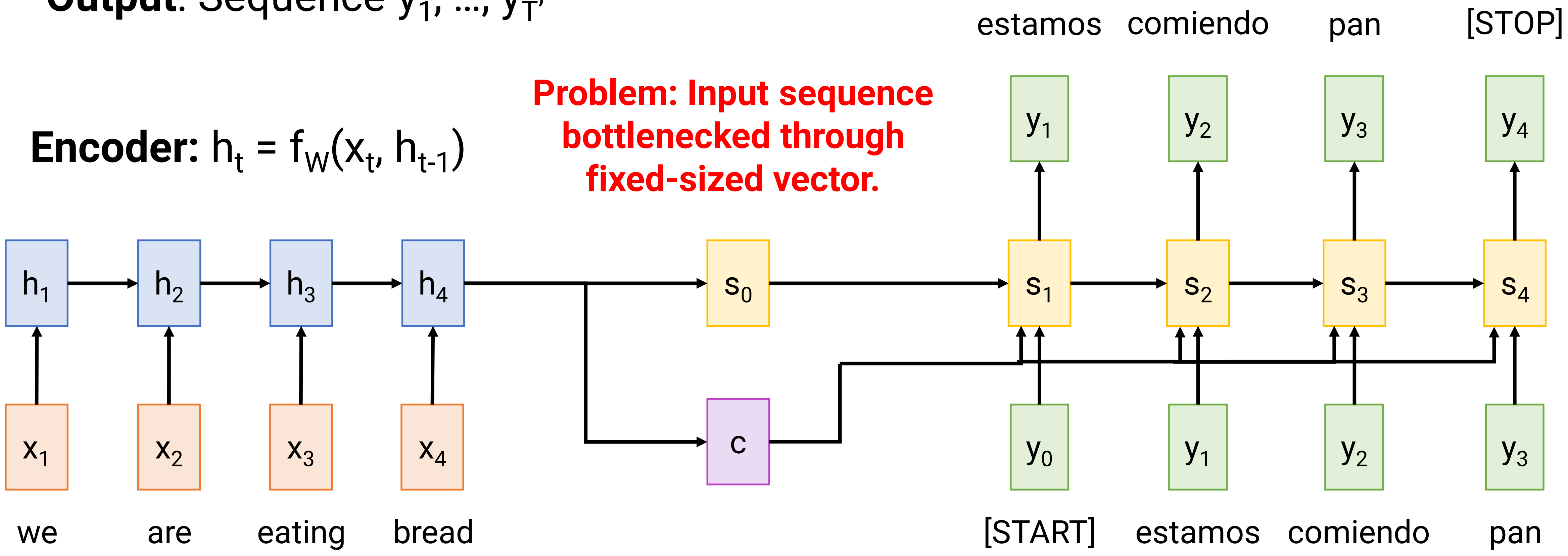
Encoder: $h_t = f_W(x_t, h_{t-1})$

Problem: Input sequence bottlenecked through fixed-sized vector.



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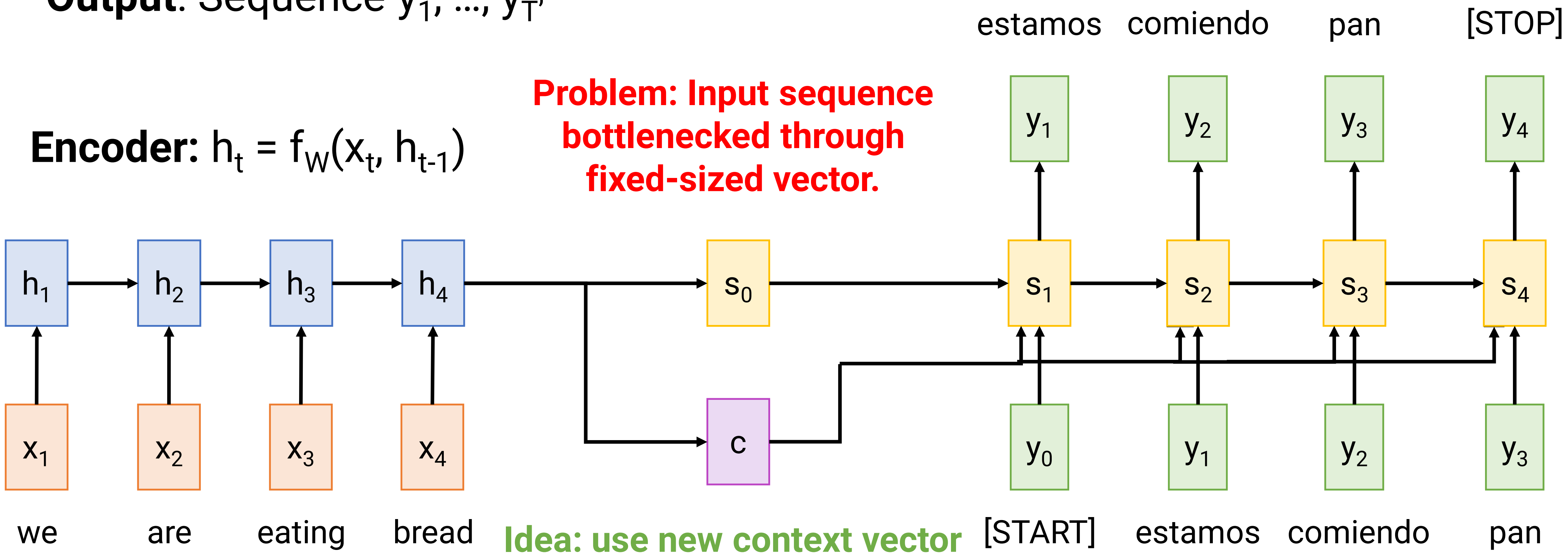

Idea: use new context vector at each step of decoder!

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Sequence-to-Sequence with RNNs **and Attention**

Input: Sequence $x_1, \dots x_T$
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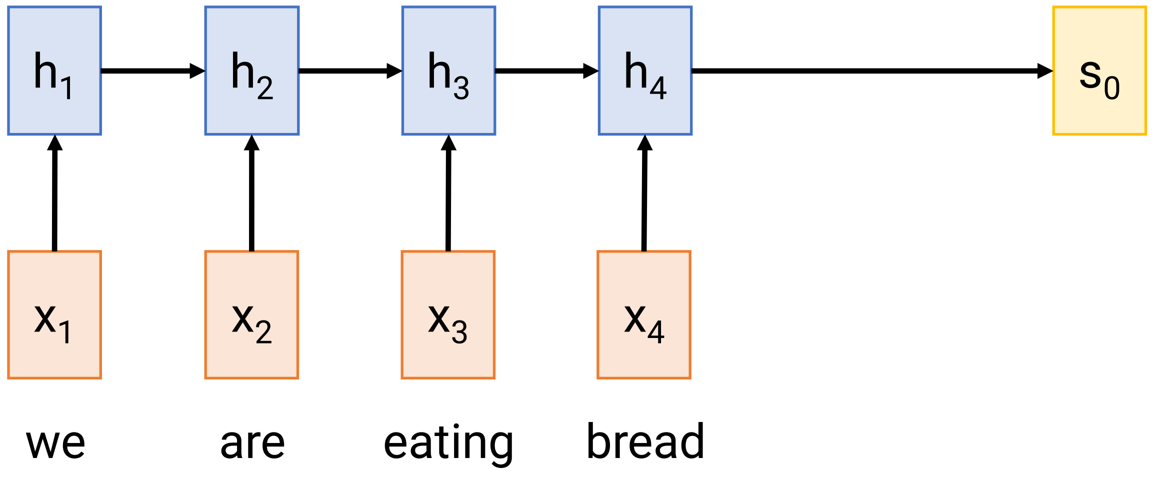
Encoder: $h_t = f_W(x_t, h_{t-1})$

From final hidden state:
Initial decoder state s_0



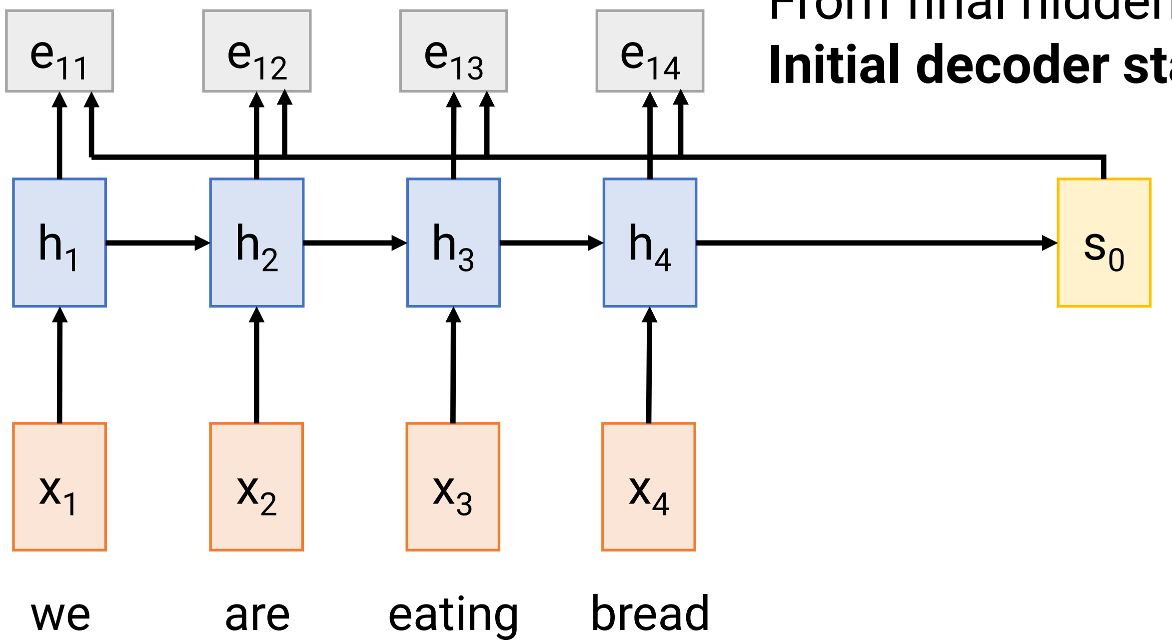
Bahdanau et al, "Neural machine translation by jointly learning to align and translate", ICLR 2015

Slide Credit: Justin Johnson

Sequence-to-Sequence with RNNs **and Attention**

Compute (scalar) **alignment scores**

$e_{t,i} = f_{att}(s_{t-1}, h_i)$ (f_{att} is an MLP)



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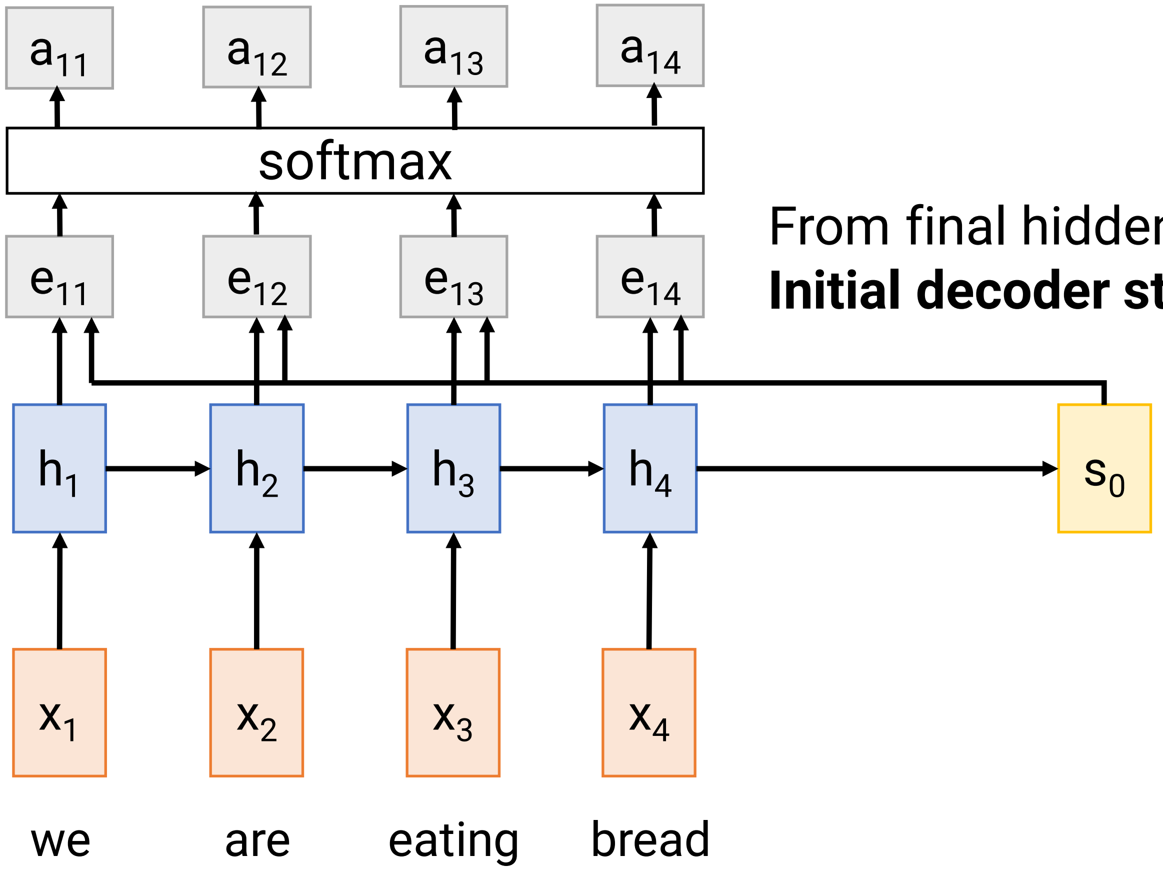
$e_{t,i} = f_{att}(s_{t-1}, h_i)$ (f_{att} is an MLP)

Normalize alignment scores to get **attention weights**
$0 < a_{t,i} < 1$ $\sum_i a_{t,i} = 1$



From final hidden state:
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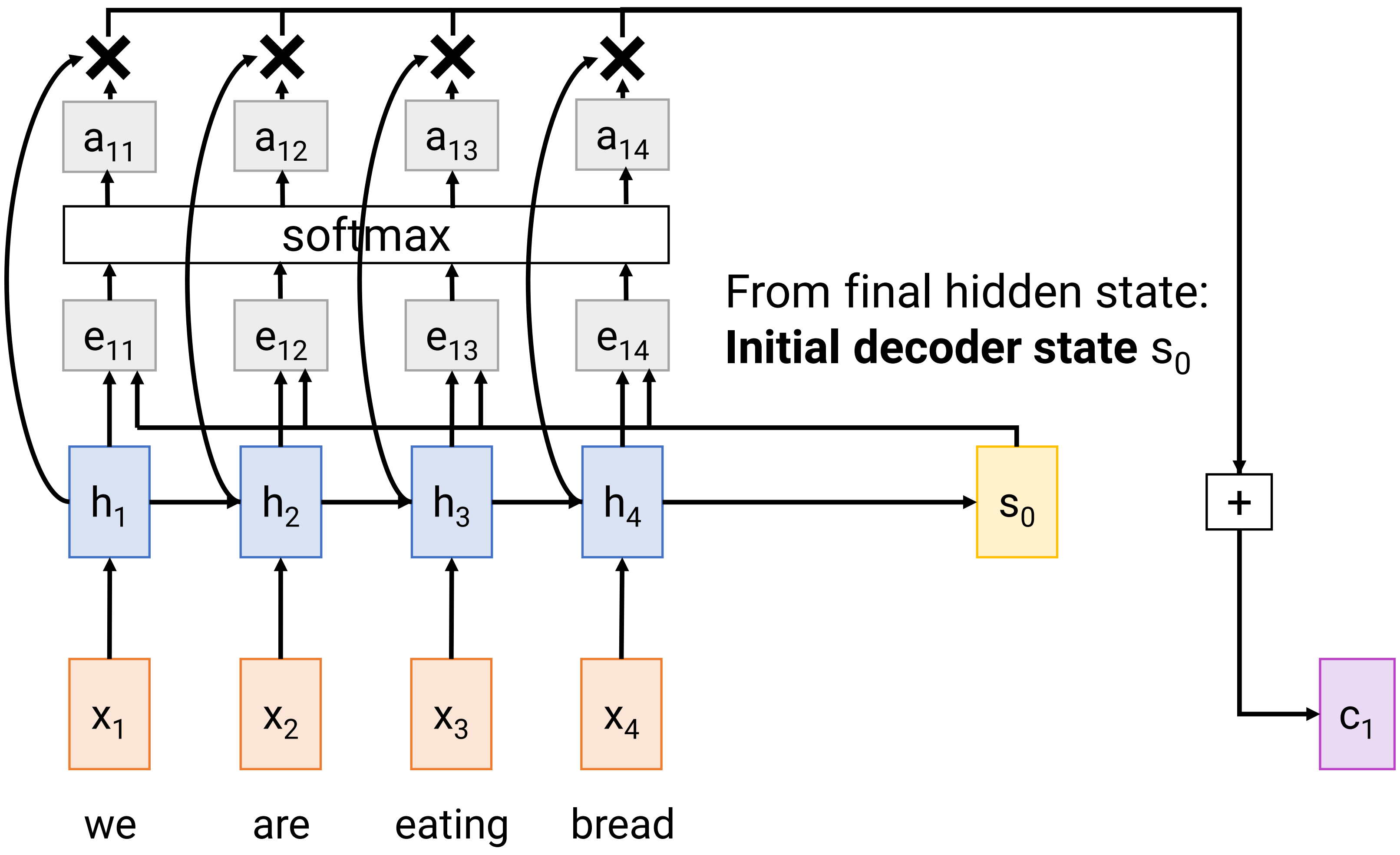

From final hidden state: **Initial decoder state** s_0

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Compute context vector as linear combination of hidden states
$c_t = \sum_i a_{t,i} h_i$

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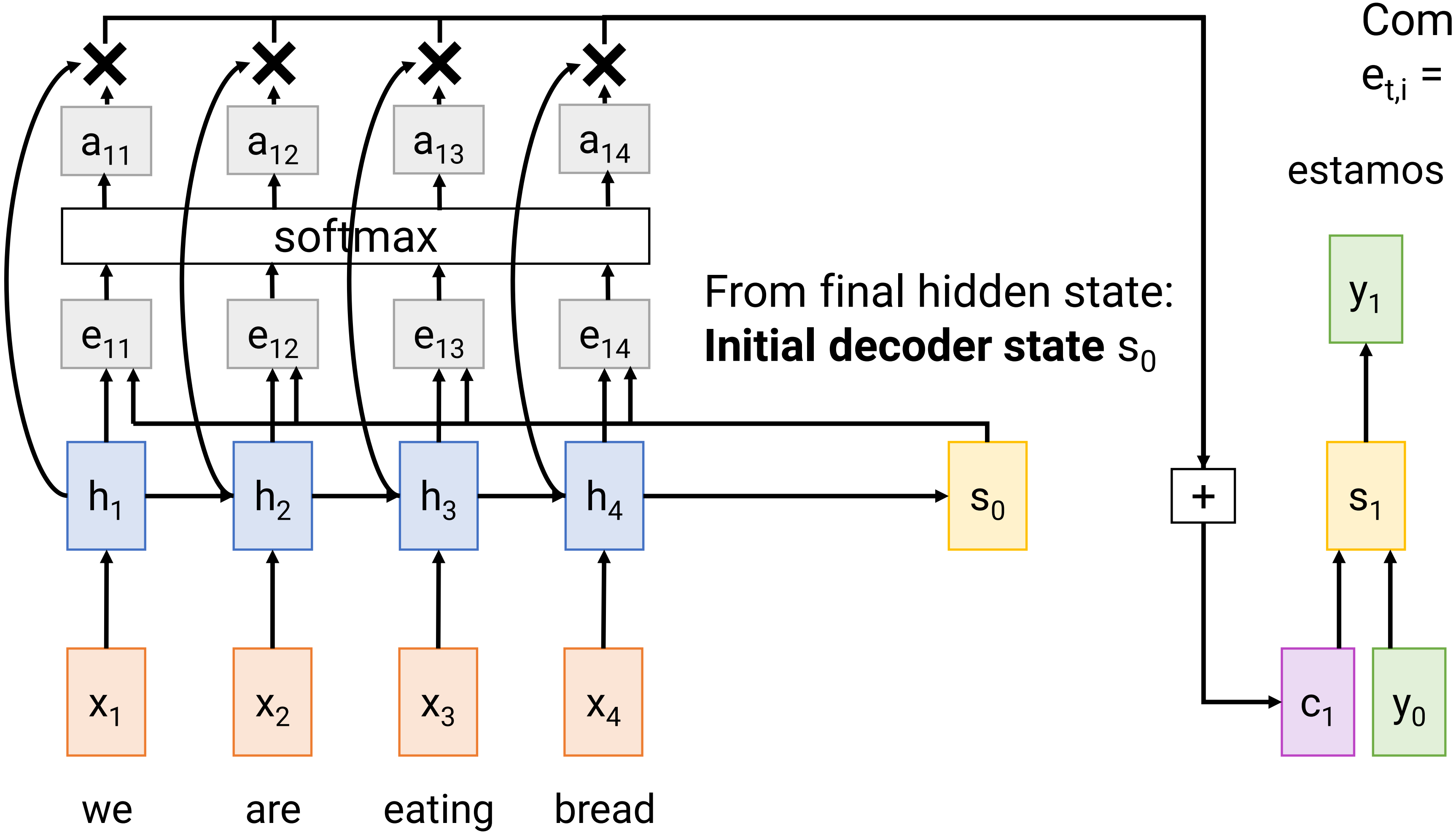

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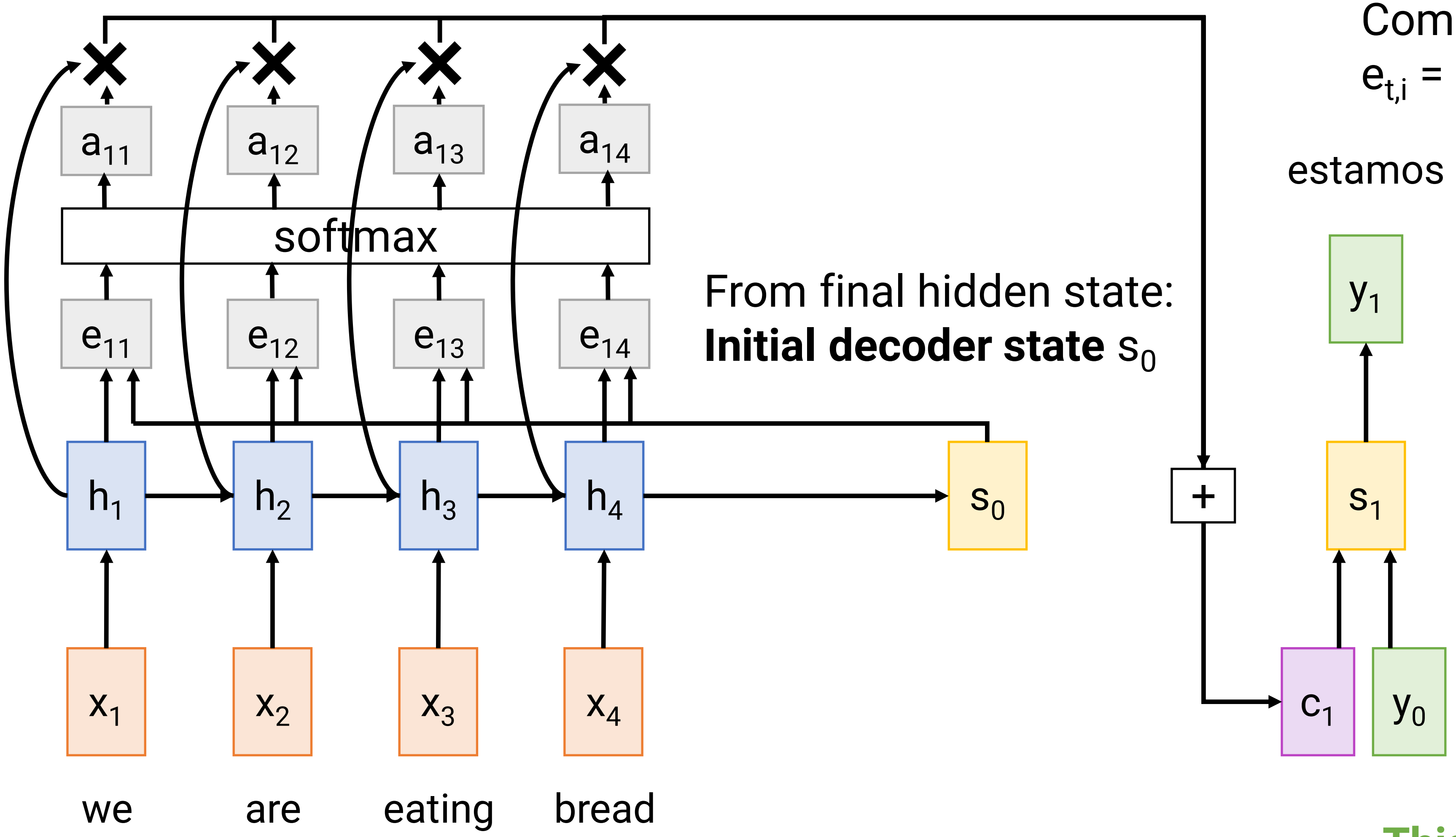

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This is all differentiable! Do not supervise attention weights – backprop through everything

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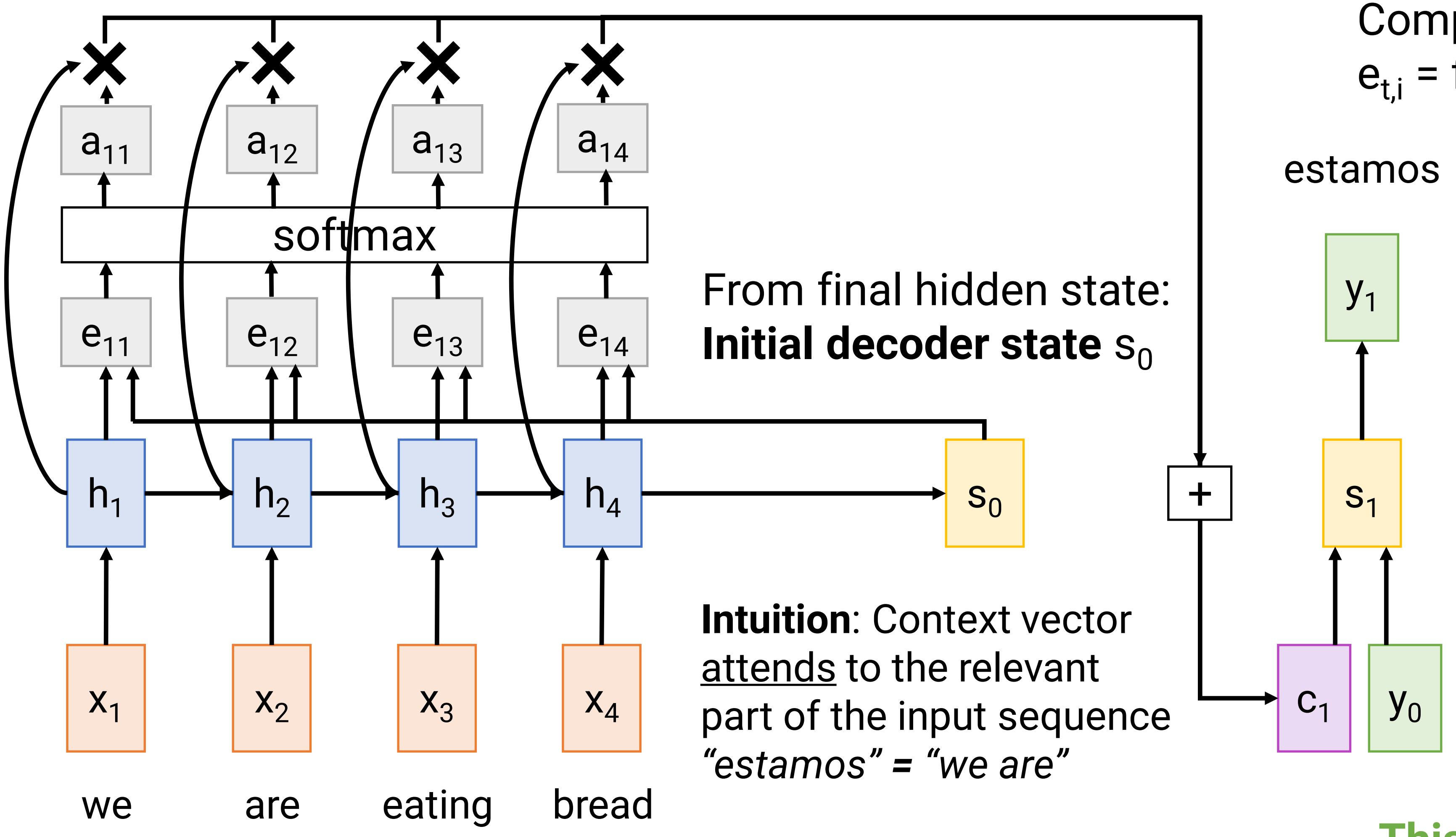
Sequence-to-Sequence with RNNs **and Attention**



