Topics:

- Linear Classification, Loss functions
- Gradient Descent

CS 4803-DL / 7643-A ZSOLT KIRA

- Assignment 1 out today!
 - Start early, start early, start early!
- **Piazza:** Enroll now! https://piazza.com/class/kjsselshfiz18c (Code: DL2021)
 - NOTE: There is an OMSCS section with a DIFFERENT piazza. Make sure you are in the right one
- Office hours start this week

Parametric Model

Explicitly model the function $f: X \to Y$ in the form of a parametrized function f(x, W) = y, **examples**:

- Logistic regression/classification
- Neural networks

Capacity (size of hypothesis class) **does not** grow with size of training data!

Parametric - Linear Classifier

$$f(x,W) = Wx + b$$

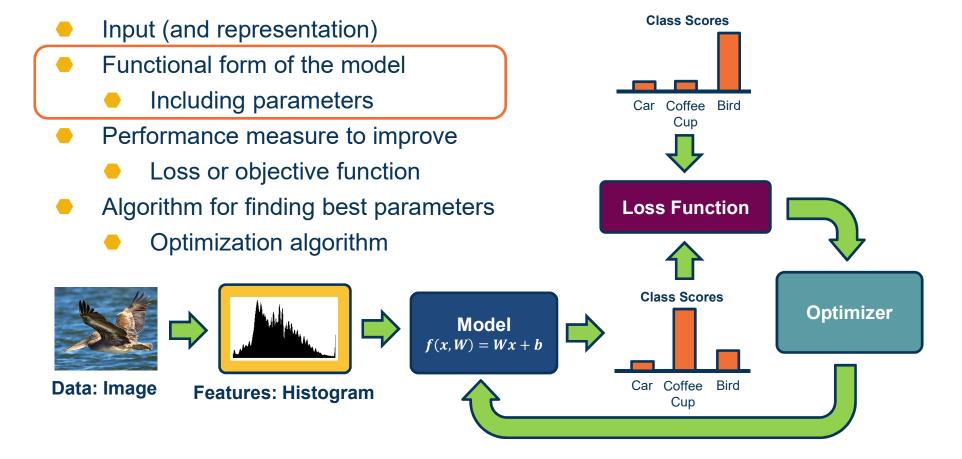
Procedure:

Calculate score per class for example

Return label of maximum score (argmax)

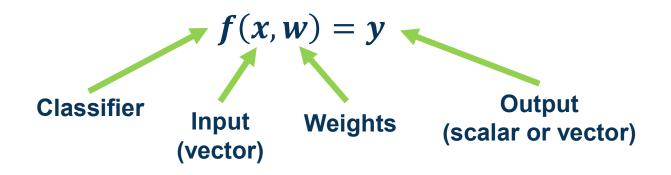
Learning is **search**





Components of a Parametric Model





- Input: Continuous number or vector
- Output: A continuous number
 - For classification typically a score
 - For regression what we want to regress to (house prices, crime rate, etc.)
- w is a vector and weights to optimize to fit target function

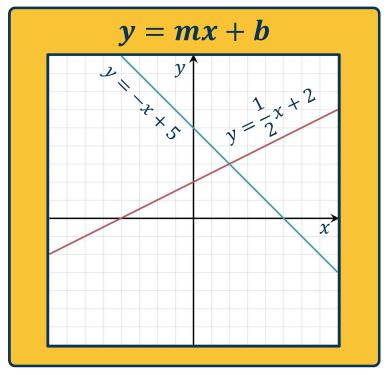


Neural Network

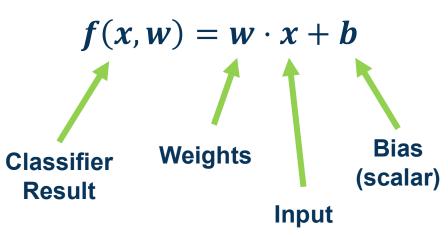


Slide Credit: Fei-Fei Li, Justin Johnson, Serena Yeung, CS 231n

What is the **simplest function** you can think of?



Our model is:



(Note if w and x are column vectors we often show this as $w^T x$)

Image adapted from:

https://en.wikipedia.org/wiki/Linear_equation#/media/File:Linear_Function_Graph.svg

Simple Function



Linear Classification and Regression

Simple linear classifier:

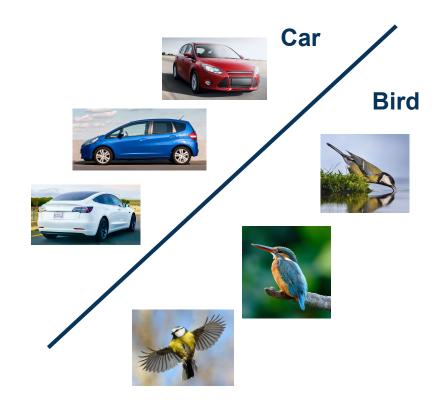
- Calculate score: $f(x, w) = w \cdot x + b$
- Binary classification rule (w is a vector):

$$y = \begin{cases} 1 & \text{if } f(x, w) > = 0 \\ 0 & \text{otherwise} \end{cases}$$