From final hidden state: **Initial decoder state** s_0

Intuition: Context vector attends to the relevant part of the input sequence *"estamos" = "we are"*

$a_{11}=0.45$, $a_{12}=0.45$, $a_{13}=0.05$, $a_{14}=0.05$

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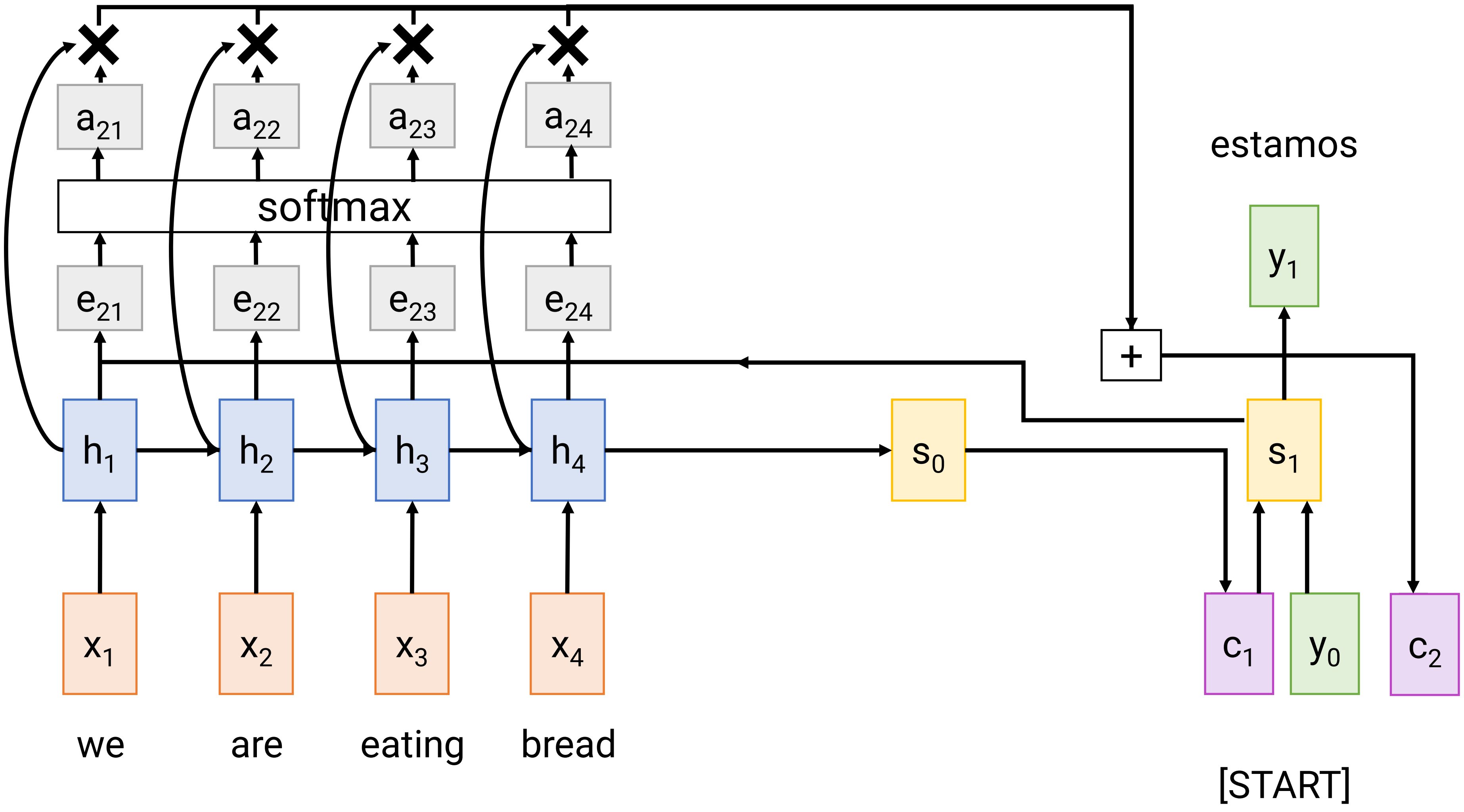
Sequence-to-Sequence with RNNs



Repeat: Use s_1 to compute new context vector c_2

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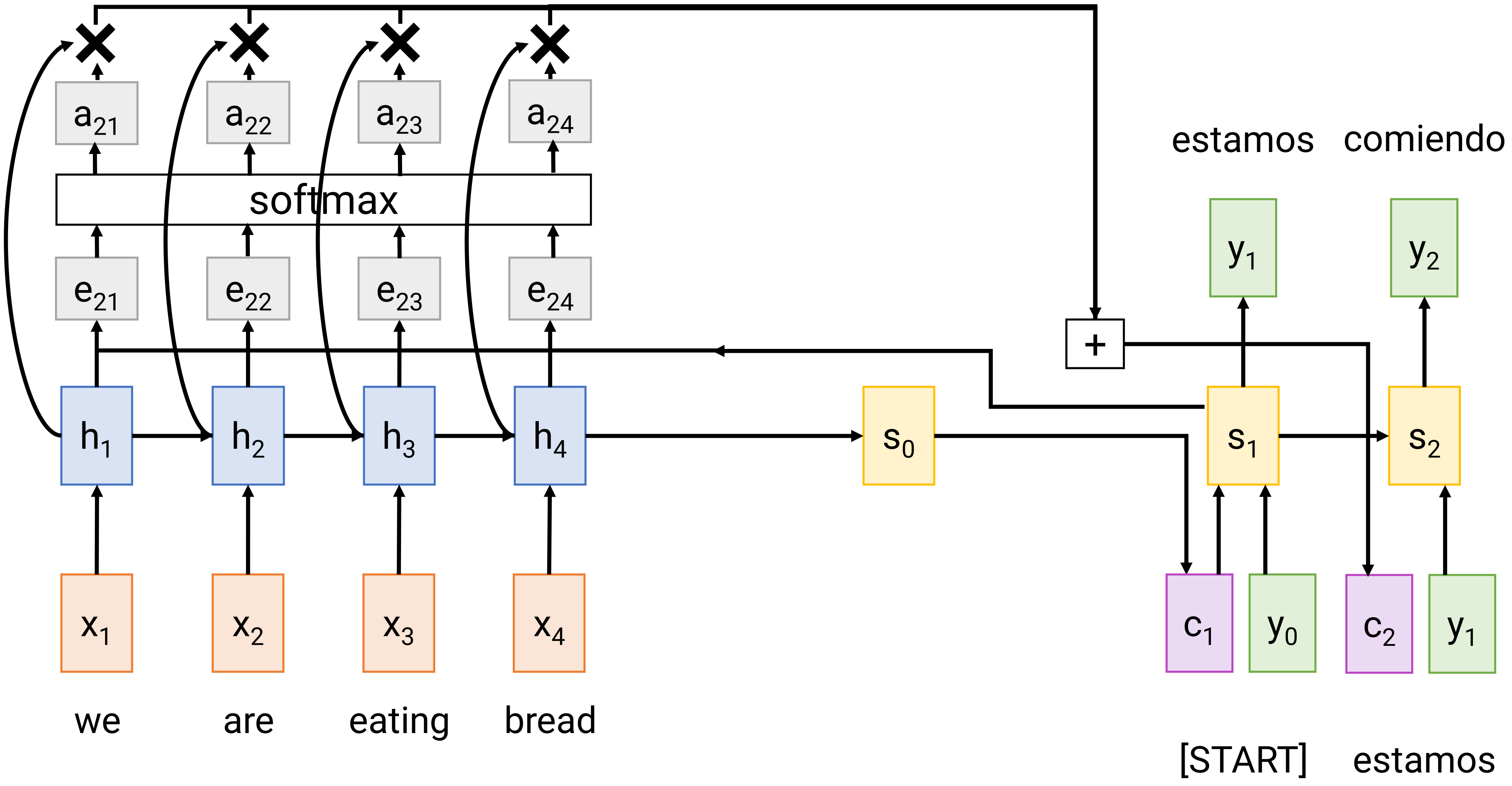
Sequence-to-Sequence with RNNs **and Attention**



Repeat: Use s_1 to compute new context vector c_2

Use c_2 to compute s_2, y_2

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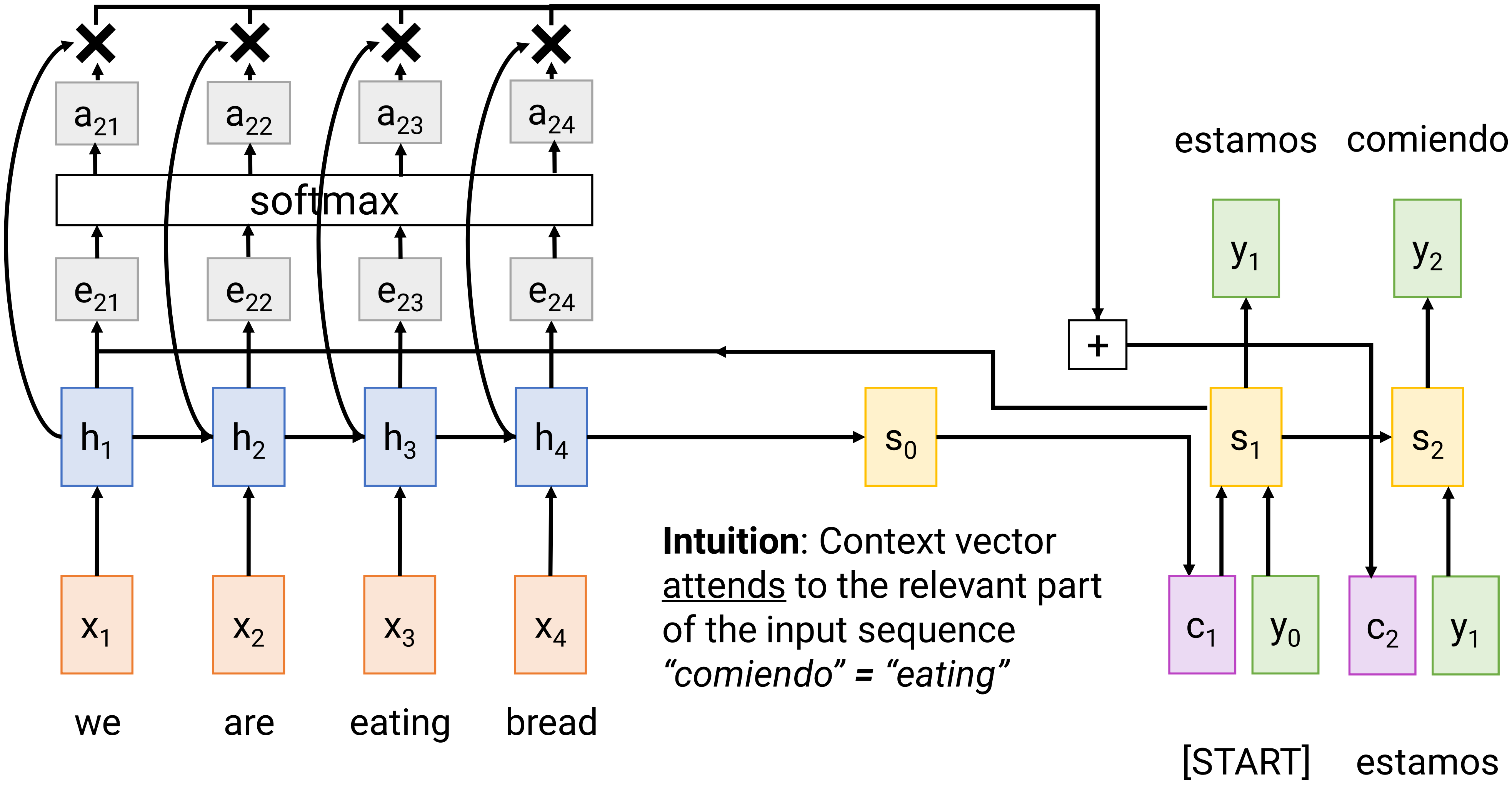

Repeat: Use s_1 to compute new context vector c_2

Use c_2 to compute s_2, y_2

Intuition: Context vector <u>attends</u> to the relevant part of the input sequence *"comiendo" = "eating"*

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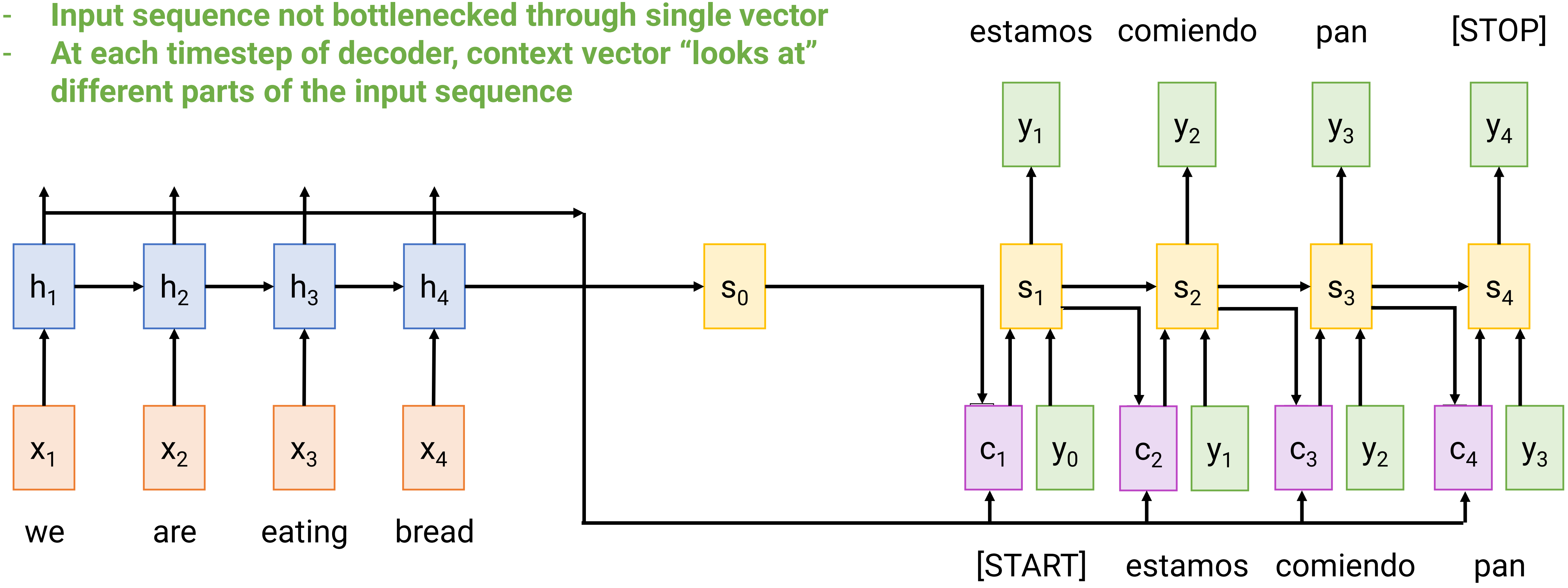
Sequence-to-Sequence with RNNs **and Attention**

Use a different context vector in each timestep of decoder
- **Input sequence not bottlenecked through single vector**
- **At each timestep of decoder, context vector "looks at" different parts of the input sequence**



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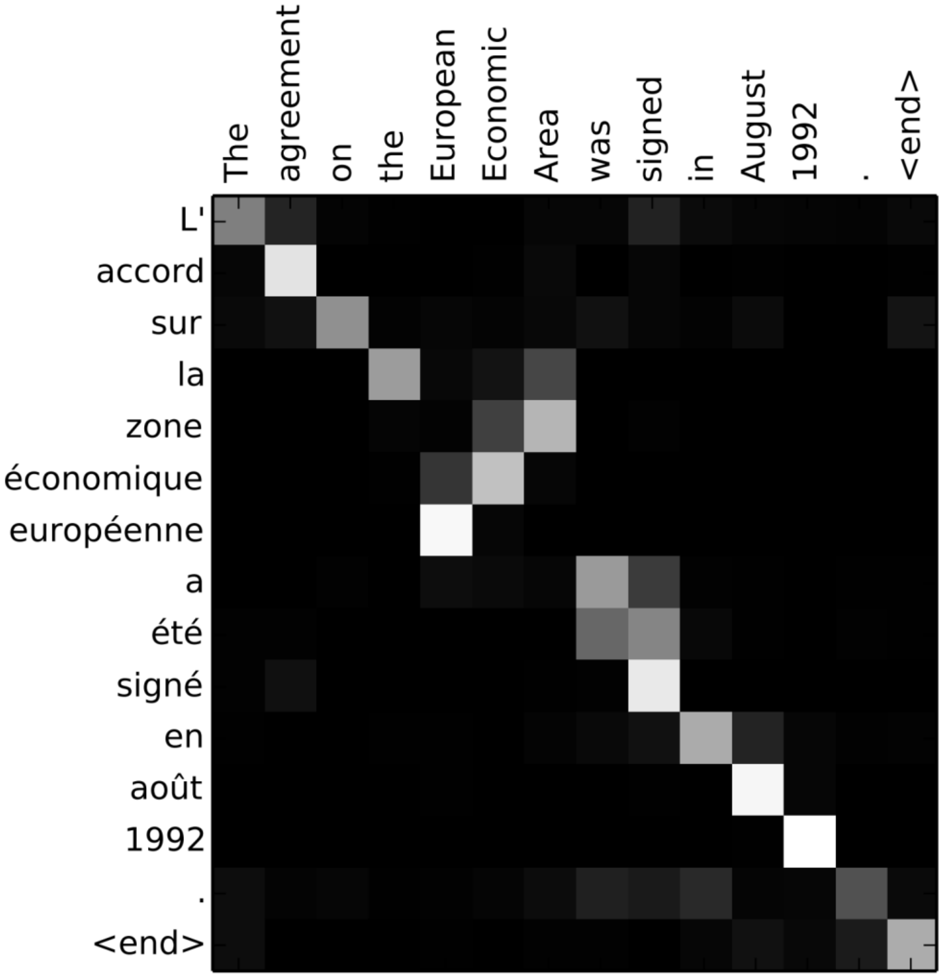
Sequence-to-Sequence with RNNs **and Attention**

Example: English to French translation

Input: "The agreement on the European Economic Area was signed in August 1992."

Output: "L'accord sur la zone économique européenne a été signé en août 1992."

Visualize attention weights $a_{t,i}$



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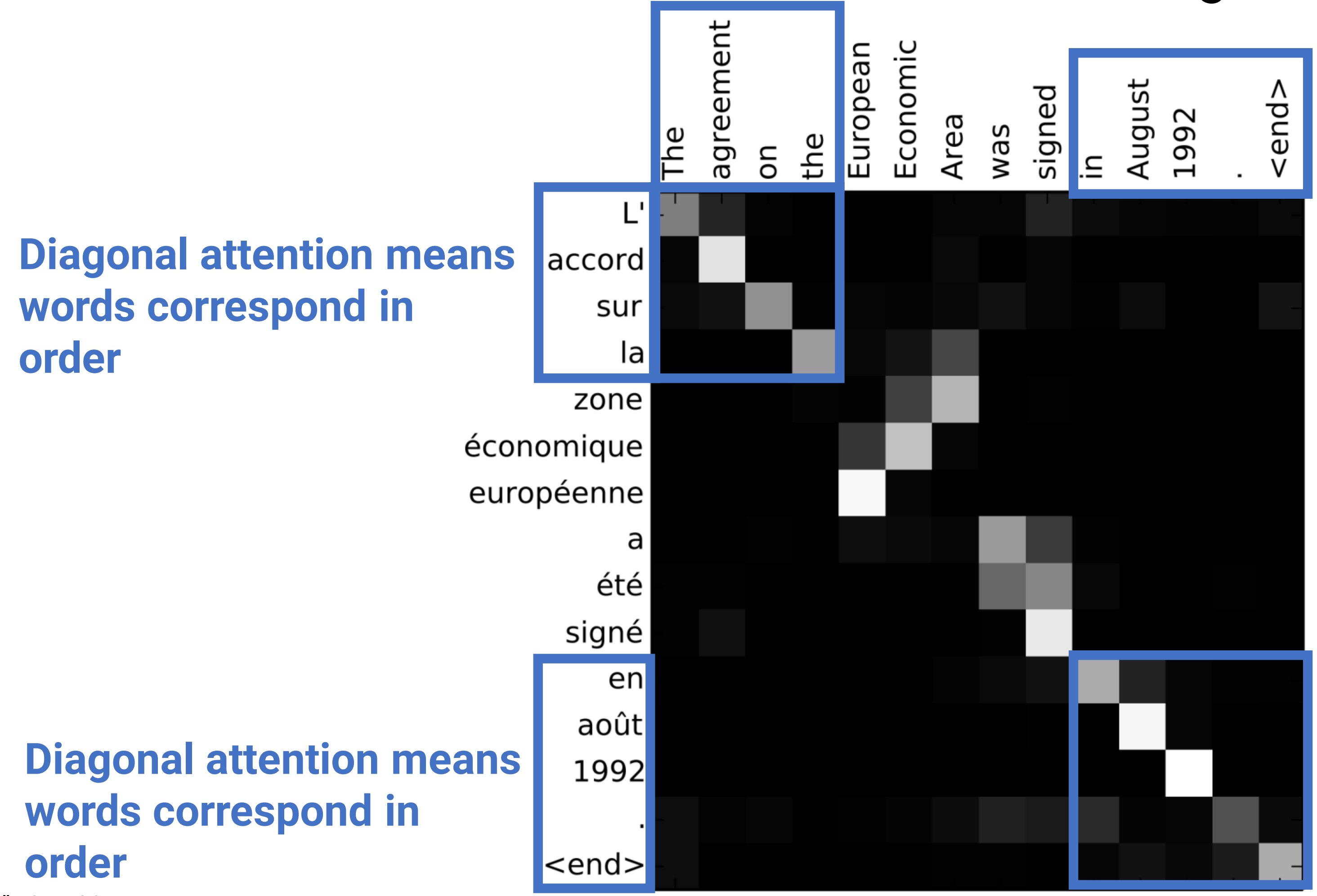

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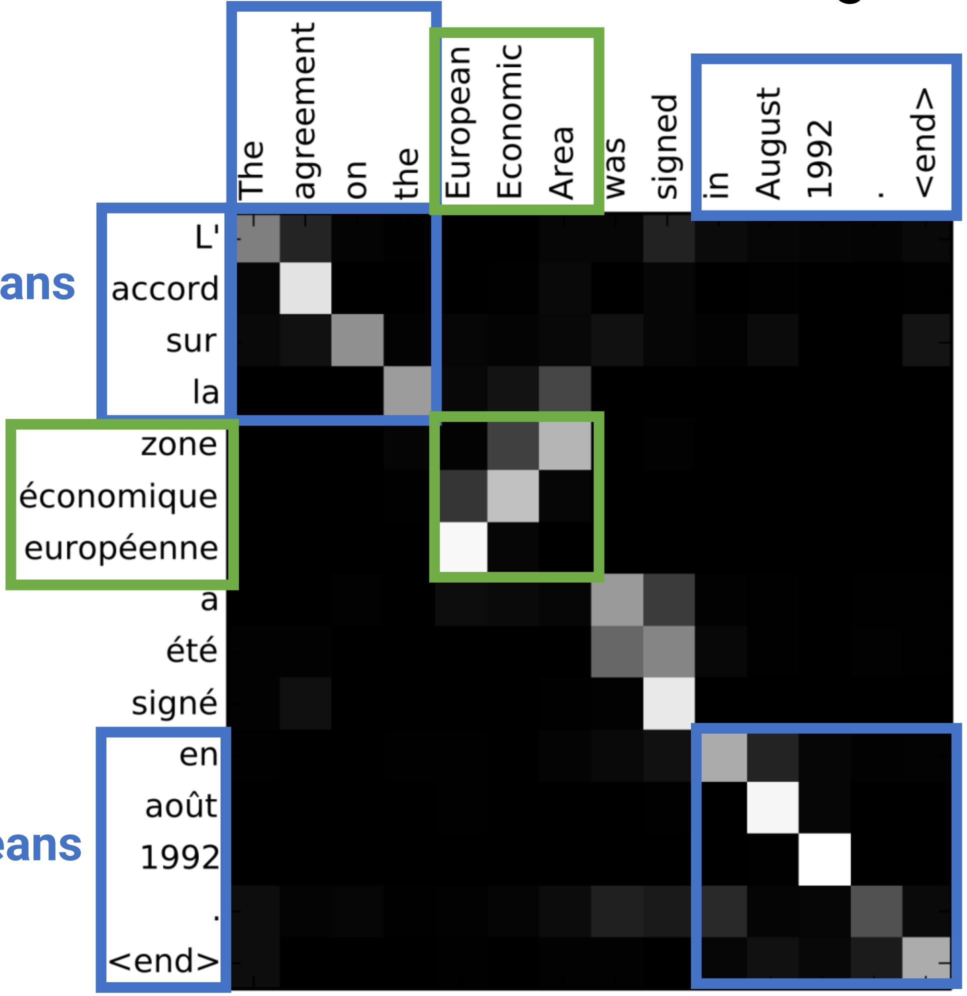
Diagonal attention means words correspond in order

Attention figures out different word orders

Diagonal attention means words correspond in order



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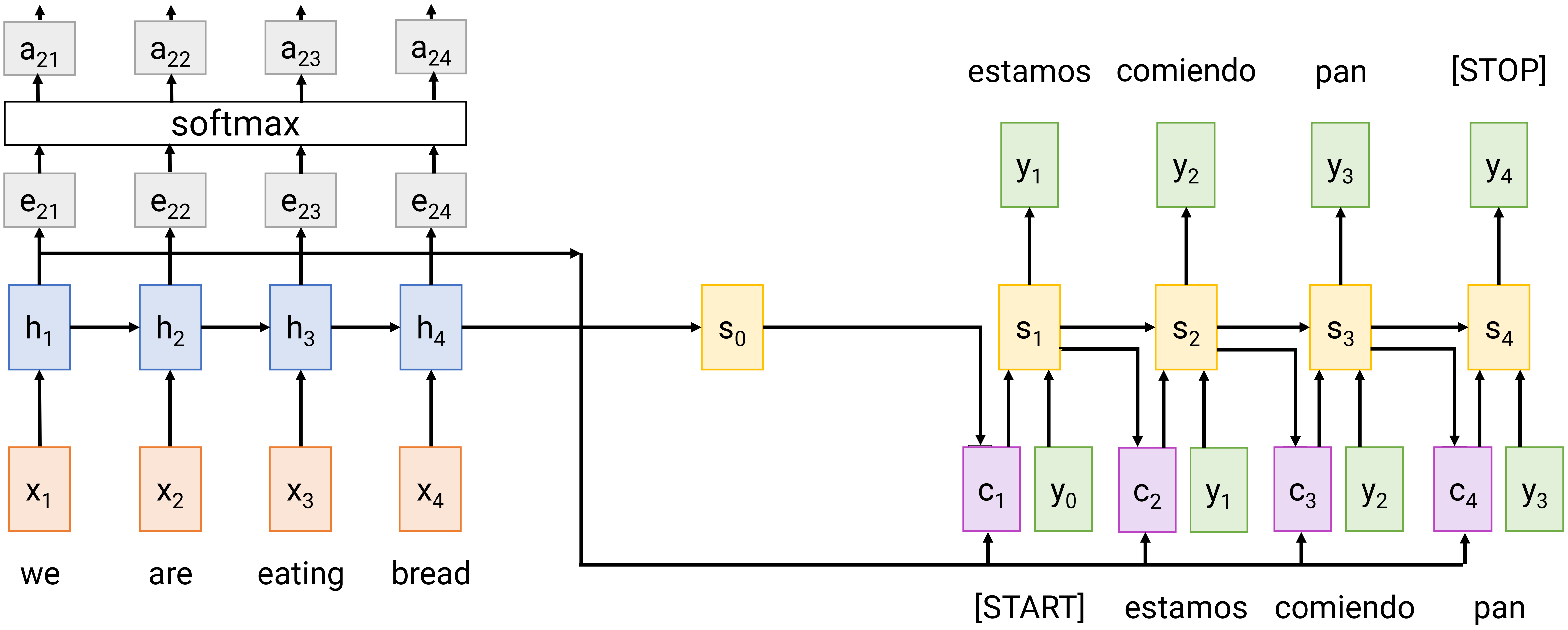

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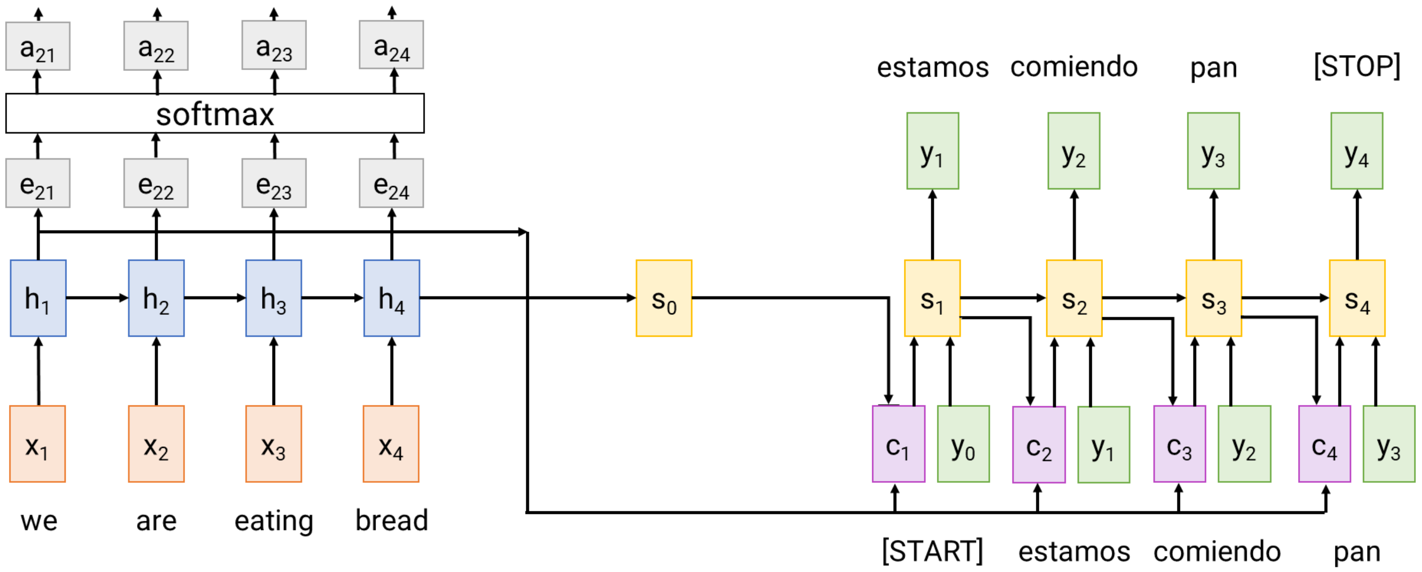
Attention Layer

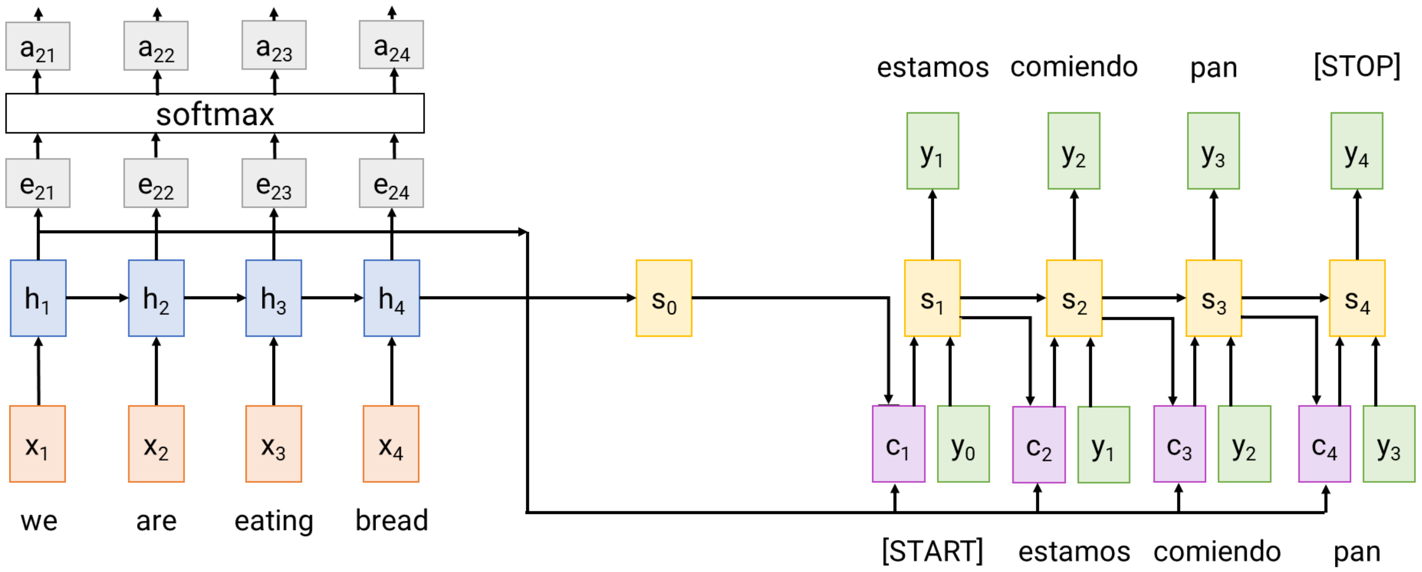
Inputs:
State vector: s_i (Shape: D_Q)
Hidden vectors: h_i (Shape: $N_X \times D_H$)
Similarity function: f_{att}



Computation:
Similarities: e (Shape: N_X) $e_i = f_{att}(s_{t-1}, h_i)$
Attention weights: $a = \text{softmax}(e)$ (Shape: N_X)
Output vector: $y = \sum_i a_i h_i$ (Shape: D_X)

Attention Layer

Inputs:
Query vector: **q** (Shape: D_Q)
Input vectors: **X** (Shape: N_X x D_X)
Similarity function: f_{att}

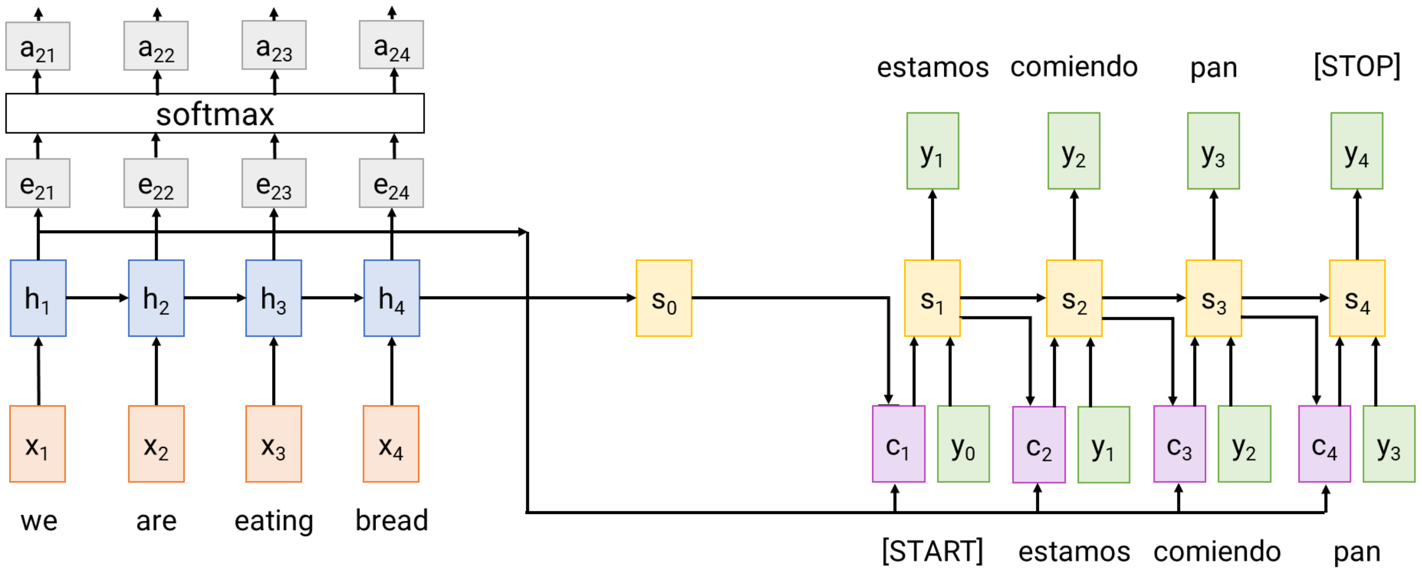


Computation:
Similarities: e (Shape: N_X) $e_i = f_{att}(\mathbf{q}, \mathbf{X}_i)$
Attention weights: a = softmax(e) (Shape: N_X)
Output vector: $y = \sum_i a_i \mathbf{X}_i$ (Shape: D_X)

Slide Credit: Justin Johnson

Attention Layer

Inputs:
Query vector: $\mathbf{q}$ (Shape: D_Q)
Input vectors: $\mathbf{X}$ (Shape: N_X x D_Q)
Similarity function: $\boxed{\text{dot product}}$

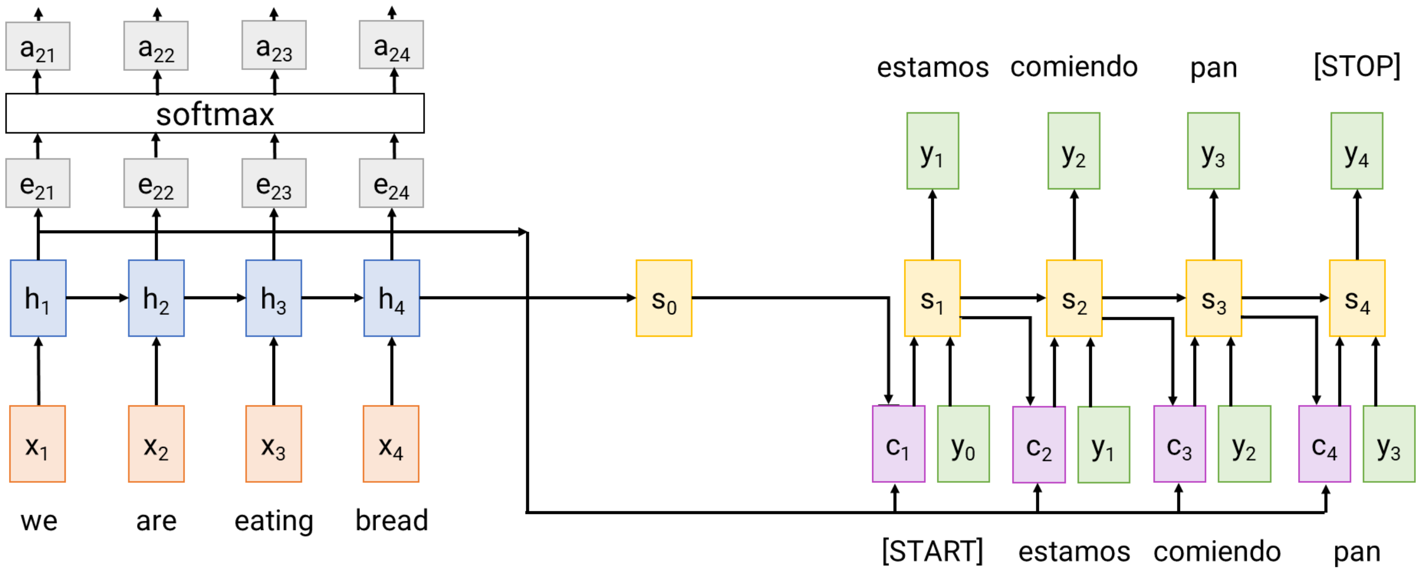


Computation:
Similarities: e (Shape: N_X) $\boxed{e_i = \mathbf{q} \cdot \mathbf{X}_i}$
Attention weights: a = softmax(e) (Shape: N_X)
Output vector: $y = \sum_i a_i \mathbf{X}_i$ (Shape: D_X)

Changes:
- Use dot product for similarity

Attention Layer

Inputs:
Query vector: **q** (Shape: D_Q)
Input vectors: **X** (Shape: N_X x D_Q)
Similarity function: scaled dot product



Computation:
Similarities: e (Shape: N_X) $e_i = \mathbf{q} \cdot \mathbf{X}_i / \mathrm{sqrt}(D_Q)$
Attention weights: a = softmax(e) (Shape: N_X)
Output vector: $y = \sum_i a_i \mathbf{X}_i$ (Shape: D_X)

Changes:
- Use **scaled** dot product for similarity

Attention Layer

Inputs:
Query vectors: $\boxed{\mathbf{Q} \text{ (Shape: } N_Q \times D_Q)}$
Input vectors: $\mathbf{X}$ (Shape: $N_X \times D_Q$)

Computation:
Similarities: $E = \mathbf{Q}\mathbf{X}^T$ (Shape: $N_Q \times N_X$) $E_{i,j} = \mathbf{Q_i} \cdot \mathbf{X_j} / \text{sqrt}(D_Q)$
Attention weights: $A = \text{softmax}(E, \text{dim}=1)$ (Shape: $N_Q \times N_X$)
Output vectors: $Y = A\mathbf{X}$ (Shape: $N_Q \times D_X$) $Y_i = \sum_j A_{i,j} X_j$

Changes:
- Use dot product for similarity
- Multiple **query** vectors

Slide Credit: Justin Johnson

Attention Layer

Inputs:
Query vectors: **Q** (Shape: N_Q x D_Q)
Input vectors: **X** (Shape: N_X x D_X)
Key matrix: W_K (Shape: D_X x D_Q)
Value matrix: W_V (Shape: D_X x D_V)

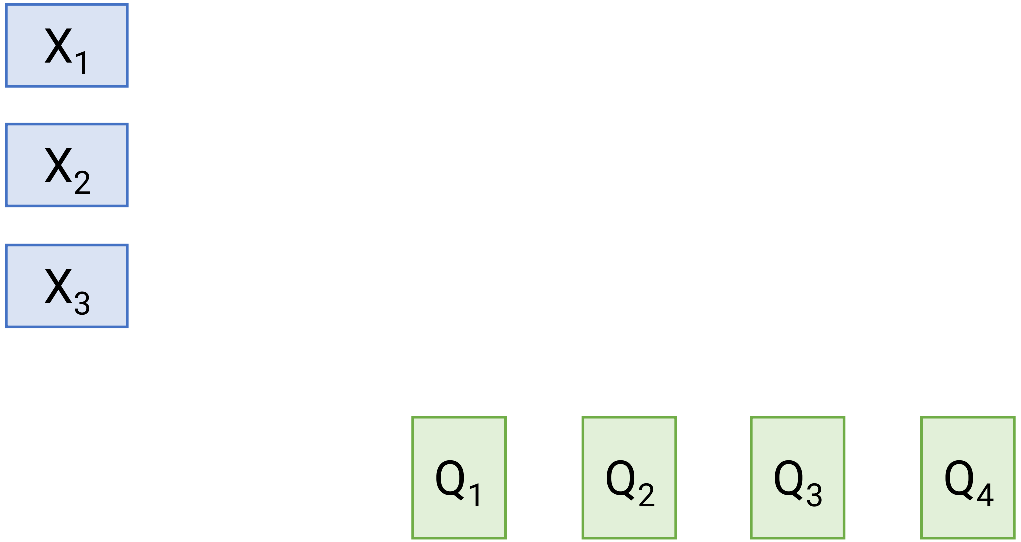
Computation:
Key vectors: $K = XW_K$ (Shape: N_X x D_Q)
Value Vectors: $V = XW_V$ (Shape: N_X x D_V)
Similarities: $E = QK^T$ (Shape: N_Q x N_X) $E_{i,j} = Q_i \cdot K_j / \text{sqrt}(D_Q)$
Attention weights: A = softmax(E, dim=1) (Shape: N_Q x N_X)
Output vectors: $Y = AV$ (Shape: N_Q x D_V) $Y_i = \sum_j A_{i,j} V_j$

Changes:
- Use dot product for similarity
- Multiple **query** vectors
- Separate **key** and **value**

Attention Layer

Inputs:
Query vectors: $\mathbf{Q}$ (Shape: N_Q x D_Q)
Input vectors: $\mathbf{X}$ (Shape: N_X x D_X)
Key matrix: $\mathbf{W_K}$ (Shape: D_X x D_Q)
Value matrix: $\mathbf{W_V}$ (Shape: D_X x D_V)

Computation:
Key vectors: $\mathbf{K} = \mathbf{XW_K}$ (Shape: N_X x D_Q)
Value Vectors: $\mathbf{V} = \mathbf{XW_V}$ (Shape: N_X x D_V)
Similarities: $E = \mathbf{QK}^T$ (Shape: N_Q x N_X) $E_{i,j} = \mathbf{Q_i} \cdot \mathbf{K_j} / \mathrm{sqrt}(D_Q)$
Attention weights: $A = \mathrm{softmax}(E, \mathrm{dim}=1)$ (Shape: N_Q x N_X)
Output vectors: $Y = A\mathbf{V}$ (Shape: N_Q x D_V) $Y_i = \sum_j A_{i,j} \mathbf{V_j}$



Slide Credit: Justin Johnson

Attention Layer

Inputs:
Query vectors: **Q** (Shape: N_Q x D_Q)
Input vectors: **X** (Shape: N_X x D_X)
Key matrix: $\mathbf{W_K}$ (Shape: D_X x D_Q)
Value matrix: $\mathbf{W_V}$ (Shape: D_X x D_V)

Computation:
Key vectors: $\mathbf{K} = \mathbf{XW_K}$ (Shape: N_X x D_Q)
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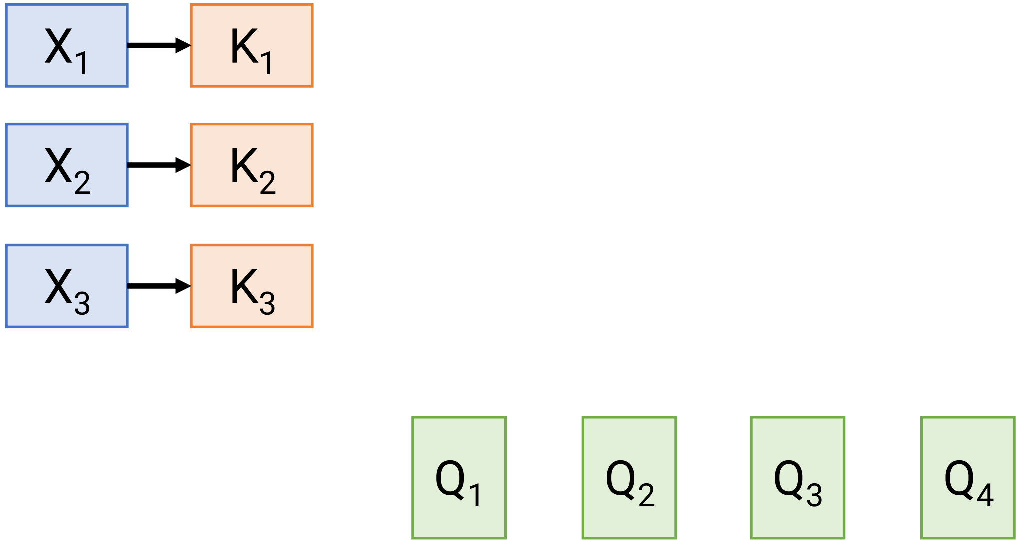
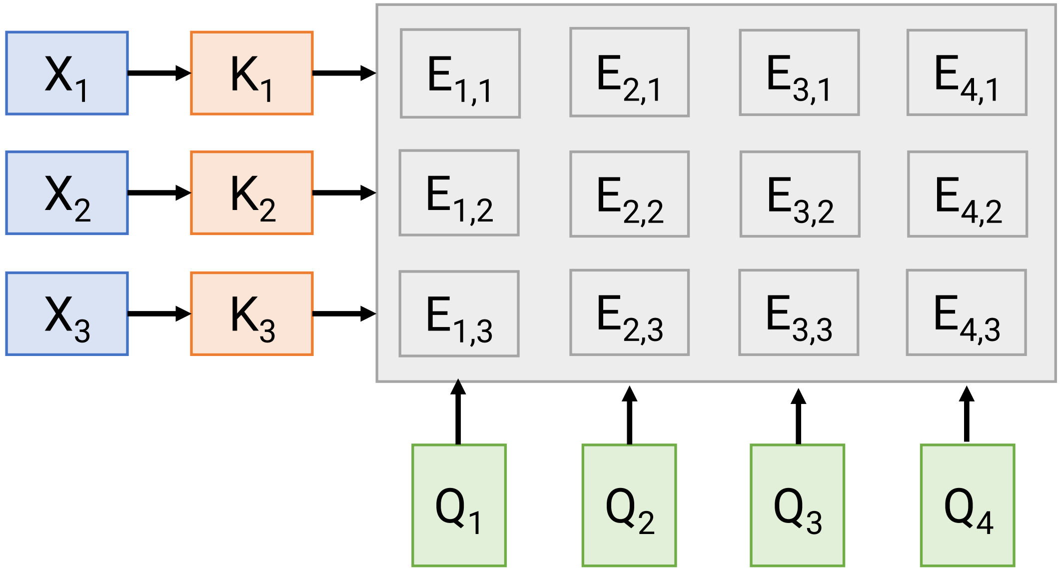
Attention weights: A = softmax(E, dim=1) (Shape: N_Q x N_X)
Output vectors: $Y = A\mathbf{V}$ (Shape: N_Q x D_V) $Y_i = \sum_j A_{i,j}\mathbf{V_j}$



Attention Layer

Inputs:
Query vectors: Q (Shape: $N_Q \times D_Q$)
Input vectors: X (Shape: $N_X \times D_X$)
Key matrix: W_K (Shape: $D_X \times D_Q$)
Value matrix: W_V (Shape: $D_X \times D_V$)

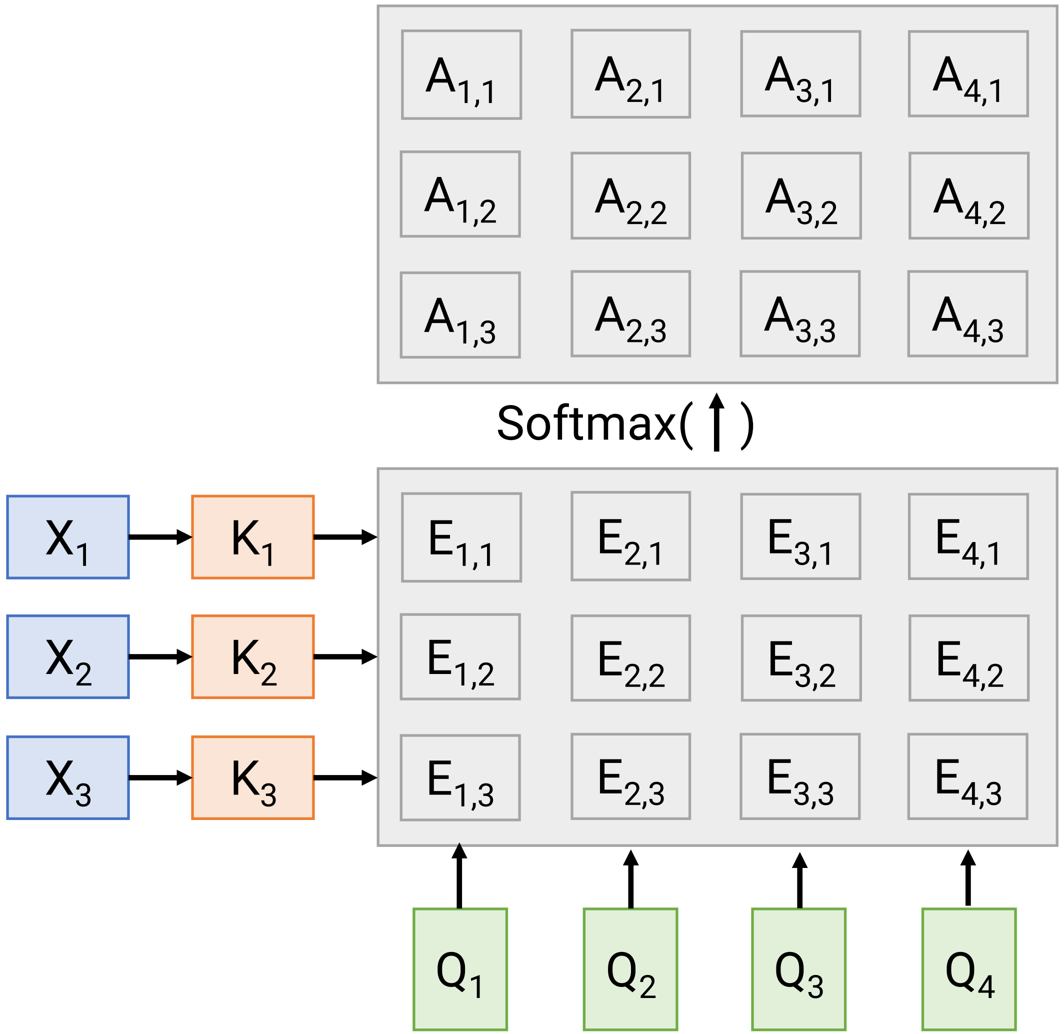
Computation:
Key vectors: $K = XW_K$ (Shape: $N_X \times D_Q$)
Value Vectors: $V = XW_V$ (Shape: $N_X \times D_V$)
Similarities: $E = QK^T$ (Shape: $N_Q \times N_X$) $E_{i,j} = Q_i \cdot K_j / \text{sqrt}(D_Q)$
Attention weights: $A = \text{softmax}(E, \text{dim}=1)$ (Shape: $N_Q \times N_X$)
Output vectors: $Y = AV$ (Shape: $N_Q \times D_V$) $Y_i = \sum_j A_{i,j} V_j$



Attention Layer

Inputs:
Query vectors: $\mathbf{Q}$ (Shape: $N_Q \times D_Q$)
Input vectors: $\mathbf{X}$ (Shape: $N_X \times D_X$)
Key matrix: $\mathbf{W_K}$ (Shape: $D_X \times D_Q$)
Value matrix: $\mathbf{W_V}$ (Shape: $D_X \times D_V$)

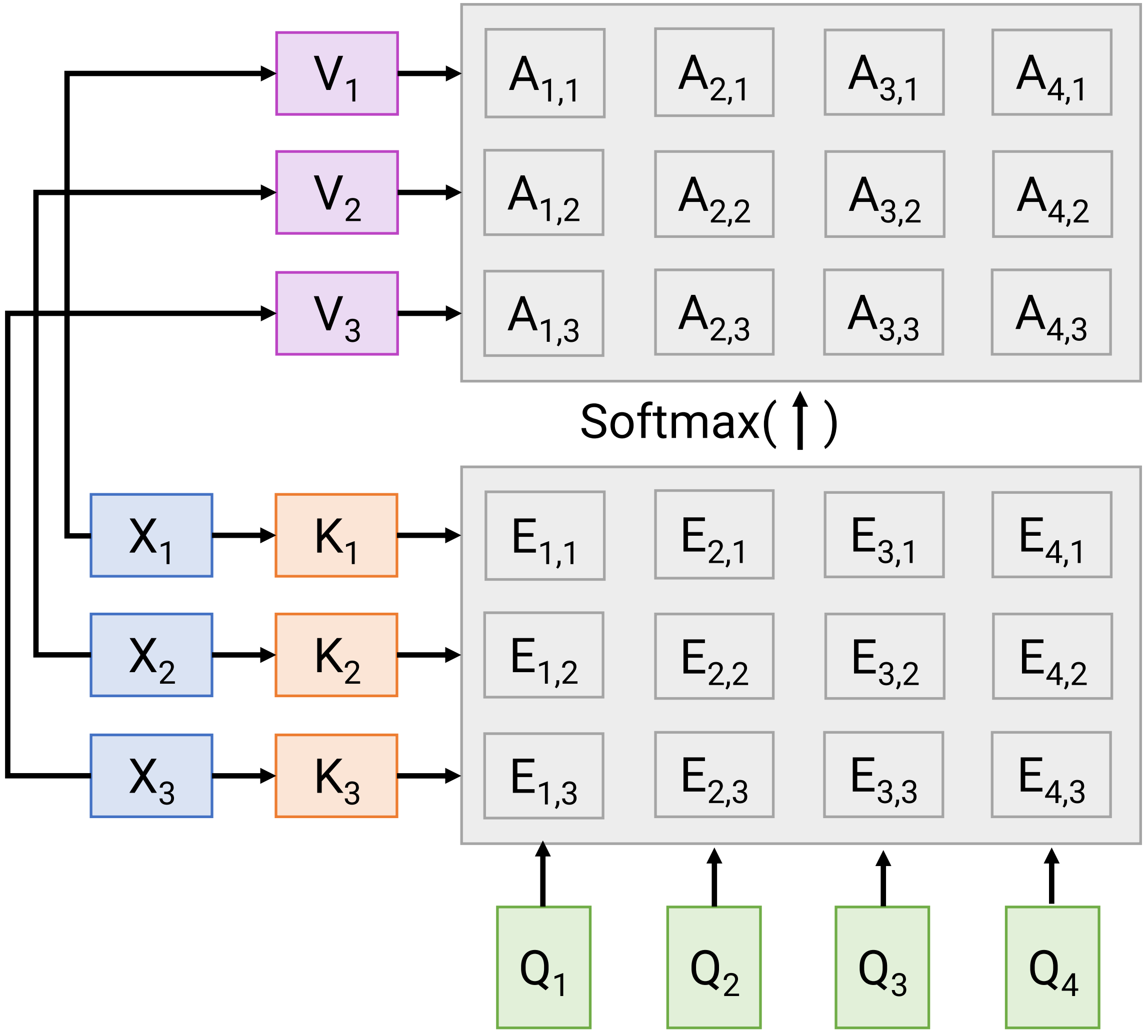
Computation:
Key vectors: $\mathbf{K} = \mathbf{XW_K}$ (Shape: $N_X \times D_Q$)
Value Vectors: $\mathbf{V} = \mathbf{XW_V}$ (Shape: $N_X \times D_V$)
Similarities: $E = \mathbf{QK^T}$ (Shape: $N_Q \times N_X$) $E_{i,j} = \mathbf{Q_i} \cdot \mathbf{K_j} / \mathrm{sqrt}(D_Q)$
Attention weights: $A = \mathrm{softmax}(E, \mathrm{dim}=1)$ (Shape: $N_Q \times N_X$)
Output vectors: $Y = A\mathbf{V}$ (Shape: $N_Q \times D_V$) $Y_i = \sum_j A_{i,j}\mathbf{V_j}$



Attention Layer

Inputs:
Query vectors: **Q** (Shape: N_Q x D_Q)
Input vectors: **X** (Shape: N_X x D_X)
Key matrix: $\mathbf{W_K}$ (Shape: D_X x D_Q)
Value matrix: $\mathbf{W_V}$ (Shape: D_X x D_V)

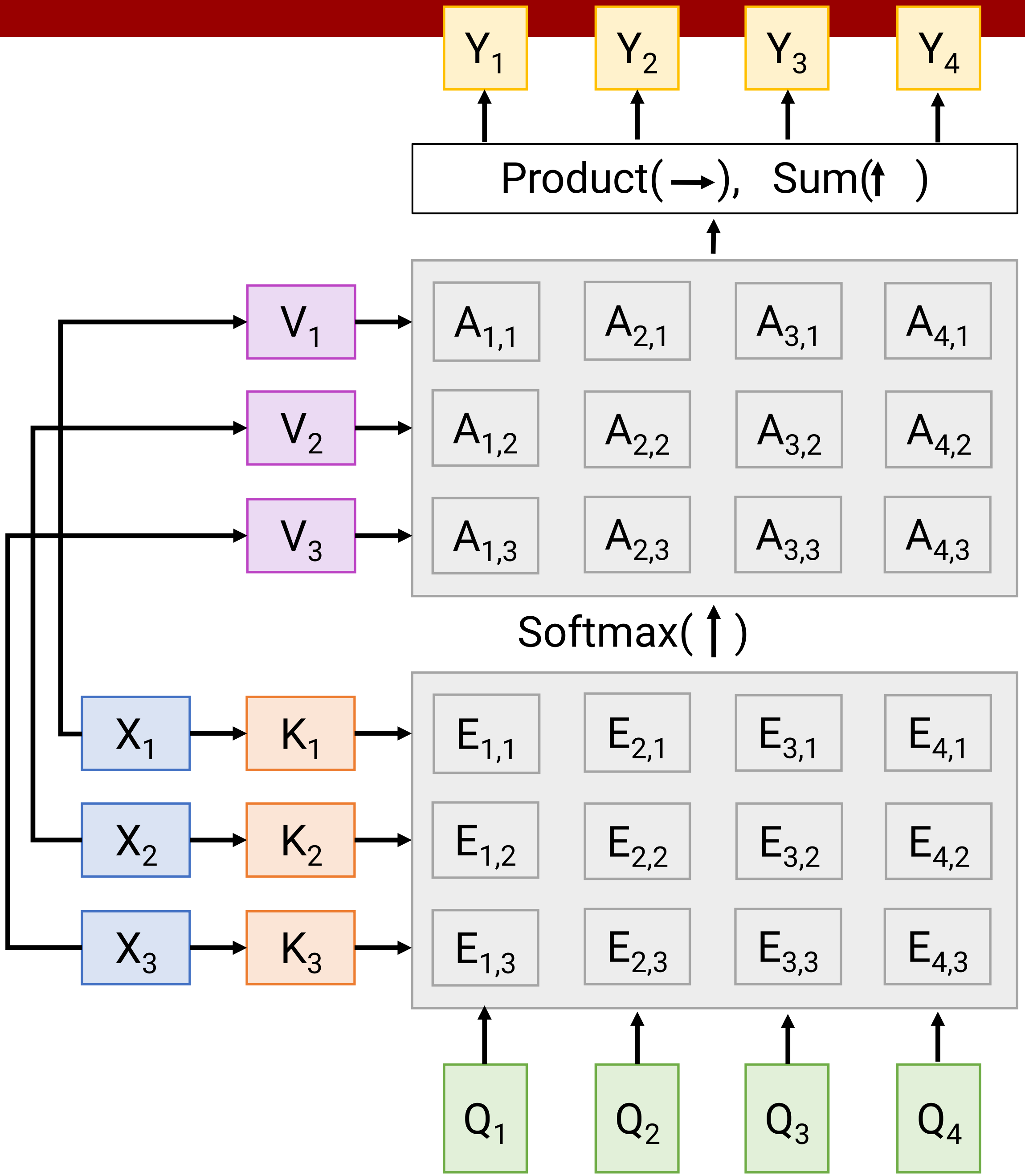
Computation:
Key vectors: **K** = $\mathbf{XW_K}$ (Shape: N_X x D_Q)
Value Vectors: **V** = $\mathbf{XW_V}$ (Shape: N_X x D_V)
Similarities: E = $\mathbf{QK^T}$ (Shape: N_Q x N_X) $E_{i,j} = \mathbf{Q_i} \cdot \mathbf{K_j} / \text{sqrt}(D_Q)$
Attention weights: A = softmax(E, dim=1) (Shape: N_Q x N_X)
Output vectors: Y = A**V** (Shape: N_Q x D_V) $Y_i = \sum_j A_{i,j} \mathbf{V_j}$



Attention Layer

Inputs:
Query vectors: **Q** (Shape: N_Q x D_Q)
Input vectors: **X** (Shape: N_X x D_X)
Key matrix: $\mathbf{W_K}$ (Shape: D_X x D_Q)
Value matrix: $\mathbf{W_V}$ (Shape: D_X x D_V)

Computation:
Key vectors: **K** = $\mathbf{XW_K}$ (Shape: N_X x D_Q)
Value Vectors: **V** = $\mathbf{XW_V}$ (Shape: N_X x D_V)
Similarities: E = $\mathbf{QK^T}$ (Shape: N_Q x N_X) $E_{i,j} = \mathbf{Q_i} \cdot \mathbf{K_j} / \text{sqrt}(D_Q)$
Attention weights: A = softmax(E, dim=1) (Shape: N_Q x N_X)
Output vectors: Y = A**V** (Shape: N_Q x D_V) $Y_i = \sum_j A_{i,j} \mathbf{V_j}$



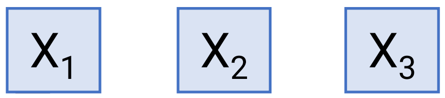
Slide Credit: Justin Johnson

Self-Attention Layer

One **query** per **input vector**

Inputs:
Input vectors: $\mathbf{X}$ (Shape: $N_X \times D_X$)
Key matrix: $\mathbf{W_K}$ (Shape: $D_X \times D_Q$)
Value matrix: $\mathbf{W_V}$ (Shape: $D_X \times D_V$)
Query matrix: $\mathbf{W_Q}$ (Shape: $D_X \times D_Q$)

Computation:
Query vectors: $\mathbf{Q} = \mathbf{XW_Q}$
Key vectors: $\mathbf{K} = \mathbf{XW_K}$ (Shape: $N_X \times D_Q$)
Value Vectors: $\mathbf{V} = \mathbf{XW_V}$ (Shape: $N_X \times D_V$)
Similarities: $E = \mathbf{QK}^T$ (Shape: $N_X \times N_X$) $E_{i,j} = \mathbf{Q_i} \cdot \mathbf{K_j} / \mathrm{sqrt}(D_Q)$
Attention weights: $A = \mathrm{softmax}(E, \mathrm{dim}=1)$ (Shape: $N_X \times N_X$)
Output vectors: $Y = A\mathbf{V}$ (Shape: $N_X \times D_V$) $Y_i = \sum_j A_{i,j}\mathbf{V_j}$



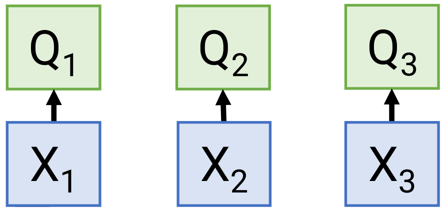
Slide Credit: Justin Johnson

Self-Attention Layer

One **query** per **input vector**

<u>Inputs</u>:
Input vectors: $\mathbf{X}$ (Shape: N_X x D_X)
Key matrix: $\mathbf{W_K}$ (Shape: D_X x D_Q)
Value matrix: $\mathbf{W_V}$ (Shape: D_X x D_V)
Query matrix: $\mathbf{W_Q}$ (Shape: D_X x D_Q)

<u>Computation</u>:
Query vectors: $\mathbf{Q} = \mathbf{XW_Q}$
Key vectors: $\mathbf{K} = \mathbf{XW_K}$ (Shape: N_X x D_Q)
Value Vectors: $\mathbf{V} = \mathbf{XW_V}$ (Shape: N_X x D_V)
Similarities: $E = \mathbf{QK}^T$ (Shape: N_X x N_X) $E_{i,j} = \mathbf{Q_i} \cdot \mathbf{K_j} / \mathrm{sqrt}(D_Q)$
Attention weights: $A = \mathrm{softmax}(E, \mathrm{dim}=1)$ (Shape: N_X x N_X)
Output vectors: $Y = A\mathbf{V}$ (Shape: N_X x D_V) $Y_i = \sum_j A_{i,j}\mathbf{V_j}$



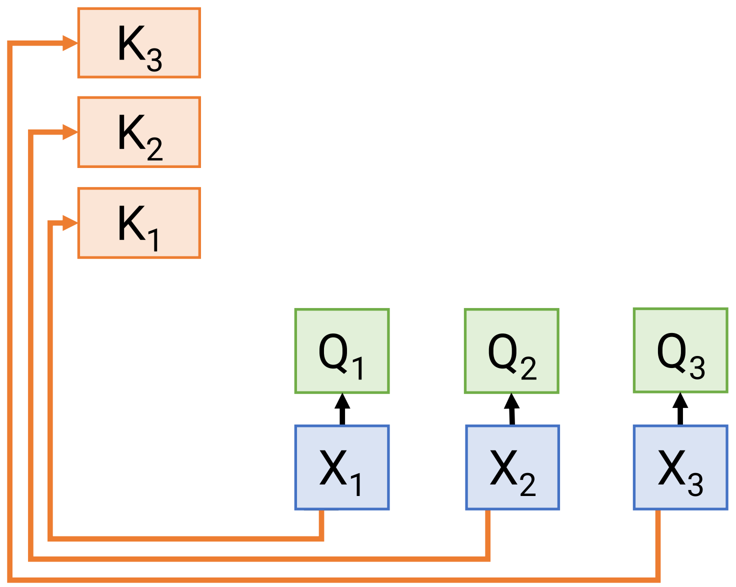
Slide Credit: Justin Johnson

Self-Attention Layer

One **query** per **input vector**

Inputs:
Input vectors: **X** (Shape: N_X x D_X)
Key matrix: $\mathbf{W_K}$ (Shape: D_X x D_Q)
Value matrix: $\mathbf{W_V}$ (Shape: D_X x D_V)
Query matrix: $\mathbf{W_Q}$ (Shape: D_X x D_Q)

Computation:
Query vectors: $\mathbf{Q} = \mathbf{XW_Q}$
Key vectors: $\mathbf{K} = \mathbf{XW_K}$ (Shape: N_X x D_Q)
Value Vectors: $\mathbf{V} = \mathbf{XW_V}$ (Shape: N_X x D_V)
Similarities: $E = \mathbf{QK}^T$ (Shape: N_X x N_X) $E_{i,j} = \mathbf{Q_i} \cdot \mathbf{K_j} / \mathrm{sqrt}(D_Q)$
Attention weights: A = softmax(E, dim=1) (Shape: N_X x N_X)
Output vectors: $Y = A\mathbf{V}$ (Shape: N_X x D_V) $Y_i = \sum_j A_{i,j} \mathbf{V_j}$

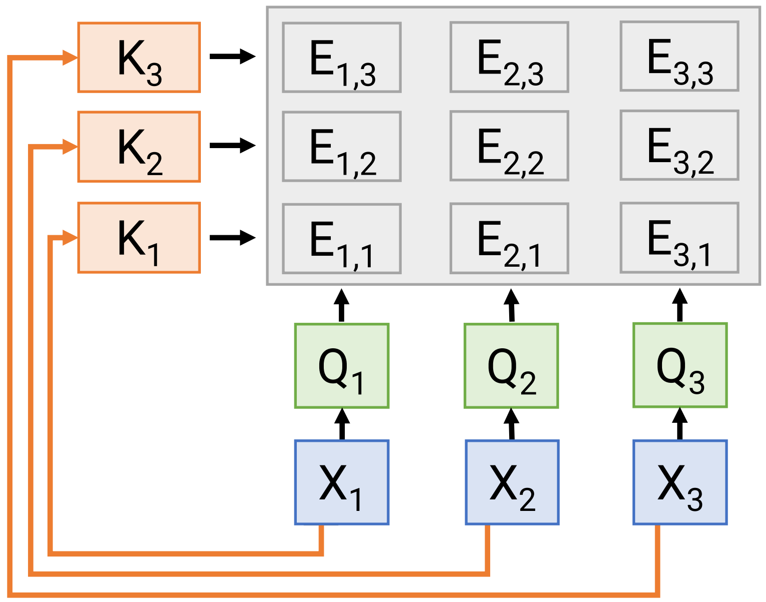


Self-Attention Layer

One **query** per **input vector**

Inputs:
Input vectors: **X** (Shape: N_X x D_X)
Key matrix: $\mathbf{W_K}$ (Shape: D_X x D_Q)
Value matrix: $\mathbf{W_V}$ (Shape: D_X x D_V)
Query matrix: $\mathbf{W_Q}$ (Shape: D_X x D_Q)

Computation:
Query vectors: $\mathbf{Q} = \mathbf{XW_Q}$
Key vectors: $\mathbf{K} = \mathbf{XW_K}$ (Shape: N_X x D_Q)
Value Vectors: $\mathbf{V} = \mathbf{XW_V}$ (Shape: N_X x D_V)
Similarities: $E = \mathbf{QK}^T$ (Shape: N_X x N_X) $E_{i,j} = \mathbf{Q_i} \cdot \mathbf{K_j} / \mathrm{sqrt}(D_Q)$
Attention weights: A = softmax(E, dim=1) (Shape: N_X x N_X)
Output vectors: $Y = A\mathbf{V}$ (Shape: N_X x D_V) $Y_i = \sum_j A_{i,j}\mathbf{V_j}$



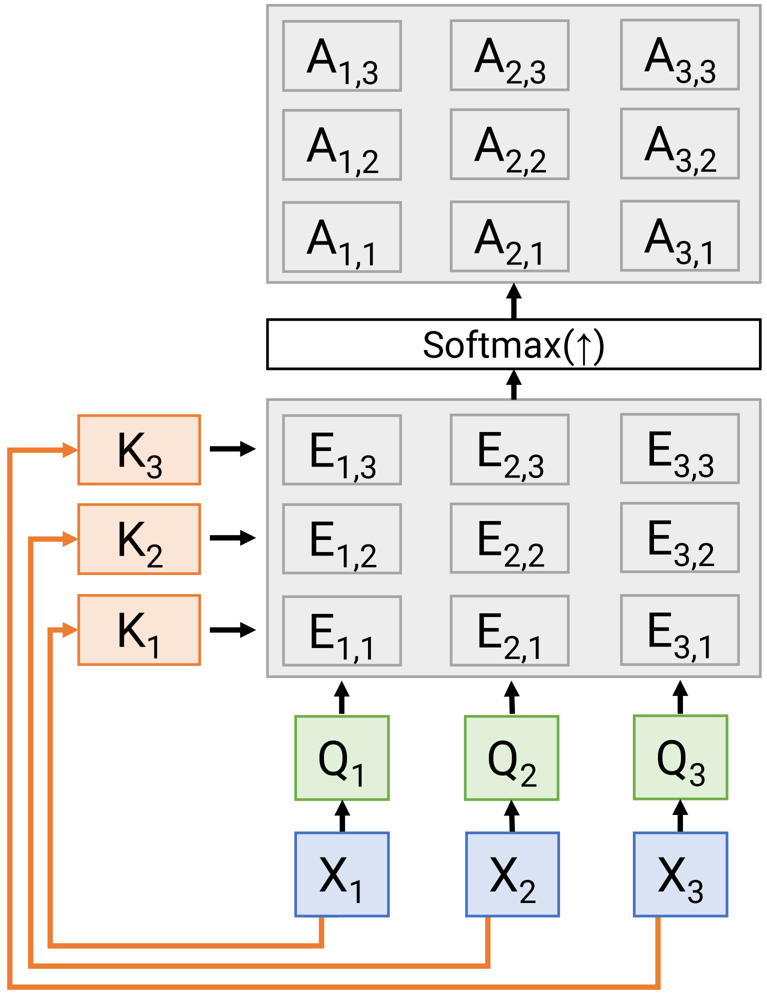
Slide Credit: Justin Johnson

Self-Attention Layer

One **query** per **input vector**

Inputs:
Input vectors: **X** (Shape: N_X x D_X)
Key matrix: W_K (Shape: D_X x D_Q)
Value matrix: W_V (Shape: D_X x D_V)
Query matrix: W_Q (Shape: D_X x D_Q)

Computation:
Query vectors: $Q = XW_Q$
Key vectors: $K = XW_K$ (Shape: N_X x D_Q)
Value Vectors: $V = XW_V$ (Shape: N_X x D_V)
Similarities: $E = QK^T$ (Shape: N_X x N_X) $E_{i,j} = Q_i \cdot K_j / \text{sqrt}(D_Q)$
Attention weights: $A = \text{softmax}(E, \text{dim}=1)$ (Shape: N_X x N_X)
Output vectors: $Y = AV$ (Shape: N_X x D_V) $Y_i = \sum_j A_{i,j} V_j$



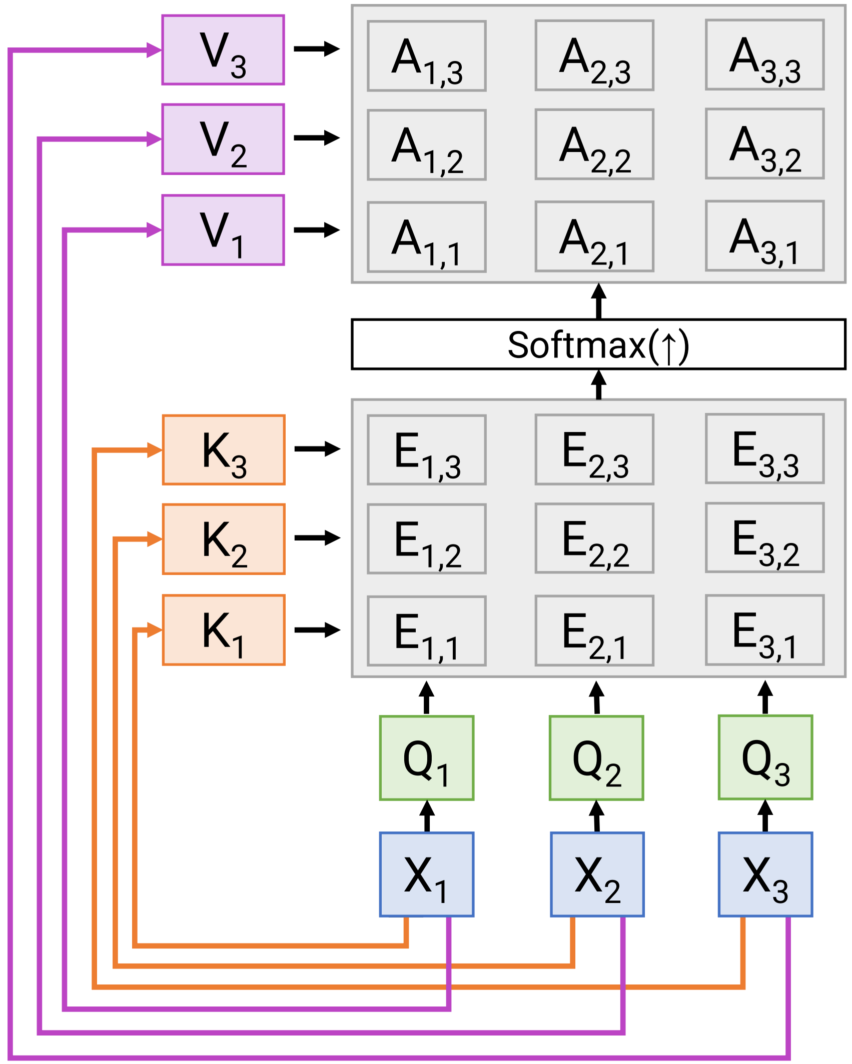
Slide Credit: Justin Johnson

Self-Attention Layer

One **query** per **input vector**

Inputs:
Input vectors: **X** (Shape: N_X x D_X)
Key matrix: $\mathbf{W_K}$ (Shape: D_X x D_Q)
Value matrix: $\mathbf{W_V}$ (Shape: D_X x D_V)
Query matrix: $\mathbf{W_Q}$ (Shape: D_X x D_Q)

Computation:
Query vectors: $\mathbf{Q} = \mathbf{XW_Q}$
Key vectors: $\mathbf{K} = \mathbf{XW_K}$ (Shape: N_X x D_Q)
Value Vectors: $\mathbf{V} = \mathbf{XW_V}$ (Shape: N_X x D_V)
Similarities: $E = \mathbf{QK}^T$ (Shape: N_X x N_X) $E_{i,j} = \mathbf{Q_i} \cdot \mathbf{K_j} / \text{sqrt}(D_Q)$
Attention weights: A = softmax(E, dim=1) (Shape: N_X x N_X)
Output vectors: $Y = A\mathbf{V}$ (Shape: N_X x D_V) $Y_i = \sum_j A_{i,j}\mathbf{V_j}$



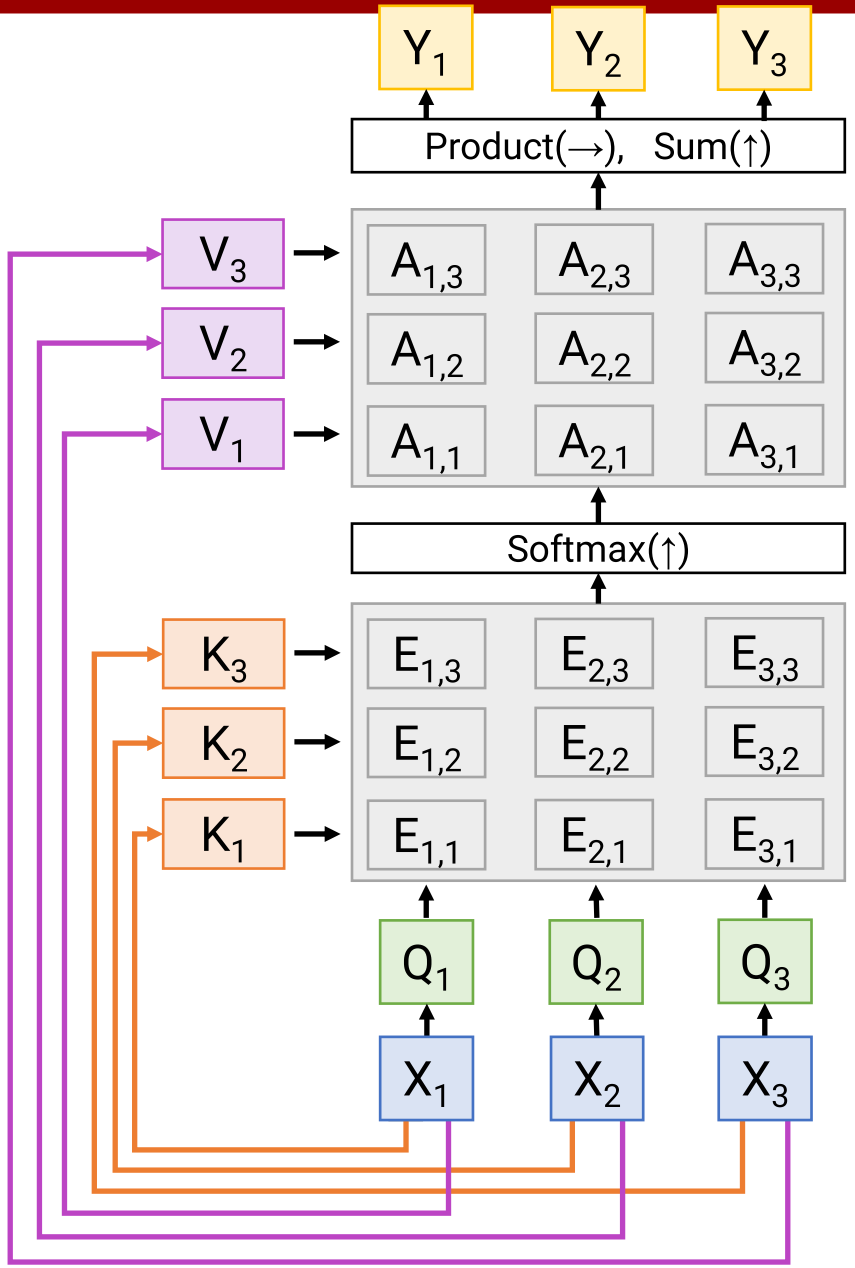
Slide Credit: Justin Johnson

Self-Attention Layer

One **query** per **input vector**

Inputs:
Input vectors: **X** (Shape: N_X x D_X)
Key matrix: $\mathbf{W_K}$ (Shape: D_X x D_Q)
Value matrix: $\mathbf{W_V}$ (Shape: D_X x D_V)
Query matrix: $\mathbf{W_Q}$ (Shape: D_X x D_Q)

Computation:
Query vectors: $\mathbf{Q} = \mathbf{XW_Q}$
Key vectors: $\mathbf{K} = \mathbf{XW_K}$ (Shape: N_X x D_Q)
Value Vectors: $\mathbf{V} = \mathbf{XW_V}$ (Shape: N_X x D_V)
Similarities: $E = \mathbf{QK}^T$ (Shape: N_X x N_X) $E_{i,j} = \mathbf{Q_i} \cdot \mathbf{K_j} / \mathrm{sqrt}(D_Q)$
Attention weights: A = softmax(E, dim=1) (Shape: N_X x N_X)
Output vectors: $Y = A\mathbf{V}$ (Shape: N_X x D_V) $Y_i = \sum_j A_{i,j}\mathbf{V_j}$

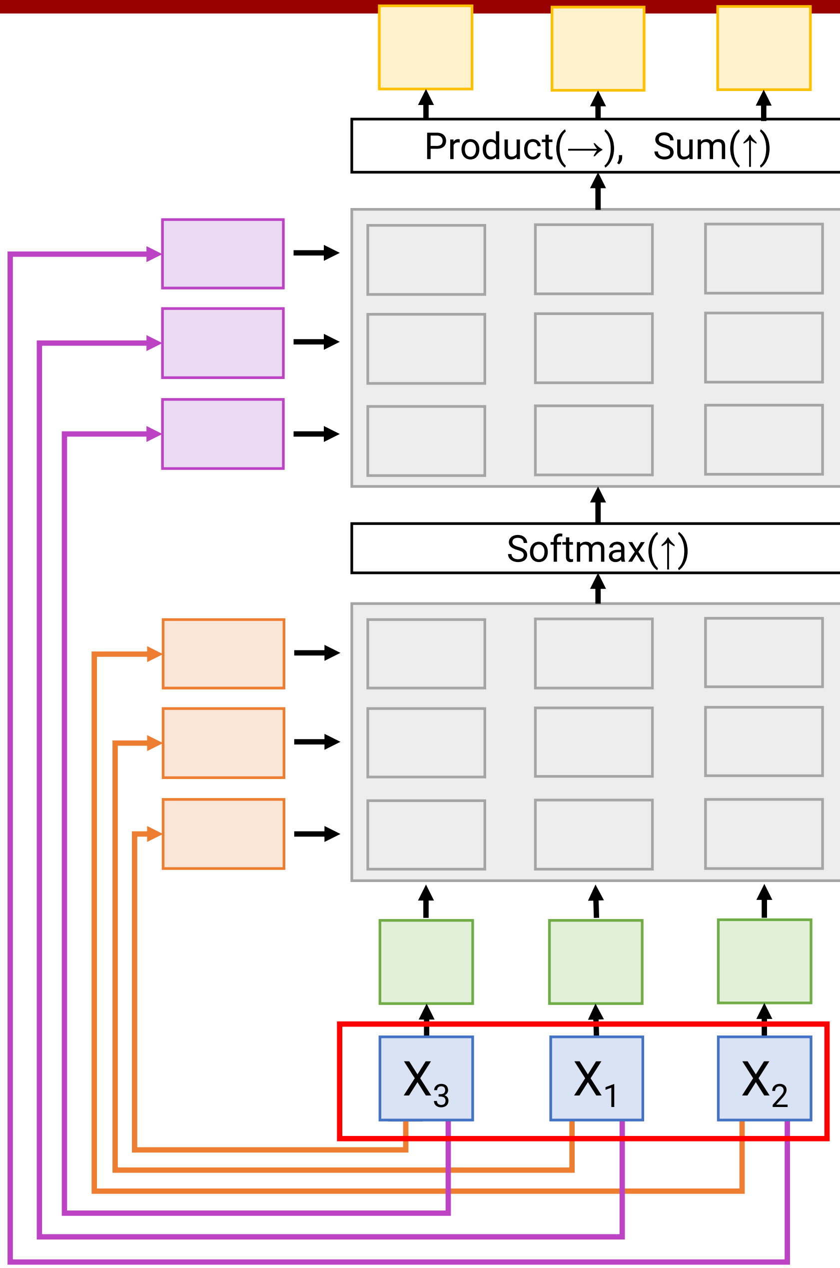


Self-Attention Layer

Inputs:
Input vectors: **X** (Shape: N_X x D_X)
Key matrix: **W_K** (Shape: D_X x D_Q)
Value matrix: W_V (Shape: D_X x D_V)
Query matrix: **W_Q** (Shape: D_X x D_Q)

Consider **permuting** the input vectors:

Computation:
Query vectors: **Q** = **XW_Q**
Key vectors: **K** = **XW_K** (Shape: N_X x D_Q)
Value Vectors: **V** = **XW_V** (Shape: N_X x D_V)
Similarities: E = **QK^T** (Shape: N_X x N_X) $E_{i,j} = Q_i \cdot K_j / \mathrm{sqrt}(D_Q)$
Attention weights: A = softmax(E, dim=1) (Shape: N_X x N_X)
Output vectors: Y = A**V** (Shape: N_X x D_V) $Y_i = \sum_j A_{i,j} V_j$



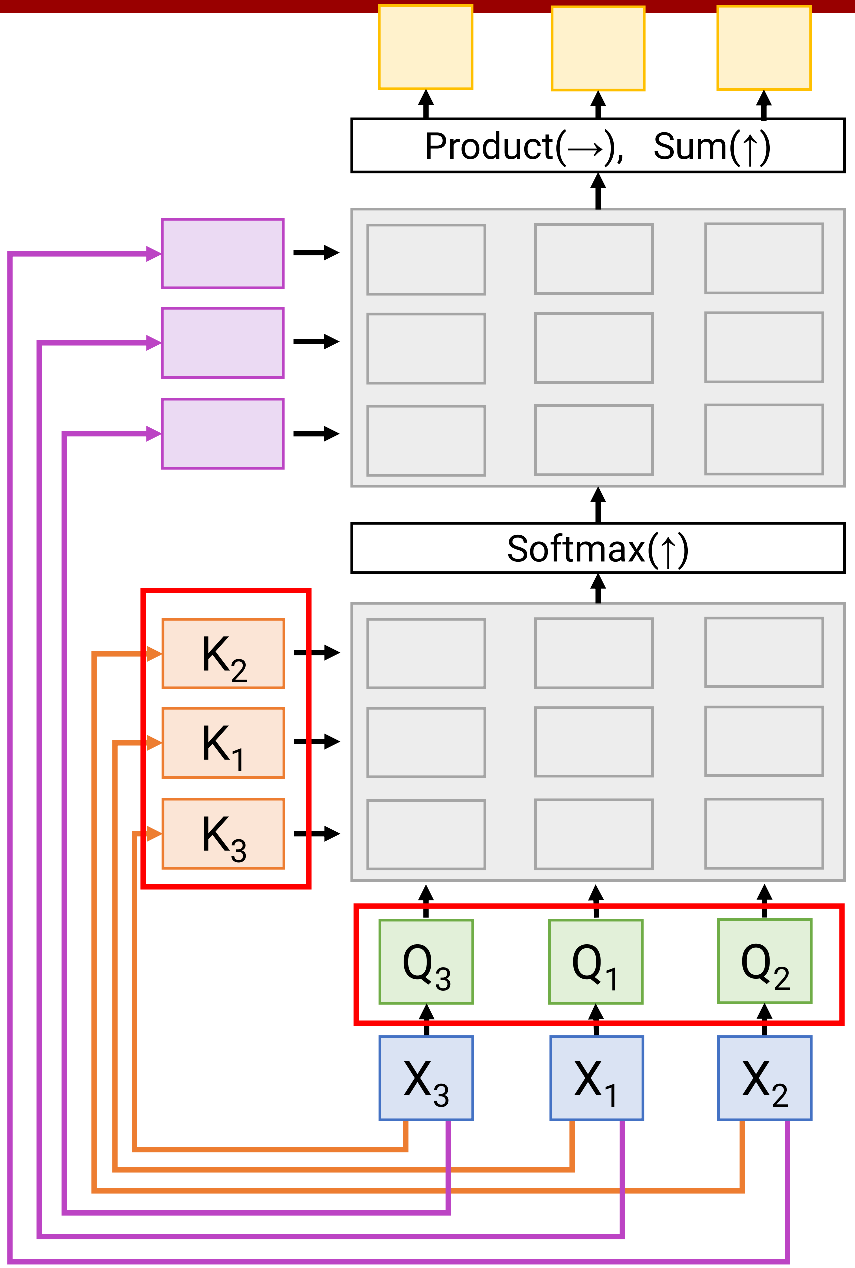
Self-Attention Layer

Inputs:
Input vectors: X (Shape: N_X x D_X)
Key matrix: W_K (Shape: D_X x D_Q)
Value matrix: W_V (Shape: D_X x D_V)
Query matrix: W_Q (Shape: D_X x D_Q)

Computation:
Query vectors: $Q = XW_Q$
Key vectors: $K = XW_K$ (Shape: N_X x D_Q)
Value Vectors: $V = XW_V$ (Shape: N_X x D_V)
Similarities: $E = QK^T$ (Shape: N_X x N_X) $E_{i,j} = Q_i \cdot K_j / \text{sqrt}(D_Q)$
Attention weights: $A = \text{softmax}(E, \text{dim}=1)$ (Shape: N_X x N_X)
Output vectors: $Y = AV$ (Shape: N_X x D_V) $Y_i = \sum_j A_{i,j} V_j$

Consider **permuting** the input vectors:

Queries and Keys will be the same, but permuted



Slide Credit: Justin Johnson

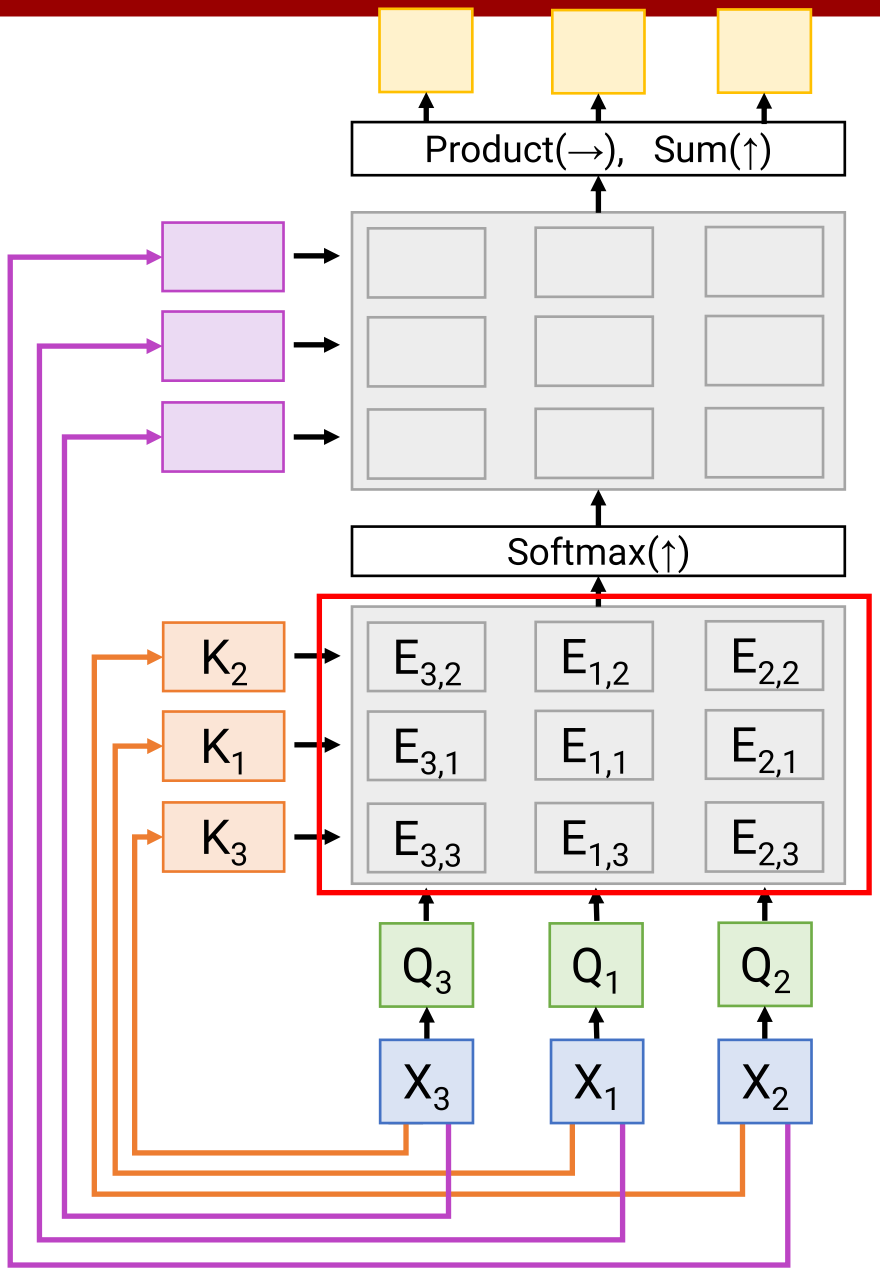
Self-Attention Layer

Inputs:
Input vectors: **X** (Shape: N_X x D_X)
Key matrix: **W_K** (Shape: D_X x D_Q)
Value matrix: **W_V** (Shape: D_X x D_V)
Query matrix: **W_Q** (Shape: D_X x D_Q)

Consider **permuting** the input vectors:

Similarities will be the same, but permuted

Computation:
Query vectors: **Q** = **XW_Q**
Key vectors: **K** = **XW_K** (Shape: N_X x D_Q)
Value Vectors: **V** = **XW_V** (Shape: N_X x D_V)
Similarities: E = QK^T (Shape: N_X x N_X) $E_{i,j} = Q_i \cdot K_j / \text{sqrt}(D_Q)$
Attention weights: A = softmax(E, dim=1) (Shape: N_X x N_X)
Output vectors: Y = AV (Shape: N_X x D_V) $Y_i = \sum_j A_{i,j} V_j$



Slide Credit: Justin Johnson

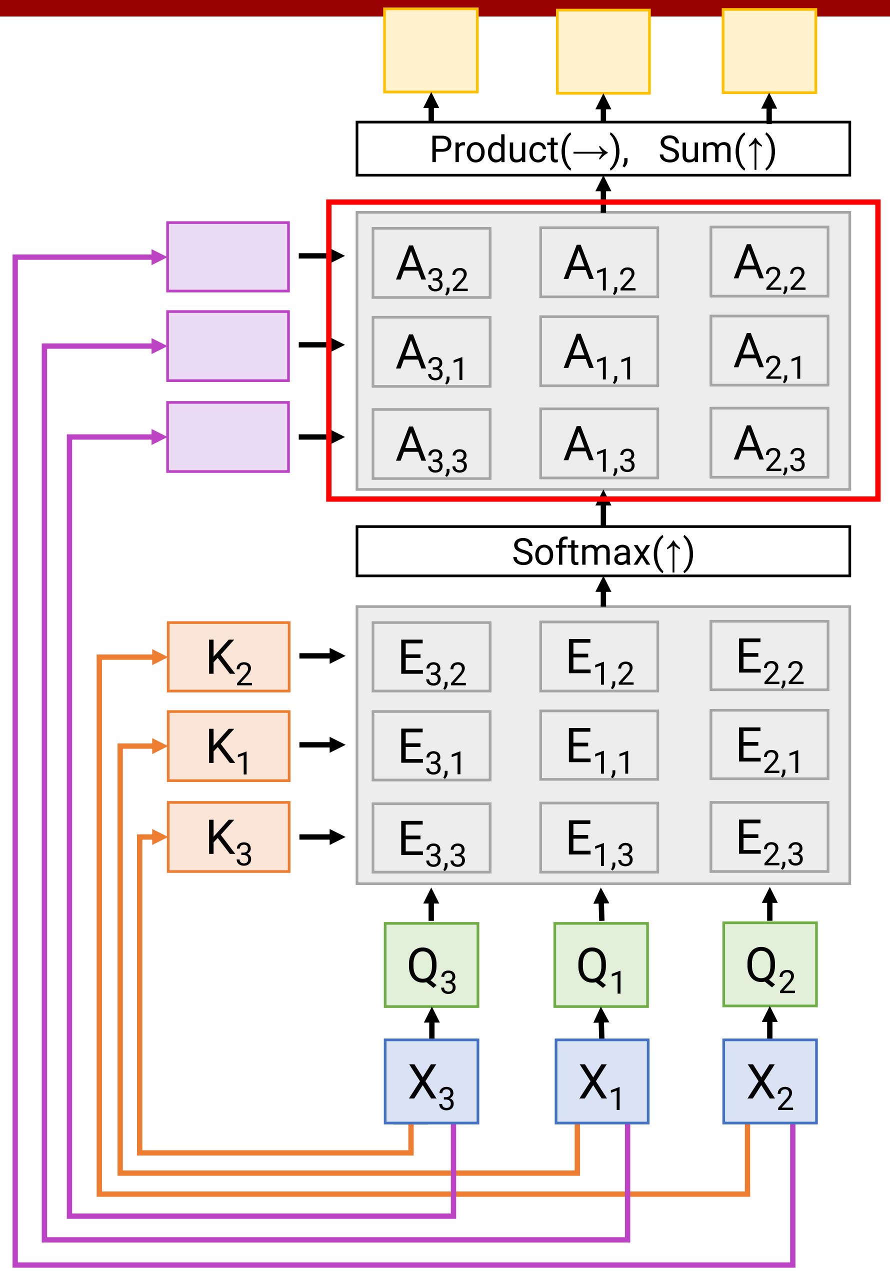
Self-Attention Layer

Inputs:
Input vectors: **X** (Shape: N_X x D_X)
Key matrix: $\mathbf{W_K}$ (Shape: D_X x D_Q)
Value matrix: $\mathbf{W_V}$ (Shape: D_X x D_V)
Query matrix: $\mathbf{W_Q}$ (Shape: D_X x D_Q)

Consider **permuting** the input vectors:

Attention weights will be the same, but permuted

Computation:
Query vectors: $\mathbf{Q} = \mathbf{XW_Q}$
Key vectors: $\mathbf{K} = \mathbf{XW_K}$ (Shape: N_X x D_Q)
Value Vectors: $\mathbf{V} = \mathbf{XW_V}$ (Shape: N_X x D_V)
Similarities: $E = \mathbf{QK}^T$ (Shape: N_X x N_X) $E_{i,j} = \mathbf{Q_i} \cdot \mathbf{K_j} / \mathrm{sqrt}(D_Q)$
Attention weights: A = softmax(E, dim=1) (Shape: N_X x N_X)
Output vectors: $Y = A\mathbf{V}$ (Shape: N_X x D_V) $Y_i = \sum_j A_{i,j} \mathbf{V_j}$



Slide Credit: Justin Johnson

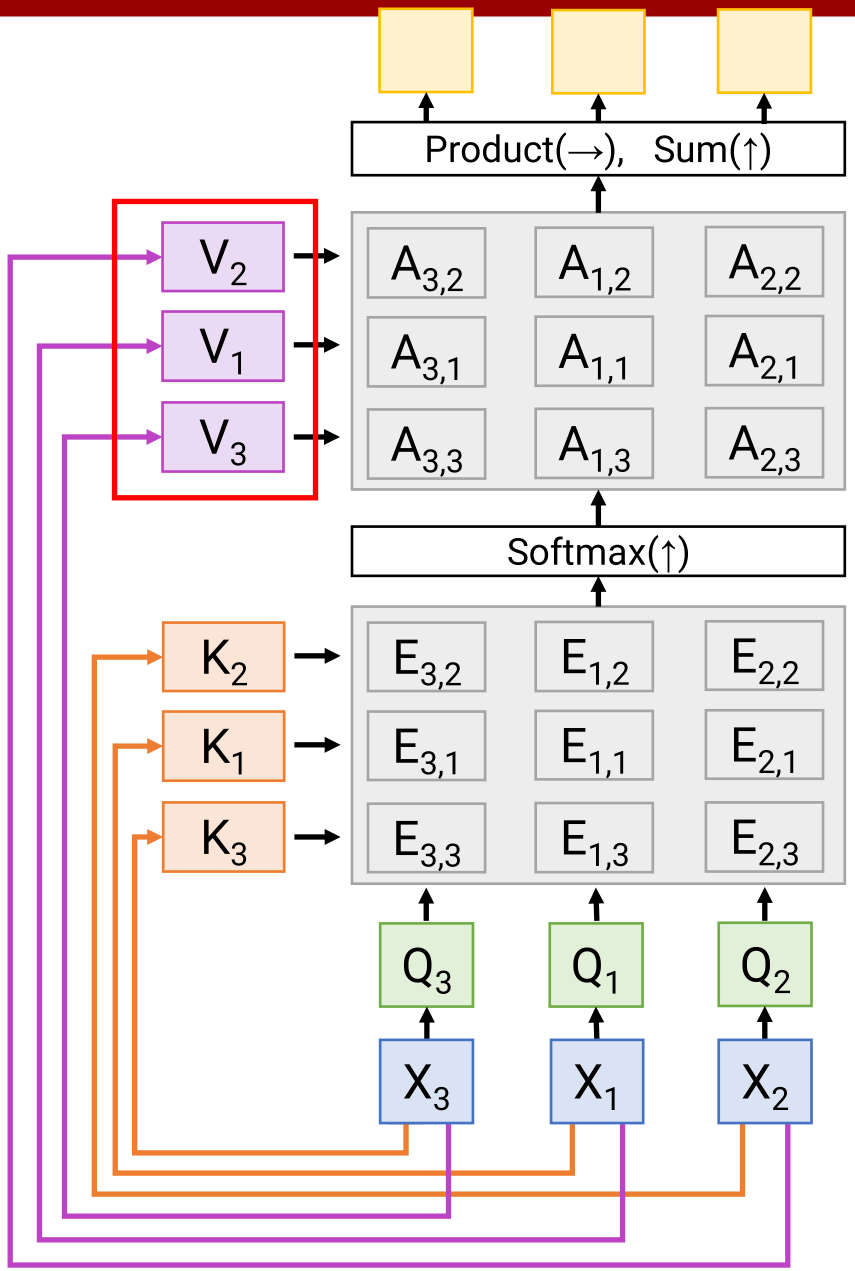
Self-Attention Layer

Inputs:
Input vectors: **X** (Shape: N_X x D_X)
Key matrix: **W_K** (Shape: D_X x D_Q)
Value matrix: **W_V** (Shape: D_X x D_V)
Query matrix: **W_Q** (Shape: D_X x D_Q)

Consider **permuting** the input vectors:

Values will be the same, but permuted

Computation:
Query vectors: **Q** = **XW_Q**
Key vectors: **K** = **XW_K** (Shape: N_X x D_Q)
Value Vectors: **V** = **XW_V** (Shape: N_X x D_V)
Similarities: E = **QK^T** (Shape: N_X x N_X) $E_{i,j} = Q_i \cdot K_j / \mathrm{sqrt}(D_Q)$
Attention weights: A = softmax(E, dim=1) (Shape: N_X x N_X)
Output vectors: Y = A**V** (Shape: N_X x D_V) $Y_i = \sum_j A_{i,j} V_j$



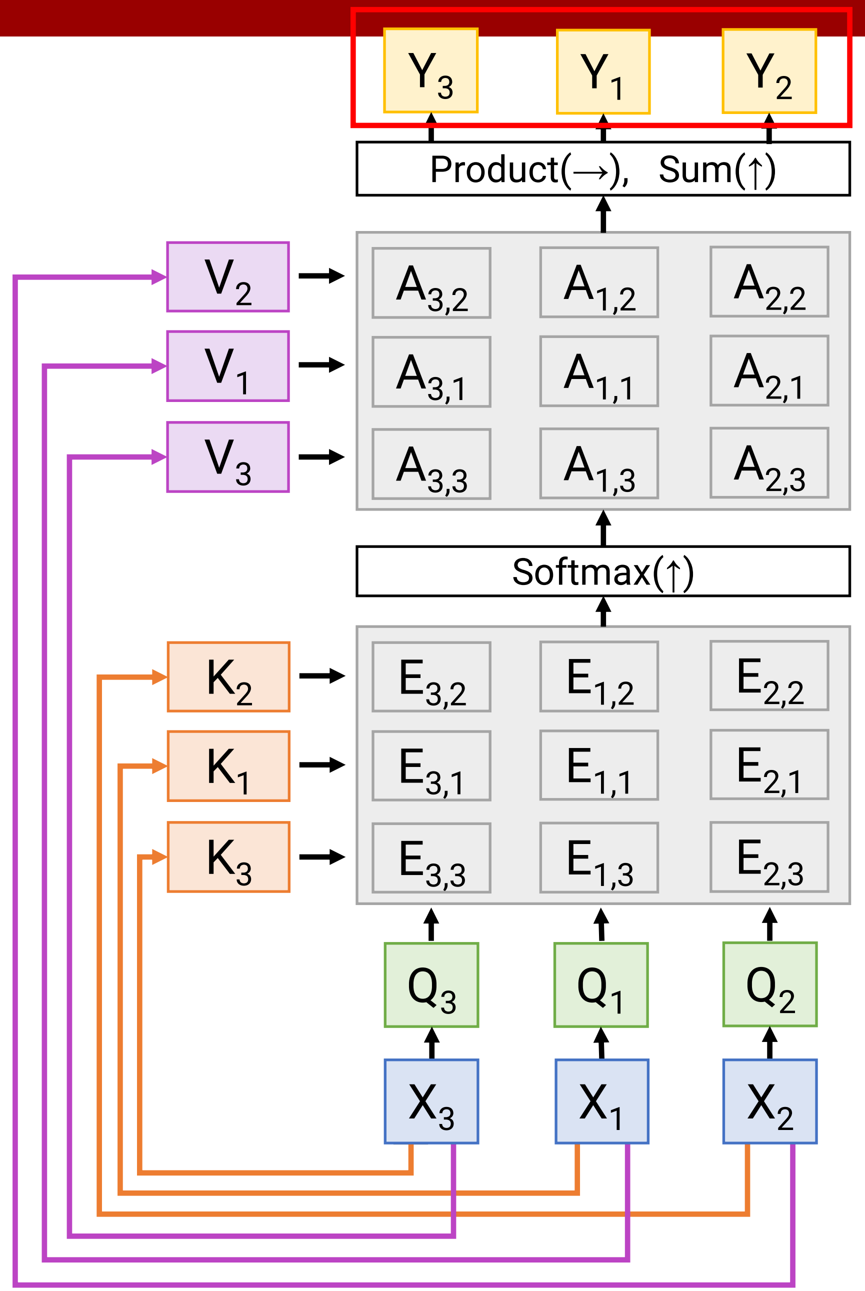
Self-Attention Layer

Inputs:
Input vectors: **X** (Shape: N_X x D_X)
Key matrix: **W_K** (Shape: D_X x D_Q)
Value matrix: **W_V** (Shape: D_X x D_V)
Query matrix: **W_Q** (Shape: D_X x D_Q)

Consider **permuting** the input vectors:

Outputs will be the same, but permuted

Computation:
Query vectors: $Q = XW_Q$
Key vectors: $K = XW_K$ (Shape: N_X x D_Q)
Value Vectors: $V = XW_V$ (Shape: N_X x D_V)
Similarities: $E = QK^T$ (Shape: N_X x N_X) $E_{i,j} = Q_i \cdot K_j / \text{sqrt}(D_Q)$
Attention weights: $A = \text{softmax}(E, \text{dim}=1)$ (Shape: N_X x N_X)
Output vectors: $Y = AV$ (Shape: N_X x D_V) $Y_i = \sum_j A_{i,j} V_j$



Self-Attention Layer

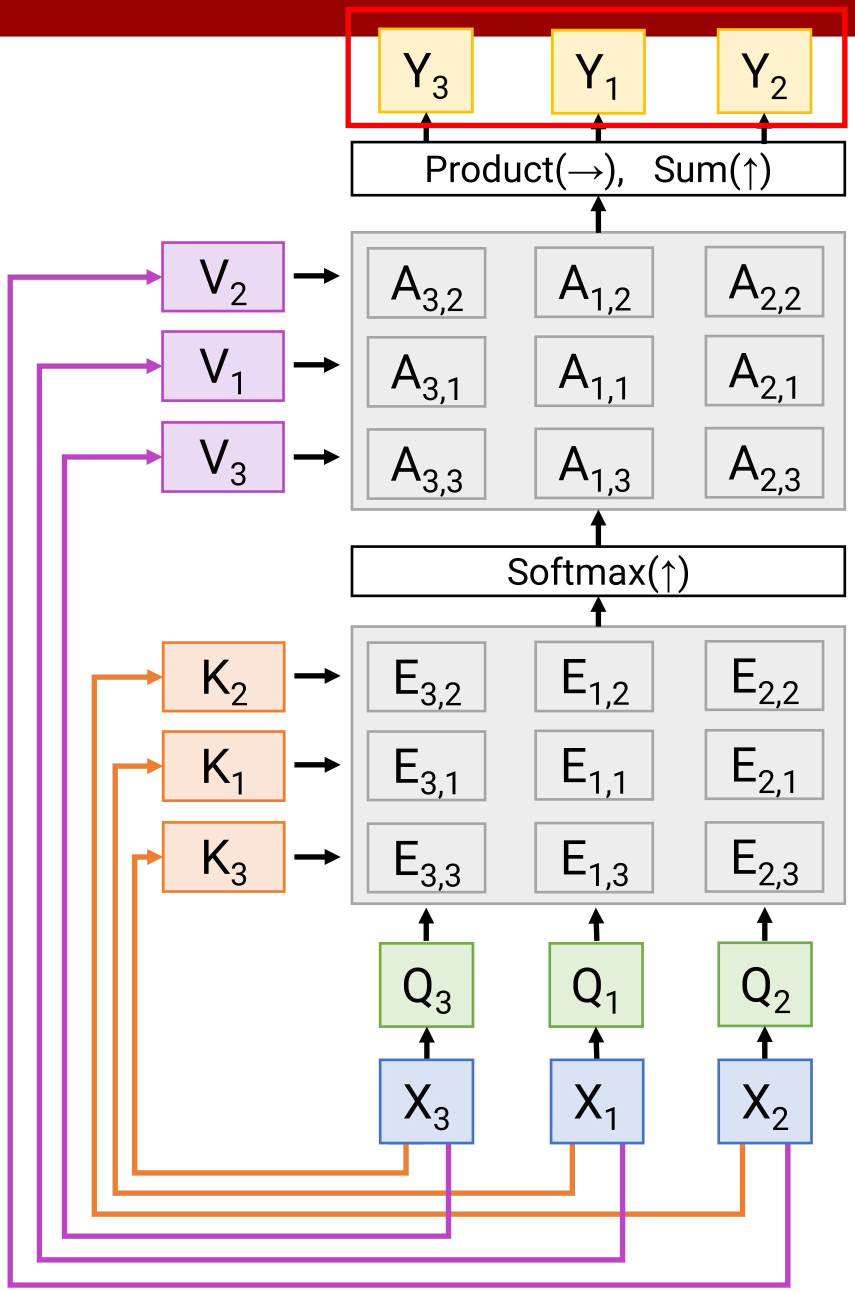
Inputs:
Input vectors: **X** (Shape: N_X x D_X)
Key matrix: **W_K** (Shape: D_X x D_Q)
Value matrix: **W_V** (Shape: D_X x D_V)
Query matrix: **W_Q** (Shape: D_X x D_Q)

Computation:
Query vectors: **Q** = **XW_Q**
Key vectors: **K** = **XW_K** (Shape: N_X x D_Q)
Value Vectors: **V** = **XW_V** (Shape: N_X x D_V)
Similarities: E = **QK^T** (Shape: N_X x N_X) $E_{i,j} = Q_i \cdot K_j / \mathrm{sqrt}(D_Q)$
Attention weights: A = softmax(E, dim=1) (Shape: N_X x N_X)
Output vectors: Y = A**V** (Shape: N_X x D_V) $Y_i = \sum_j A_{i,j} V_j$

Consider **permuting** the input vectors:

Outputs will be the same, but permuted

Self-attention layer is **Permutation Equivariant**
f(s(x)) = s(f(x))

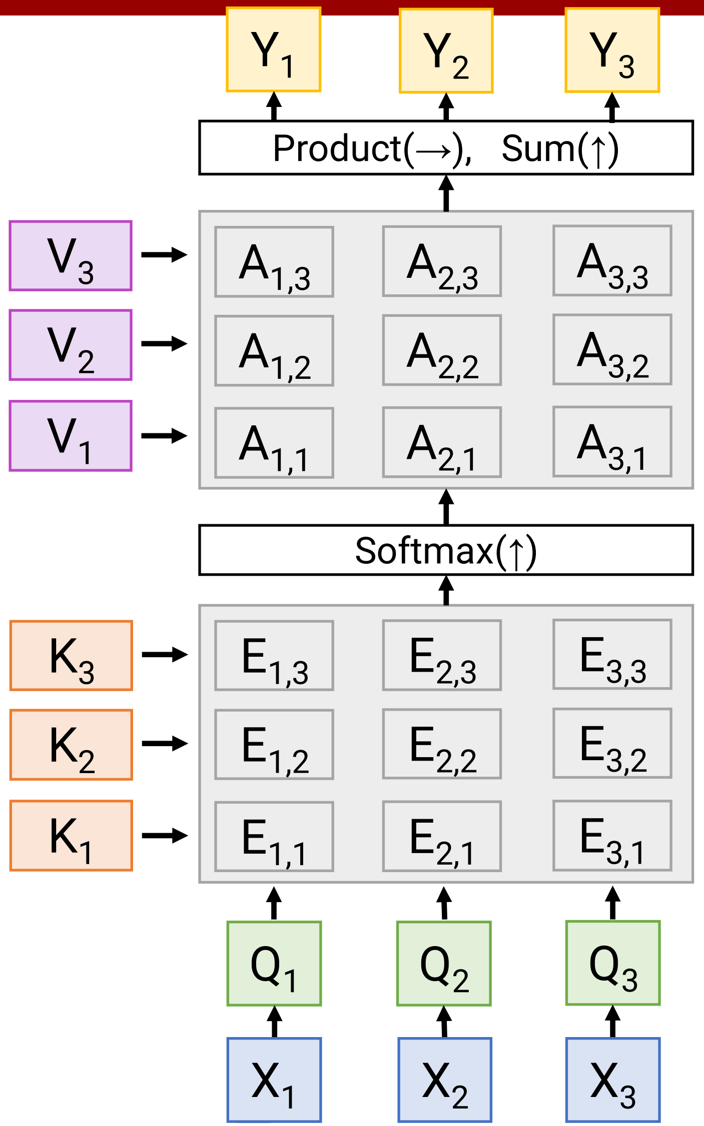


Self-Attention Layer

Inputs:
Input vectors: **X** (Shape: N_X x D_X)
Key matrix: W_K (Shape: D_X x D_Q)
Value matrix: W_V (Shape: D_X x D_V)
Query matrix: W_Q (Shape: D_X x D_Q)

Self attention doesn't "know" the order of the vectors it is processing!

Computation:
Query vectors: $Q = XW_Q$
Key vectors: $K = XW_K$ (Shape: N_X x D_Q)
Value Vectors: $V = XW_V$ (Shape: N_X x D_V)
Similarities: $E = QK^T$ (Shape: N_X x N_X) $E_{i,j} = Q_i \cdot K_j / \mathrm{sqrt}(D_Q)$
Attention weights: A = softmax(E, dim=1) (Shape: N_X x N_X)
Output vectors: $Y = AV$ (Shape: N_X x D_V) $Y_i = \sum_j A_{i,j} V_j$



Self-Attention Layer

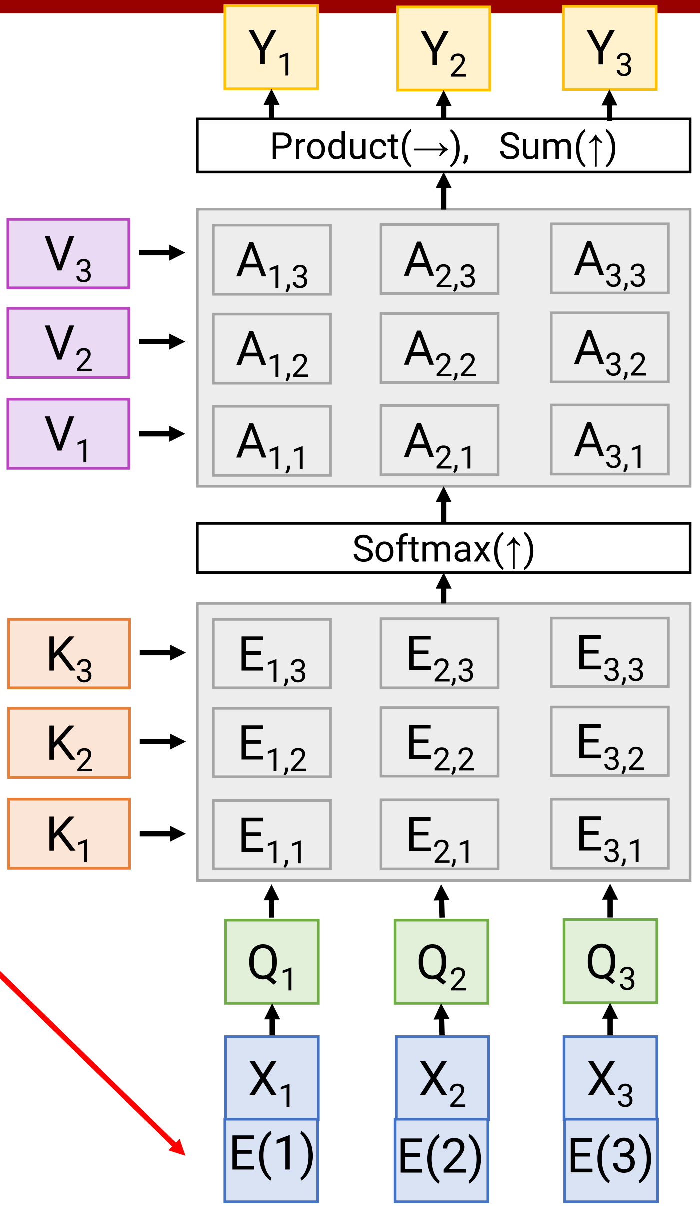
Inputs:
Input vectors: **X** (Shape: $N_X \times D_X$)
Key matrix: W_K (Shape: $D_X \times D_Q$)
Value matrix: W_V (Shape: $D_X \times D_V$)
Query matrix: W_Q (Shape: $D_X \times D_Q$)

Computation:
Query vectors: $Q = XW_Q$
Key vectors: $K = XW_K$ (Shape: $N_X \times D_Q$)
Value Vectors: $V = XW_V$ (Shape: $N_X \times D_V$)
Similarities: $E = QK^T$ (Shape: $N_X \times N_X$) $E_{i,j} = Q_i \cdot K_j / \text{sqrt}(D_Q)$
Attention weights: $A = \text{softmax}(E, \text{dim}=1)$ (Shape: $N_X \times N_X$)
Output vectors: $Y = AV$ (Shape: $N_X \times D_V$) $Y_i = \sum_j A_{i,j} V_j$

Self attention doesn't "know" the order of the vectors it is processing!

In order to make processing position-aware, concatenate input with **positional encoding**

E can be learned lookup table, or fixed function



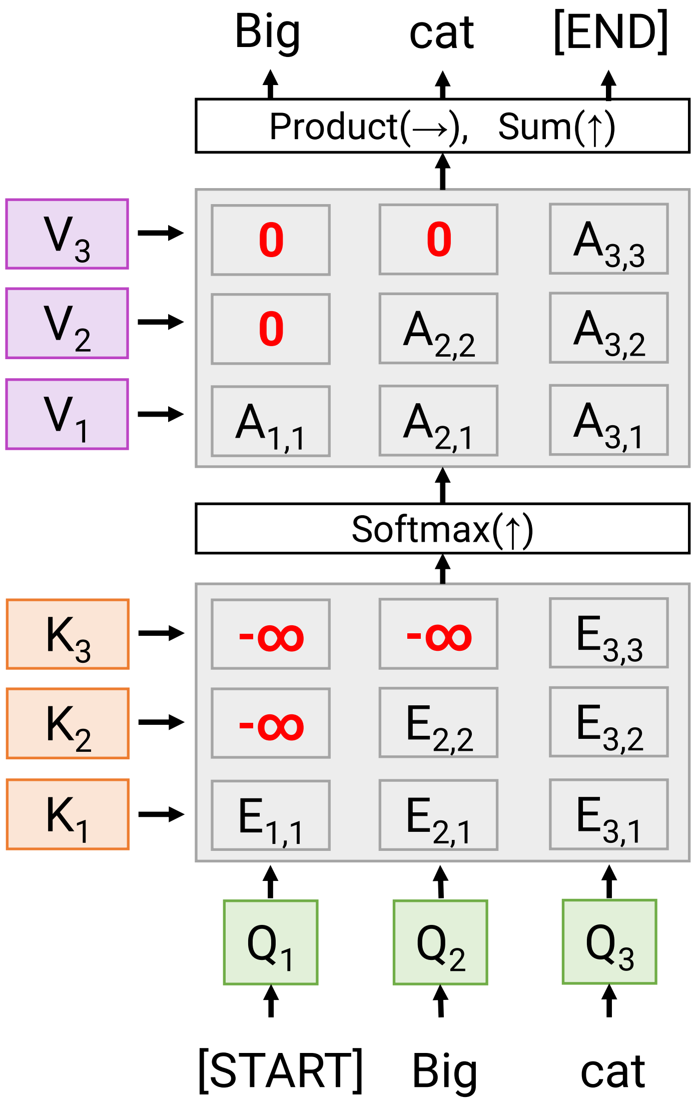
Masked Self-Attention Layer

Inputs:
Input vectors: **X** (Shape: $N_X \times D_X$)
Key matrix: W_K (Shape: $D_X \times D_Q$)
Value matrix: W_V (Shape: $D_X \times D_V$)
Query matrix: W_Q (Shape: $D_X \times D_Q$)

Computation:
Query vectors: $Q = XW_Q$
Key vectors: $K = XW_K$ (Shape: $N_X \times D_Q$)
Value Vectors: $V = XW_V$ (Shape: $N_X \times D_V$)
Similarities: $E = QK^T$ (Shape: $N_X \times N_X$) $E_{i,j} = Q_i \cdot K_j / \mathrm{sqrt}(D_Q)$
Attention weights: $A = \mathrm{softmax}(E, dim=1)$ (Shape: $N_X \times N_X$)
Output vectors: $Y = AV$ (Shape: $N_X \times D_V$) $Y_i = \sum_j A_{i,j} V_j$

Don't let vectors "look ahead" in the sequence

Used for language modeling (predict next word)



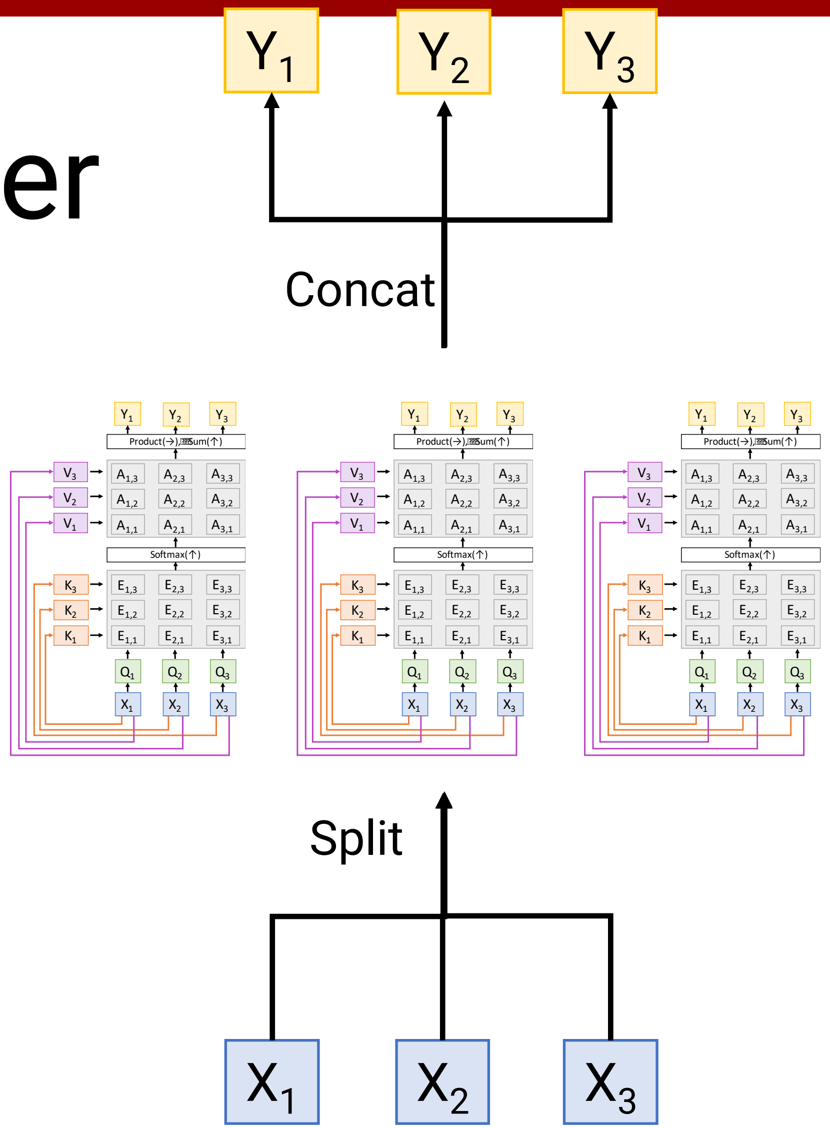
Slide Credit: Justin Johnson

Multihead Self-Attention Layer

Inputs:
Input vectors: **X** (Shape: N_X x D_X)
Key matrix: $\mathbf{W_K}$ (Shape: D_X x D_Q)
Value matrix: $\mathbf{W_V}$ (Shape: D_X x D_V)
Query matrix: $\mathbf{W_Q}$ (Shape: D_X x D_Q)

Computation:
Query vectors: $\mathbf{Q} = \mathbf{XW_Q}$
Key vectors: $\mathbf{K} = \mathbf{XW_K}$ (Shape: N_X x D_Q)
Value Vectors: $\mathbf{V} = \mathbf{XW_V}$ (Shape: N_X x D_V)
Similarities: $E = \mathbf{QK}^T$ (Shape: N_X x N_X) $E_{i,j} = \mathbf{Q_i} \cdot \mathbf{K_j} / \mathrm{sqrt}(D_Q)$
Attention weights: A = softmax(E, dim=1) (Shape: N_X x N_X)
Output vectors: $Y = A\mathbf{V}$ (Shape: N_X x D_V) $Y_i = \sum_j A_{i,j}\mathbf{V_j}$

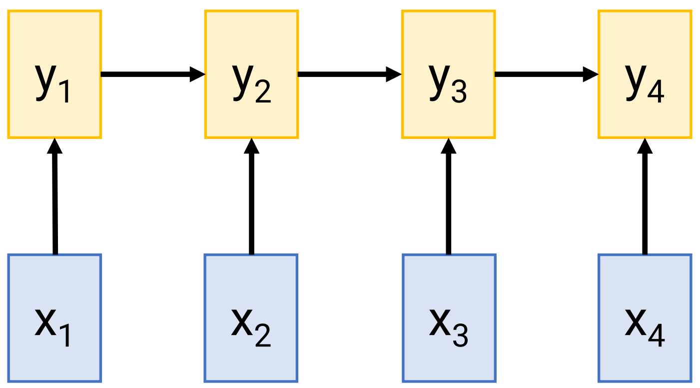
Use H independent "Attention Heads" in parallel



Slide Credit: Justin Johnson

Three Ways of Processing Sequences

Recurrent Neural Network



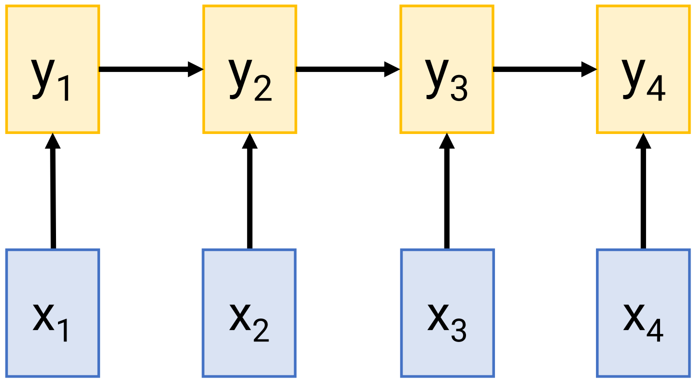
Works on **Ordered Sequences**

(+) Good at long sequences: After one RNN layer, h_T "sees" the whole sequence

(-) Not parallelizable: need to compute hidden states sequentially

Three Ways of Processing Sequences

Recurrent Neural Network



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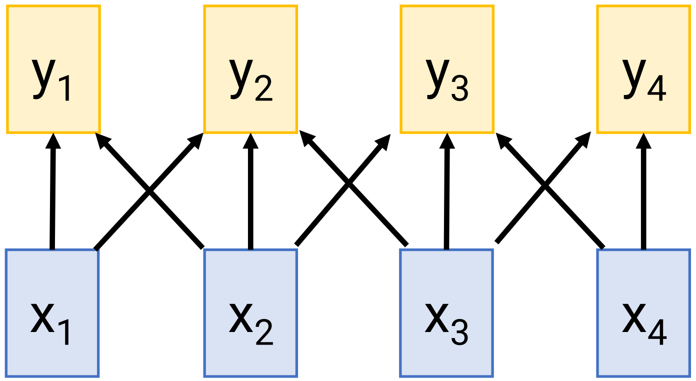
1D Convolution



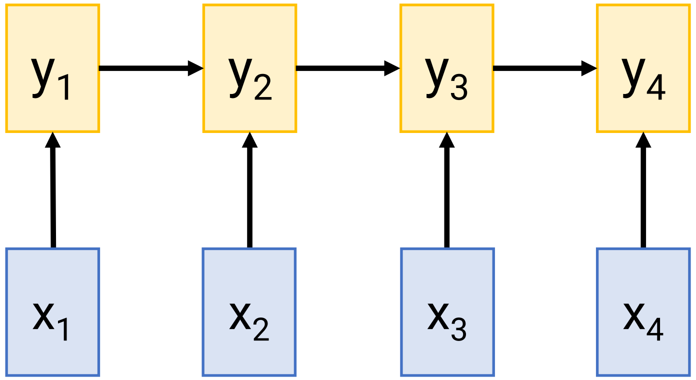
Works on **Multidimensional Grids**

(-) Bad at long sequences: Need to stack many conv layers for outputs to "see" the whole sequence

(+) Highly parallel: Each output can be computed in parallel

Three Ways of Processing Sequences

Recurrent Neural Network



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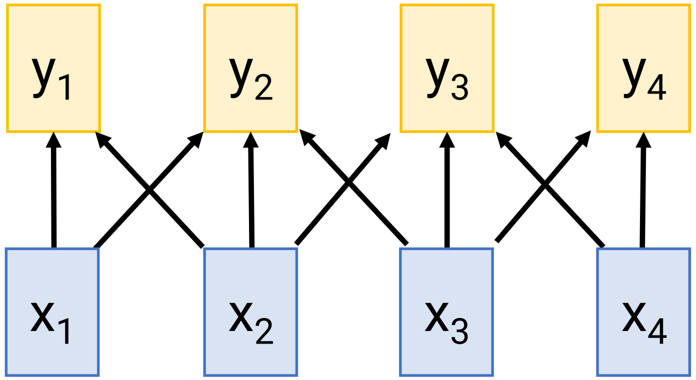

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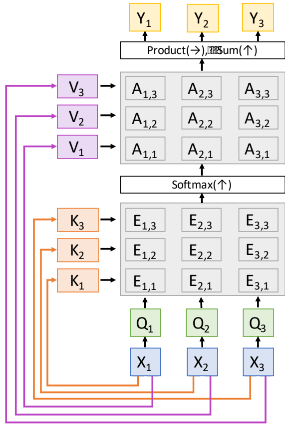
Self-Attention



Works on **Sets of Vectors**

(-) Good at long sequences: after one self-attention layer, each output "sees" all inputs!

(+) Highly parallel: Each output can be computed in parallel

(-) Very memory intensive

Slide Credit: Justin Johnson

Three Ways of Processing Sequences

Recurrent Neural Network | 1D Convolution | Self-Attention

Attention is all you need

Vaswani et al, NeurIPS 2017

Works on **Ordered Sequences**
(+) Good at long sequences: After one RNN layer, h_T "sees" the whole sequence
(-) Not parallelizable: need to compute hidden states sequentially

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(-) Bad at long sequences: Need to stack many conv layers for outputs to "see" the whole sequence
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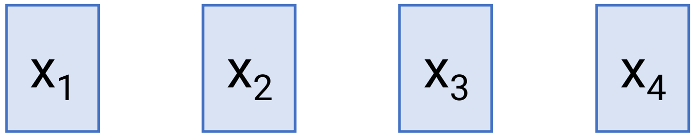
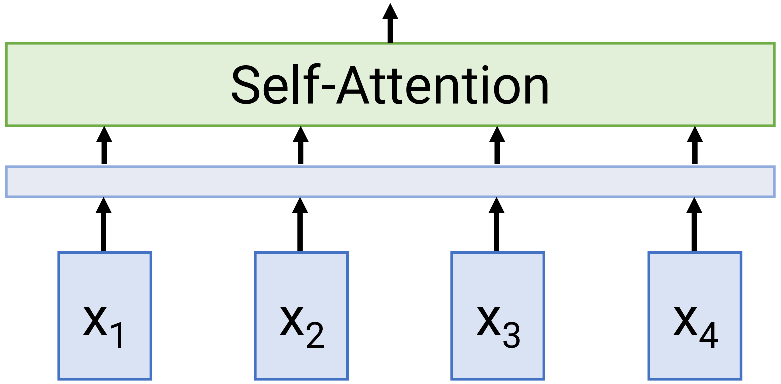
The Transformer



Vaswani et al, “Attention is all you need”, NeurIPS 2017

The Transformer

All vectors interact
with each other

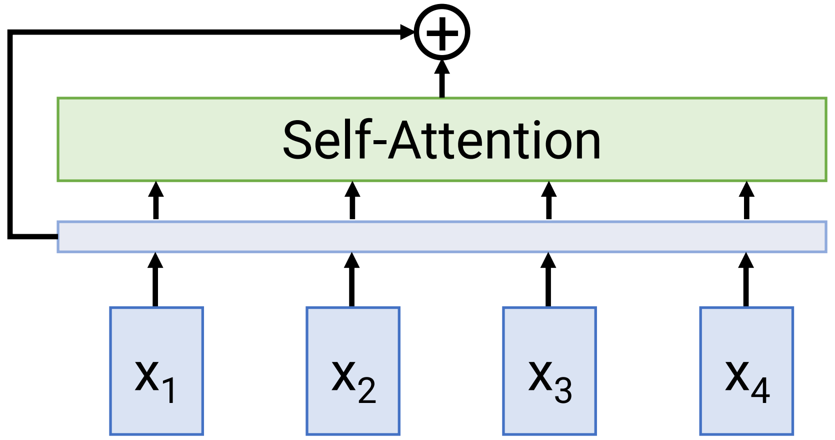


Vaswani et al, “Attention is all you need”, NeurIPS 2017

The Transformer

Residual connection

All vectors interact with each other



Vaswani et al, “Attention is all you need”, NeurIPS 2017

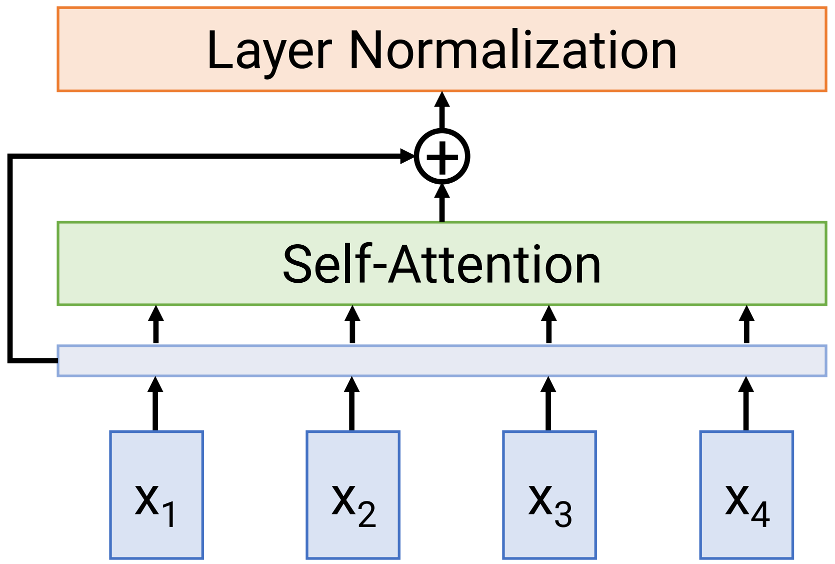
The Transformer

Recall **Layer Normalization**:
Given $h_1, \ldots, h_N$ (Shape: D)
scale: γ (Shape: D)
shift: β (Shape: D)
$\mu_i = (1/D)\sum_j h_{i,j}$ (scalar)
$\sigma_i = (\sum_j (h_{i,j} - \mu_i)^2)^{1/2}$ (scalar)
$z_i = (h_i - \mu_i) / \sigma_i$
$y_i = \gamma * z_i + \beta$

Ba et al, 2016

Residual connection

All vectors interact with each other



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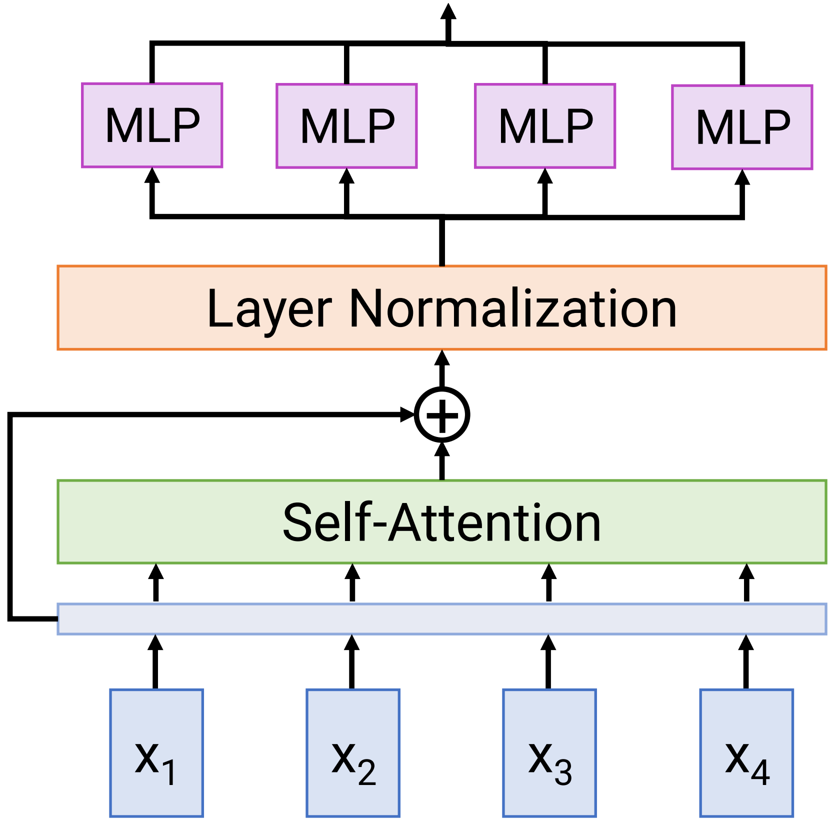
Ba et al, 2016

MLP independently on each vector

Residual connection

All vectors interact with each other



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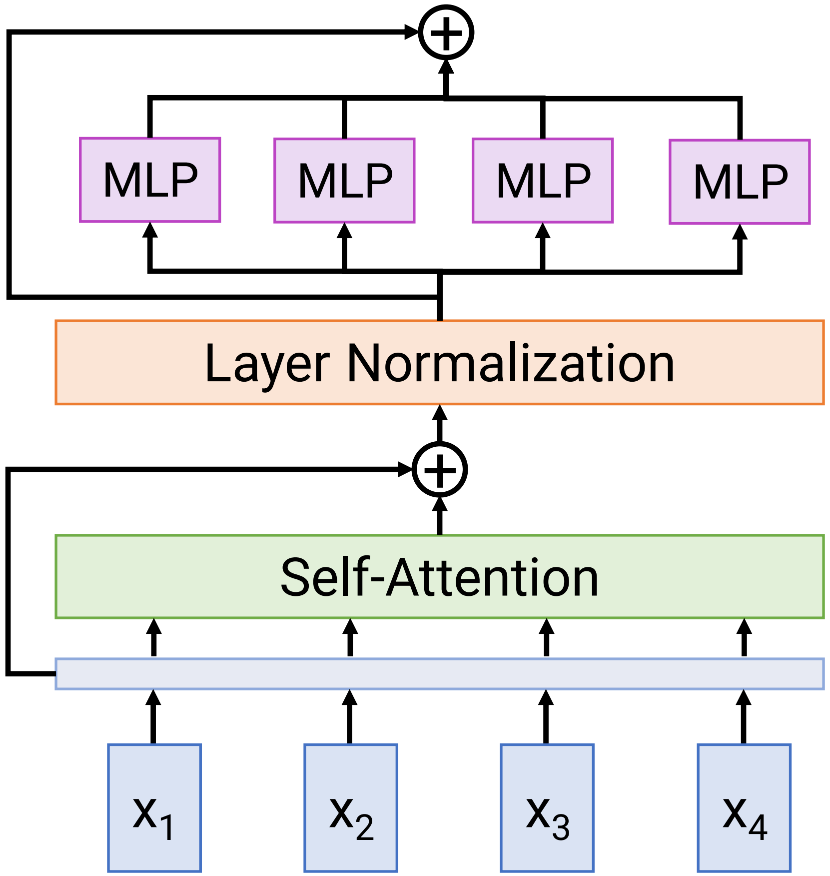

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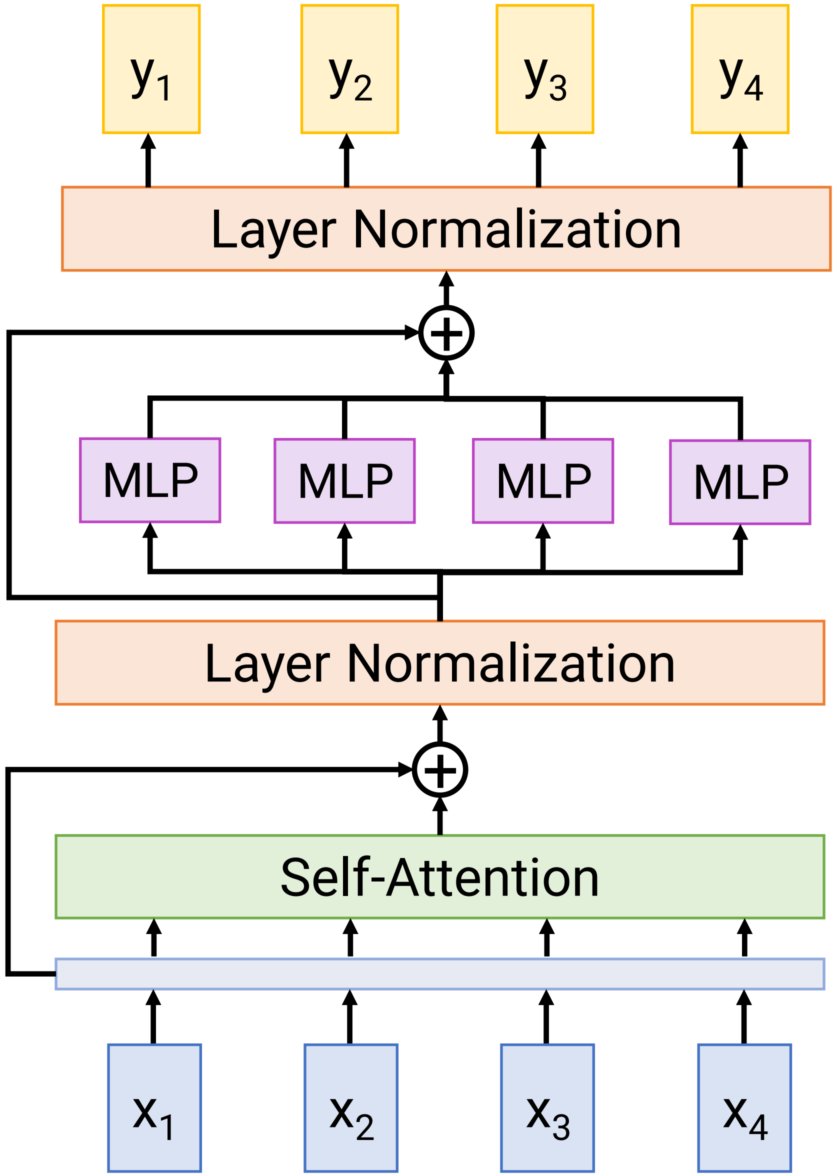


Vaswani et al, "Attention is all you need", NeurIPS 2017

Slide Credit: Justin Johnson

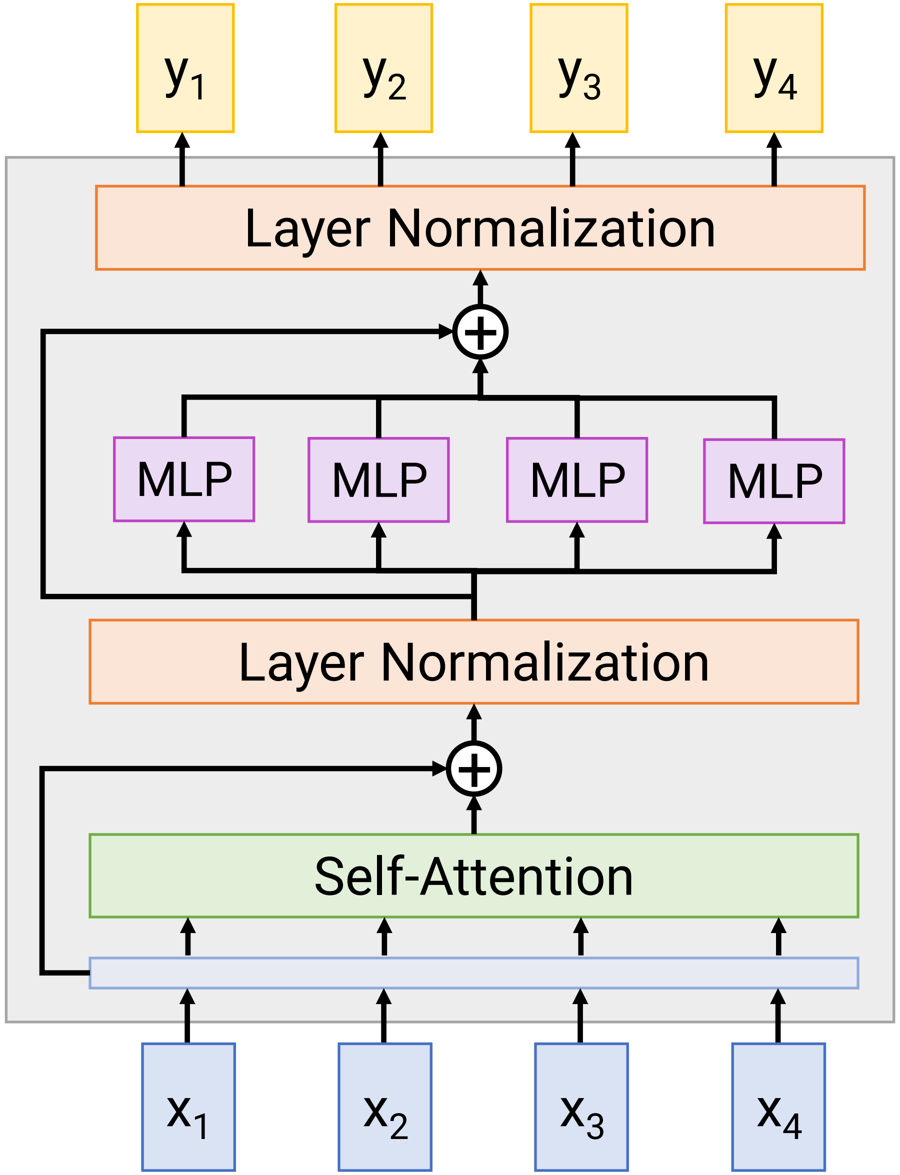
The Transformer

<u>**Transformer Block:**</u>
Input: Set of vectors x
Output: Set of vectors y

Self-attention is the only interaction between vectors!

Layer norm and MLP work independently per vector

Highly scalable, highly parallelizable



Vaswani et al, "Attention is all you need", NeurIPS 2017

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<u>Transformer Block</u>:
Input: Set of vectors x
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Self-attention is the only interaction between vectors!

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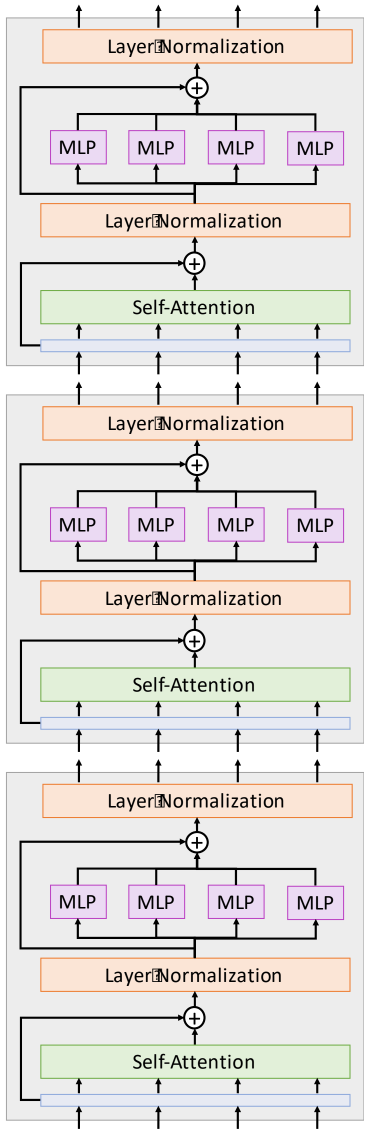
Highly scalable, highly parallelizable

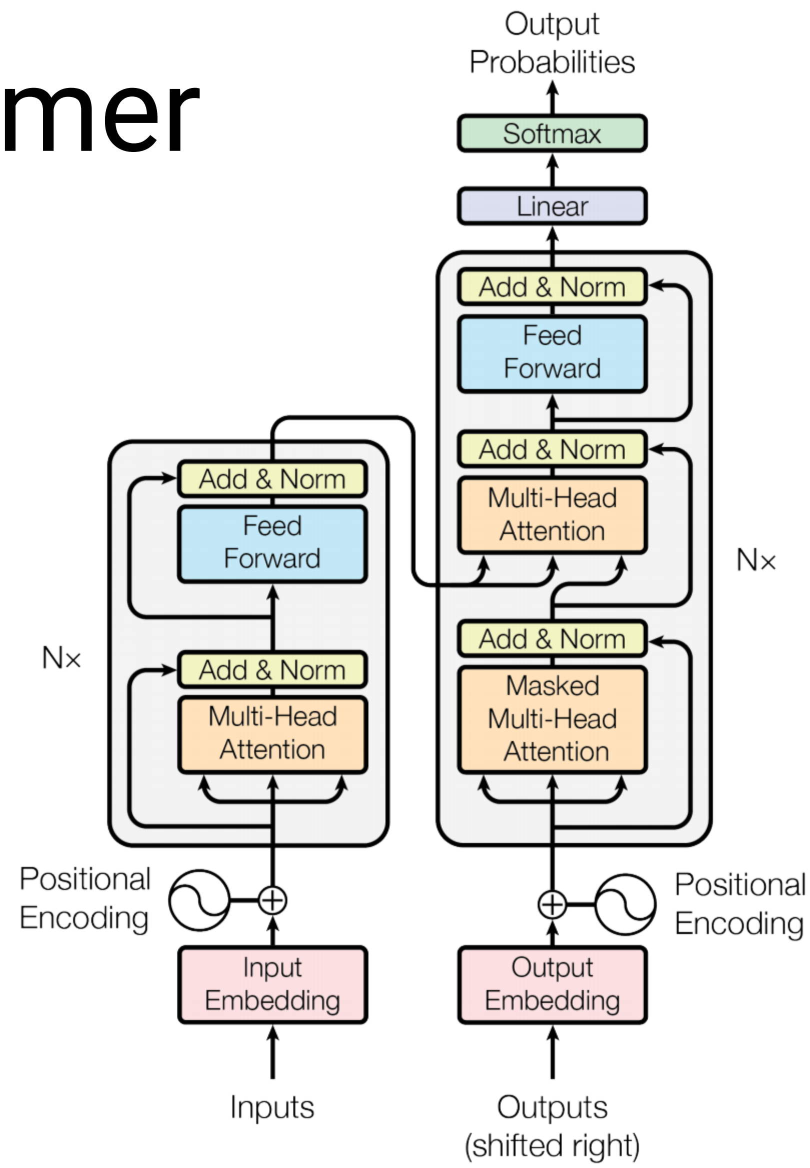
A **Transformer** is a sequence of transformer blocks



Vaswani et al, "Attention is all you need", NeurIPS 2017

Slide Credit: Justin Johnson

The Transformer



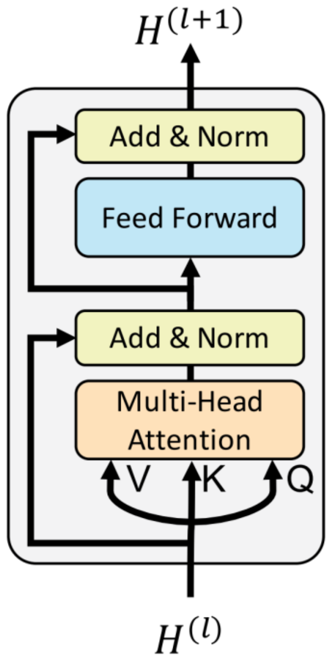
Encoder-Decoder

Vaswani et al, “Attention is all you need”, NeurIPS 2017

From Transformers To BERT

Bert Architecture

Get rid of the decoder.



Encoder Block

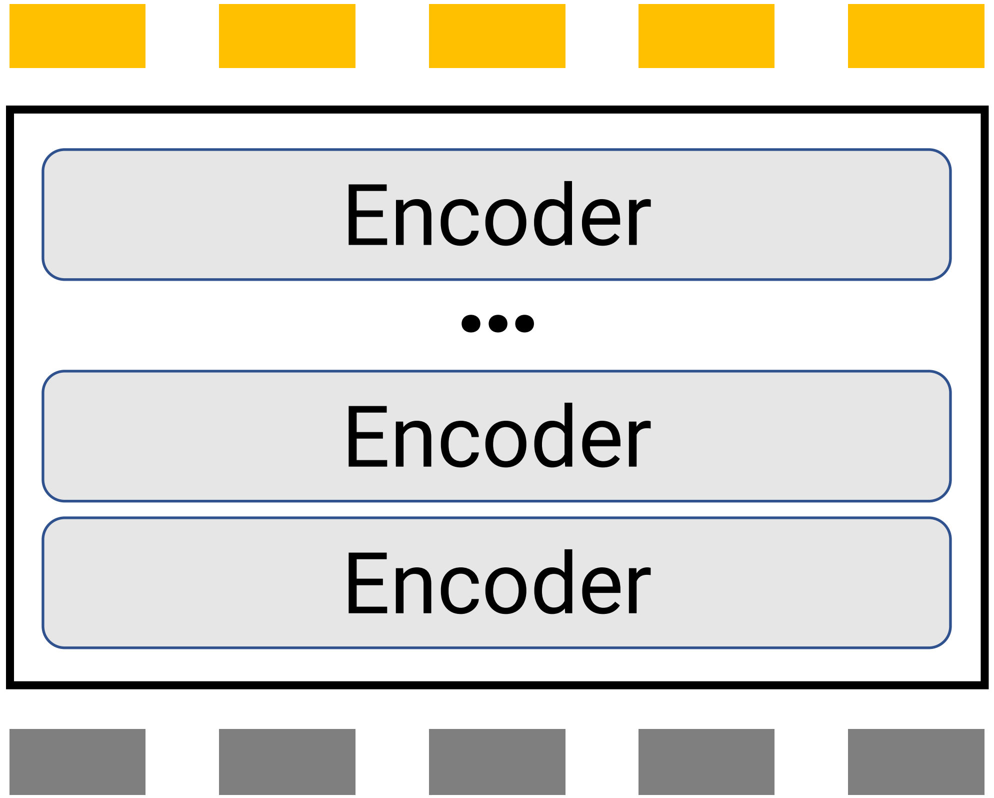
Devlin et al BERT: Pre-training of Deep Bidirectional Transformers for Language Understanding, 2018

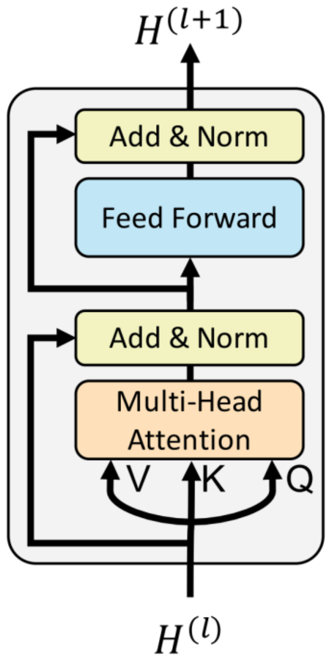
From Transformers To BERT

Bert Architecture

Get rid of the decoder.

Stack a series of Transformer encoder blocks.





Encoder Block

Devlin et al BERT: Pre-training of Deep Bidirectional Transformers for Language Understanding, 2018

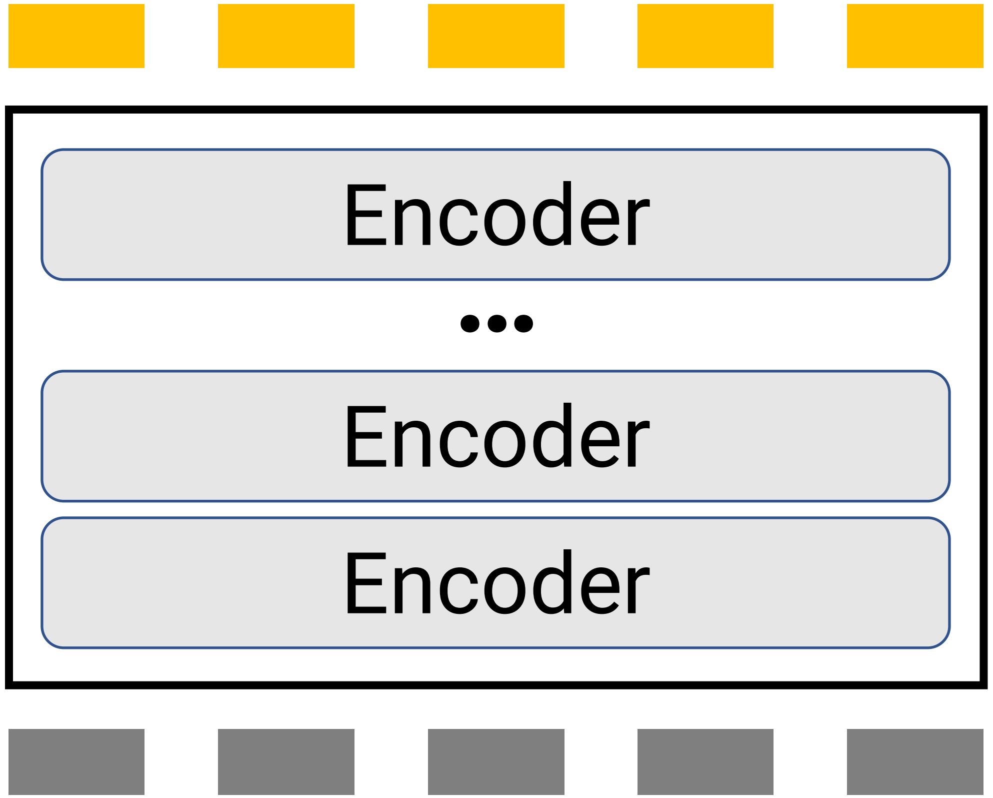
From Transformers To BERT

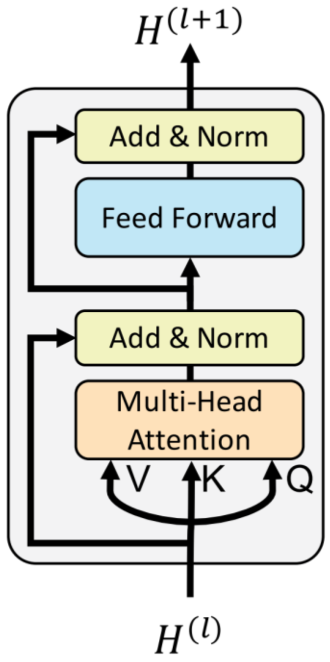
Bert Architecture

Get rid of the decoder.

Stack a series of Transformer encoder blocks.

Pre-train with *Masked Language Modeling* and *Next Sentence Prediction* (on massive datasets).





Encoder Block

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GLUE Benchmark

Rank	Name	Model	URL	Score	CoLA	SST-2	MRPC	STS-B	QQP	MNLI-m	MNLI-mm	QNLI	RTE	WNLI	AX
1	HFL iFLYTEK	MacALBERT + DKM		90.7	74.8	97.0	94.5/92.6	92.8/92.6	74.7/90.6	91.3	91.1	97.8	92.0	94.5	52.6
2	Alibaba DAMO NLP	StructBERT + TAPT		90.6	75.3	97.3	93.9/91.9	93.2/92.7	74.8/91.0	90.9	90.7	97.4	91.2	94.5	49.1
3	PING-AN Omni-Sinitic	ALBERT + DAAF + NAS		90.6	73.5	97.2	94.0/92.0	93.0/92.4	76.1/91.0	91.6	91.3	97.5	91.7	94.5	51.2
4	ERNIE Team - Baidu	ERNIE		90.4	74.4	97.5	93.5/91.4	93.0/92.6	75.2/90.9	91.4	91.0	96.6	90.9	94.5	51.7
5	T5 Team - Google	T5		90.3	71.6	97.5	92.8/90.4	93.1/92.8	75.1/90.6	92.2	91.9	96.9	92.8	94.5	53.1
6	Microsoft D365 AI & MSR AI & GATECH	MT-DNN-SMART		89.9	69.5	97.5	93.7/91.6	92.9/92.5	73.9/90.2	91.0	90.8	99.2	89.7	94.5	50.2
7	Zihang Dai	Funnel-Transformer (Ensemble B10-10-10H1024)		89.7	70.5	97.5	93.4/91.2	92.6/92.3	75.4/90.7	91.4	91.1	95.8	90.0	94.5	51.6
8	ELECTRA Team	ELECTRA-Large + Standard Tricks		89.4	71.7	97.1	93.1/90.7	92.9/92.5	75.6/90.8	91.3	90.8	95.8	89.8	91.8	50.7
9	Huawei Noah's Ark Lab	NEZHA-Large		89.1	69.9	97.3	93.3/91.0	92.4/91.9	74.2/90.6	91.0	90.7	95.7	88.7	93.2	47.9
10	Microsoft D365 AI & UMD	FreeLB-RoBERTa (ensemble)		88.4	68.0	96.8	93.1/90.8	92.3/92.1	74.8/90.3	91.1	90.7	95.6	88.7	89.0	50.1
11	Junjie Yang	HIRE-RoBERTa		88.3	68.6	97.1	93.0/90.7	92.4/92.0	74.3/90.2	90.7	90.4	95.5	87.9	89.0	49.3
12	Facebook AI	RoBERTa		88.1	67.8	96.7	92.3/89.8	92.2/91.9	74.3/90.2	90.8	90.2	95.4	88.2	89.0	48.7
13	Microsoft D365 AI & MSR AI	MT-DNN-ensemble		87.6	68.4	96.5	92.7/90.3	91.1/90.7	73.7/89.9	87.9	87.4	96.0	86.3	89.0	42.8
14	GLUE Human Baselines	GLUE Human Baselines		87.1	66.4	97.8	86.3/80.8	92.7/92.6	59.5/80.4	92.0	92.8	91.2	93.6	95.9	-
15	Stanford Hazy Research	Snorkel MeTaL		83.2	63.8	96.2	91.5/88.5	90.1/89.7	73.1/89.9	87.6	87.2	93.9	80.9	65.1	39.9

source: https://gluebenchmark.com/leaderboard

GLUE Benchmark

Rank	Name	Model	URL	Score	CoLA	SST-2	MRPC	STS-B	QQP	MNLI-m	MNLI-mm	QNLI	RTE	WNLI	AX
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4	ERNIE Team - Baidu	ERNIE		90.4	74.4	97.5	93.5/91.4	93.0/92.6	75.2/90.9	91.4	91.0	96.6	90.9	94.5	51.7
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9	Huawei Noah's Ark Lab	NEZHA-Large		89.1	69.9	97.3	93.3/91.0	92.4/91.9	74.2/90.6	91.0	90.7	95.7	88.7	93.2	47.9
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15	Stanford Hazy Research	Snorkel MeTaL		83.2	63.8	96.2	91.5/88.5	90.1/89.7	73.1/89.9	87.6	87.2	93.9	80.9	65.1	39.9

source: https://gluebenchmark.com/leaderboard

SuperGLUE

Leaderboard Version: **2.0**

Rank	Name	Model	URL	Score	BoolQ	CB	COPA	MultiRC	ReCoRD	RTE	WiC	WSC	AX-b	AX-g
1	SuperGLUE Human Baselines	SuperGLUE Human Baselines		89.8	89.0	95.8/98.9	100.0	81.8/51.9	91.7/91.3	93.6	80.0	100.0	76.6	99.3/99.7
2	T5 Team - Google	T5		89.3	91.2	93.9/96.8	94.8	88.1/63.3	94.1/93.4	92.5	76.9	93.8	65.6	92.7/91.9
3	Huawei Noah's Ark Lab	NEZHA-Plus		86.7	87.8	94.4/96.0	93.6	84.6/55.1	90.1/89.6	89.1	74.6	93.2	58.0	87.1/74.4
4	Alibaba PAI&ICBU	PAI Albert		86.1	88.1	92.4/96.4	91.8	84.6/54.7	89.0/88.3	88.8	74.1	93.2	75.6	98.3/99.2
5	Tencent Jarvis Lab	RoBERTa (ensemble)		85.9	88.2	92.5/95.6	90.8	84.4/53.4	91.5/91.0	87.9	74.1	91.8	57.6	89.3/75.6
6	Zhuiyi Technology	RoBERTa-mtl-adv		85.7	87.1	92.4/95.6	91.2	85.1/54.3	91.7/91.3	88.1	72.1	91.8	58.5	91.0/78.1
7	Facebook AI	RoBERTa		84.6	87.1	90.5/95.2	90.6	84.4/52.5	90.6/90.0	88.2	69.9	89.0	57.9	91.0/78.1
8	Infosys : DAWN : AI Research	RoBERTa-iCETS		77.4	84.7	88.2/91.6	85.8	78.4/37.5	82.9/82.4	83.8	69.1	65.1	35.2	93.8/68.8
9	Timo Schick	iPET (ALBERT) - Few-Shot (32 Examples)		75.4	81.2	79.9/88.8	90.8	74.1/31.7	85.9/85.4	70.8	49.3	88.4	36.2	97.8/57.9
10	IBM Research AI	BERT-mtl		73.5	84.8	89.6/94.0	73.8	73.2/30.5	74.6/74.0	84.1	66.2	61.0	29.6	97.8/57.3
11	Ben Mann	GPT-3 few-shot - OpenAI		71.8	76.4	52.0/75.6	92.0	75.4/30.5	91.1/90.2	69.0	49.4	80.1	21.1	90.4/55.3
12	SuperGLUE Baselines	BERT++		71.5	79.0	84.8/90.4	73.8	70.0/24.1	72.0/71.3	79.0	69.6	64.4	38.0	99.4/51.4
		BERT		69.0	77.4	75.7/83.6	70.6	70.0/24.1	72.0/71.3	71.7	69.6	64.4	23.0	97.8/51.7

source: https://super.gluebenchmark.com/leaderboard

SYSTEM PROMPT (HUMAN-WRITTEN)
In a shocking finding, scientist discovered a herd of unicorns living in a remote, previously unexplored valley, in the Andes Mountains. Even more surprising to the researchers was the fact that the unicorns spoke perfect English.

MODEL COMPLETION (MACHINE-WRITTEN, 10 TRIES)
The scientist named the population, after their distinctive horn, Ovid's Unicorn. These four-horned, silver-white unicorns were previously unknown to science.

Now, after almost two centuries, the mystery of what sparked this odd phenomenon is finally solved.

Dr. Jorge Pérez, an evolutionary biologist from the University of La Paz, and several companions, were exploring the Andes Mountains when they found a small valley, with no other animals or humans. Pérez noticed that the valley had what appeared to be a natural fountain, surrounded by two peaks of rock and silver snow.

Pérez and the others then ventured further into the valley. "By the time we reached the top of one peak, the water looked blue, with some crystals on top," said Pérez.

Source: OpenAI, "Better Language Models and Their Implications"
https://openai.com/blog/better-language-models/

Can Attention/Transformers be used from more than text processing?

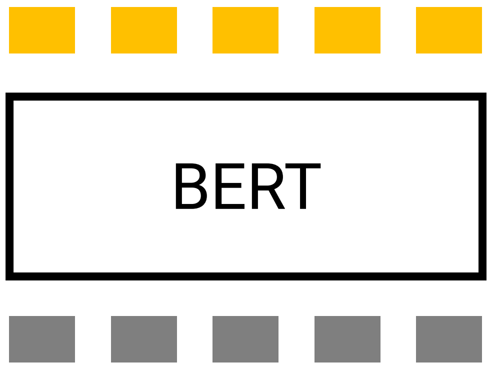
ViLBERT: A Visolinguistic Transformer

Lu et al "Vilbert: Pretraining task-agnostic visiolinguistic representations for vision-and-language tasks." *NeurIPS*. 2019.

ViLBERT: A Visolinguistic Transformer

ViLBERT Architecture

Start with a pre-trained BERT model.



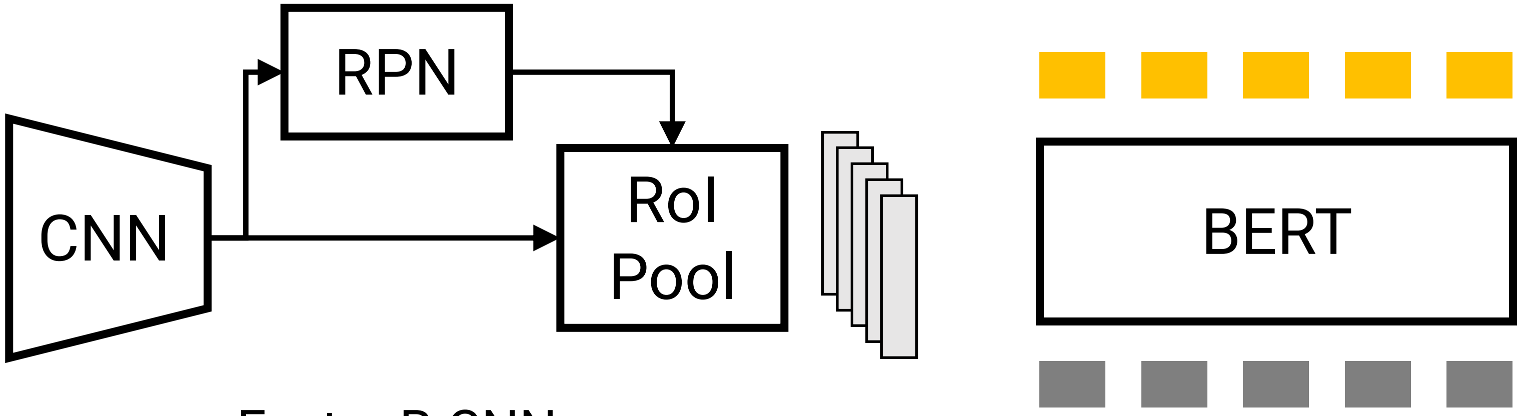
Lu et al "Vilbert: Pretraining task-agnostic visiolinguistic representations for vision-and-language tasks." *NeurIPS*. 2019.

ViLBERT: A Visolinguistic Transformer

<u>ViLBERT Architecture</u>

Start with a pre-trained BERT model.

Extract regions from an image using pre-trained detector.



Faster R-CNN

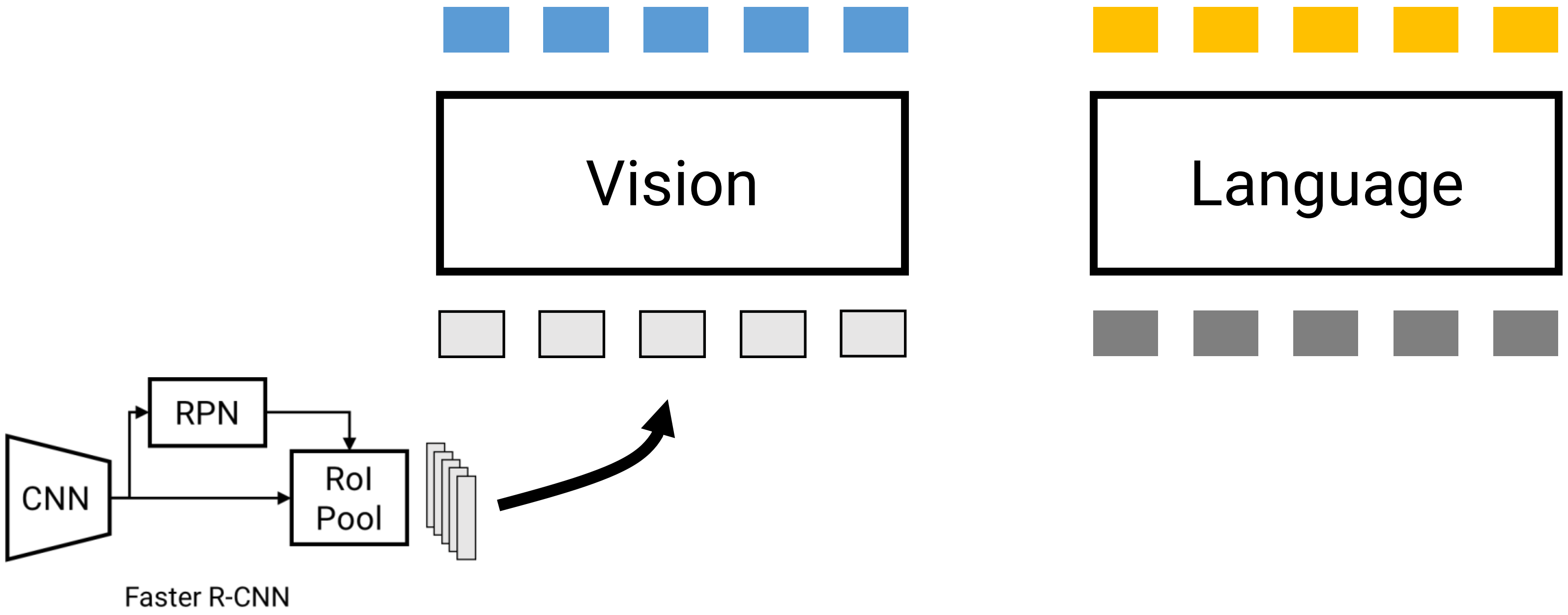
Lu et al "Vilbert: Pretraining task-agnostic visiolinguistic representations for vision-and-language tasks." *NeurIPS*. 2019.
Ren et al. "Faster r-cnn: Towards real-time object detection with region proposal networks." *NeurIPS*. 2015.

ViLBERT: A Visolinguistic Transformer

ViLBERT Architecture
Start with a pre-trained BERT model.

Extract regions from an image using pre-trained detector.

Use another BERT-like model to process the visual “tokens.”



Lu et al "Vilbert: Pretraining task-agnostic visiolinguistic representations for vision-and-language tasks." *NeurIPS*. 2019.
Ren et al. "Faster r-cnn: Towards real-time object detection with region proposal networks." *NeurIPS*. 2015.

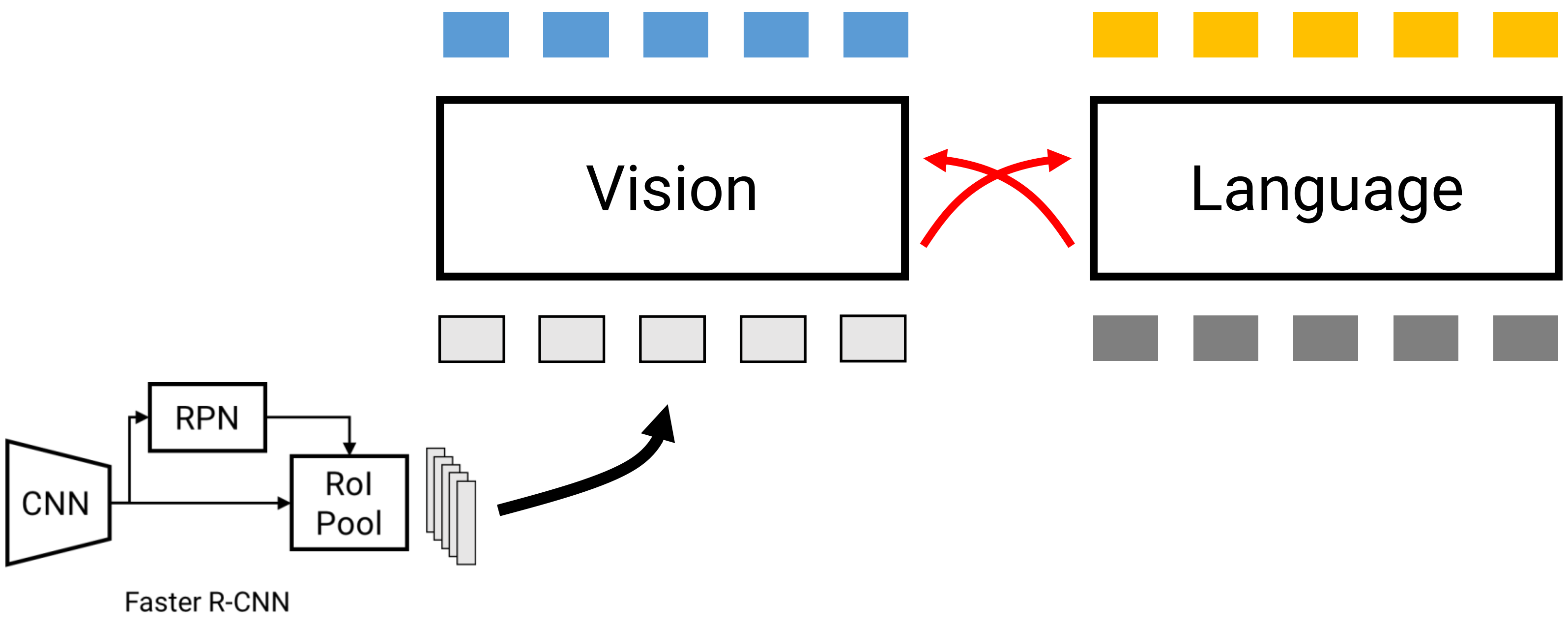
ViLBERT: A Visolinguistic Transformer

<u>ViLBERT Architecture</u>
Start with a pre-trained BERT model.

Extract regions from an image using pre-trained detector.

Use another BERT-like model to process the visual "tokens."

Connect the vision and language processing!

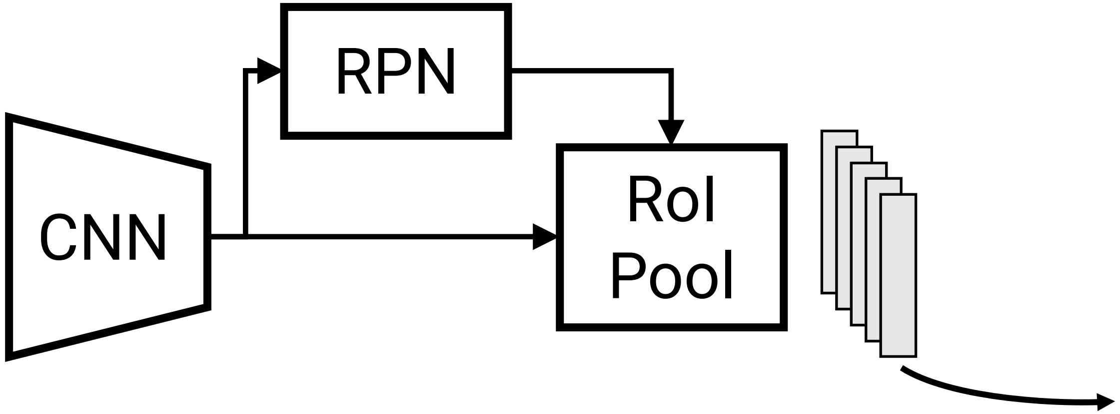


Lu et al "Vilbert: Pretraining task-agnostic visiolinguistic representations for vision-and-language tasks." *NeurIPS*. 2019.
Ren et al. "Faster r-cnn: Towards real-time object detection with region proposal networks." *NeurIPS*. 2015.

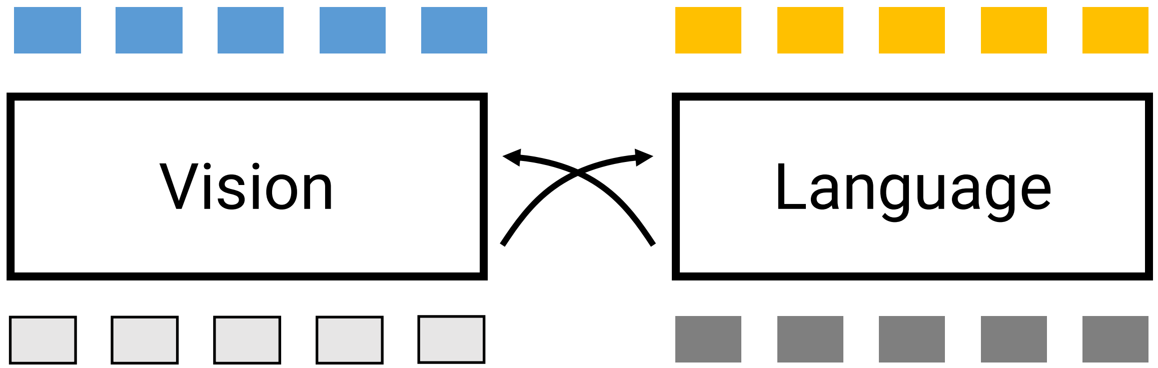
ViLBERT: A Visolinguistic Transformer

Visual Encoder

Visual and Language Processing



Faster R-CNN



BERT-Like Model

Lu et al "Vilbert: Pretraining task-agnostic visiolinguistic representations for vision-and-language tasks." *NeurIPS*. 2019.
Ren et al. "Faster r-cnn: Towards real-time object detection with region proposal networks." *NeurIPS*. 2015.

ViLBERT Pre-Training

pop artist performs at the festival in a city.

a worker helps to clear the debris.

blue sofa in the living room.

Image and captions from: Sharma, Piyush, et al. "Conceptual captions: A cleaned, hypernymed, image alt-text dataset for automatic image captioning." ACL. 2018.

ViLBERT Pre-Training

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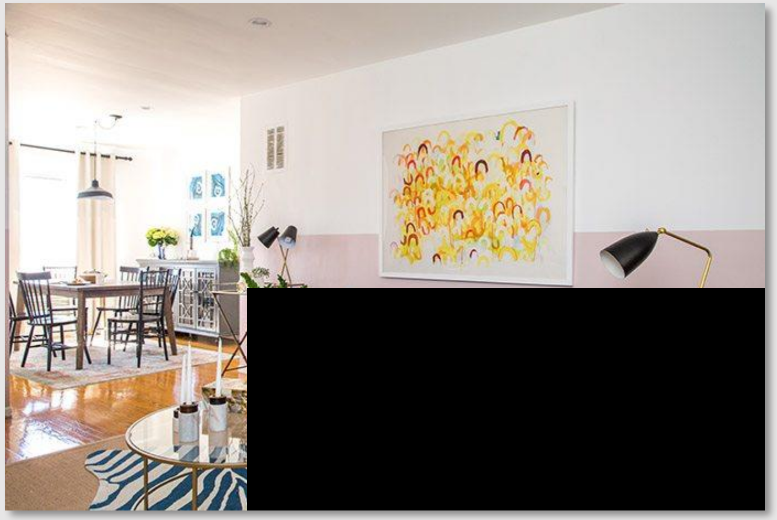


blue sofa in the living room.

Image and captions from: Sharma, Piyush, et al. "Conceptual captions: A cleaned, hypernymed, image alt-text dataset for automatic image captioning." ACL. 2018.

ViLBERT Pre-Training

pop artist performs at the festival in a city.

a worker helps to clear the debris.

[redacted] in the living room.

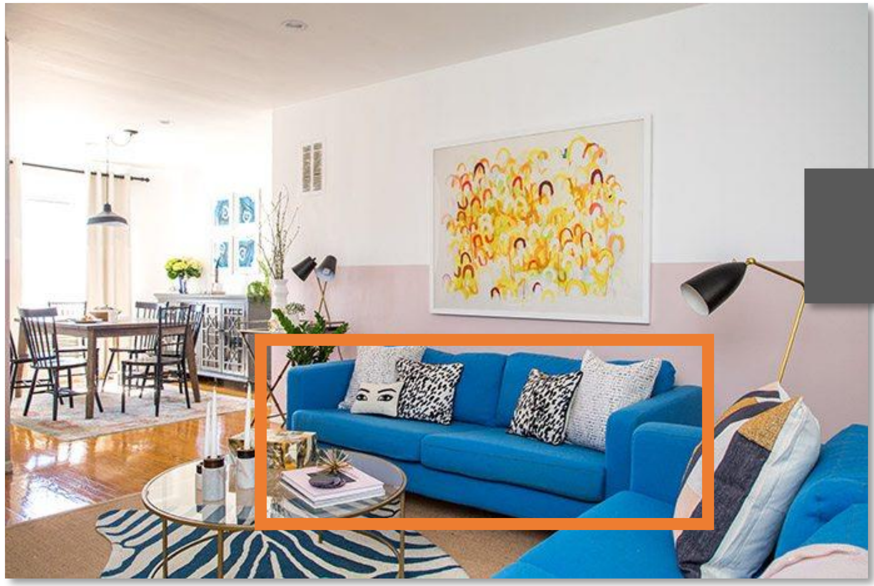
Image and captions from: Sharma, Piyush, et al. "Conceptual captions: A cleaned, hypernymed, image alt-text dataset for automatic image captioning." ACL. 2018.

ViLBERT Demo:
https://vilbert.cloudcv.org/

VLN-BERT: Transformers for VLN

Large-scale Web Data
(Conceptual Captions)

Embodied Visual Navigation
(Room-to-Room)



Transfer Grounding

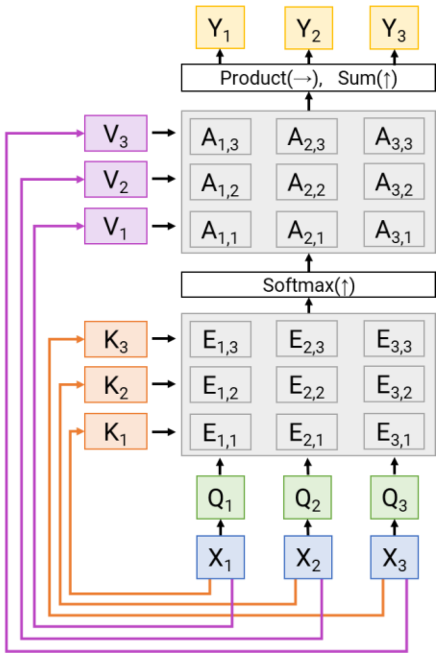
Blue sofa in the living room.

Walk through the bedroom and out of the door into the hallway. Walk down the hall along the banister rail through the open door. Continue into the bedroom with a round mirror on the wall and butterfly sculpture.

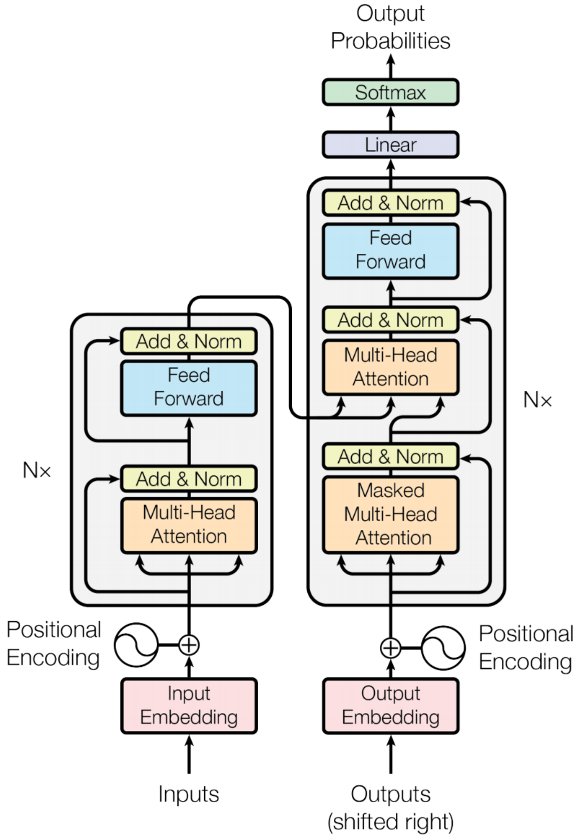
Majumdar et al. "Improving Vision-and-Language Navigation with Image-Text Pairs from the Web." *ECCV* 2020

Summary

Self-Attention



Transformer Model



ViLBERT