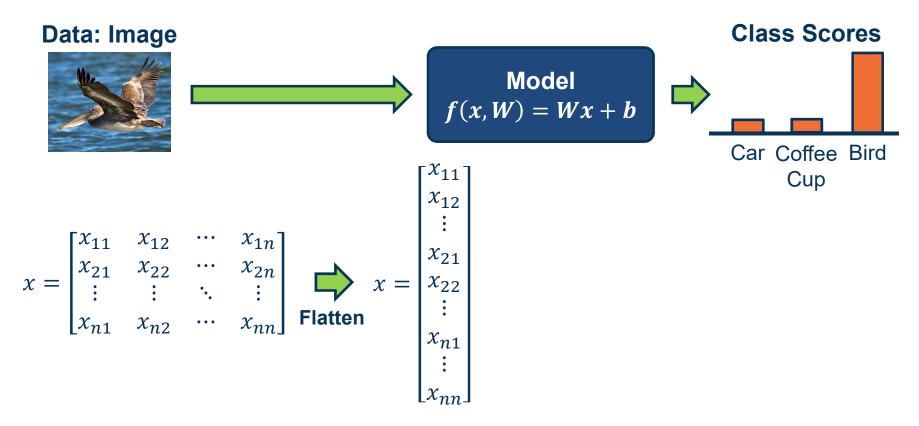
For multi-class classifier take class with highest (max) score f(x, W) = Wx + b



- Idea: Separate classes via high-dimensional linear separators (hyper-planes)
- One of the simplest parametric models, but surprisingly effective
 - Very commonly used!
- Let's look more closely at each element







To simplify notation we will refer to inputs as $x_1 \cdots x_m$ where $m = n \times n$

Classifier for class 1
$$\longrightarrow$$
 $\begin{bmatrix} w_{11} & w_{12} & \cdots & w_{1m} \\ w_{21} & w_{22} & \cdots & w_{2m} \\ w_{31} & w_{32} & \cdots & w_{3m} \end{bmatrix}$ $\begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_m \end{bmatrix} + \begin{bmatrix} b_1 \\ b_2 \\ b_3 \end{bmatrix}$

(Note that in practice, implementations can use xW instead, assuming a different shape for W. That is just a different convention and is equivalent.)

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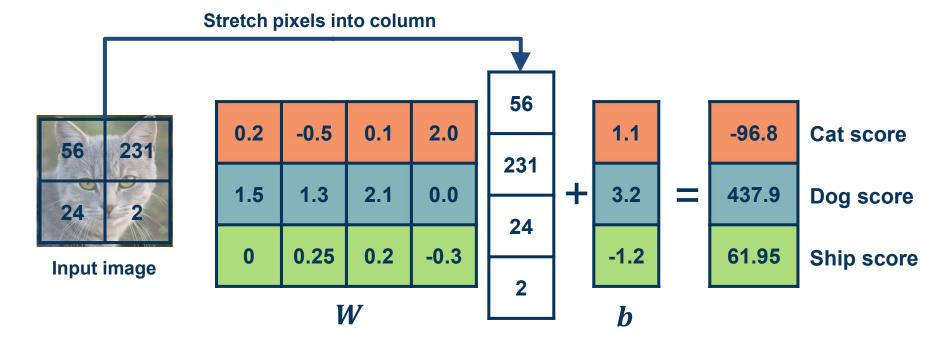
- We can move
 the bias term
 into the weight
 matrix, and a "1"
 at the end of the
 input
- Results in one matrix-vector multiplication!

$$\begin{bmatrix} w_{11} & w_{12} & \cdots & w_{1m} & b_1 \\ w_{21} & w_{22} & \cdots & w_{2m} & b_2 \\ w_{31} & w_{32} & \cdots & w_{3m} & b_3 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_m \\ 1 \end{bmatrix}$$

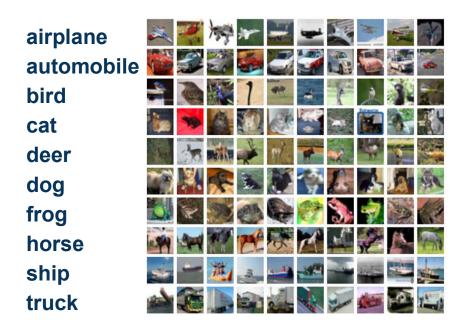
$$W$$

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Example with an image with 4 pixels, and 3 classes (cat/dog/ship)





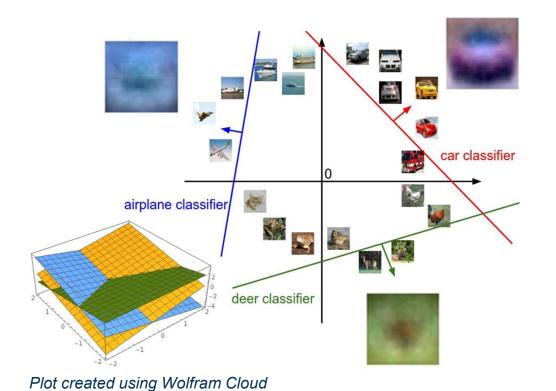


Visual Viewpoint

We can convert the weight vector back into the shape of the image and visualize







Geometric Viewpoint

$$f(x,W)=Wx+b$$



Array of **32x32x3** numbers (3072 numbers total)

Adapted from slides by Fei-Fei Li, Justin Johnson, Serena Yeung, from CS 231n

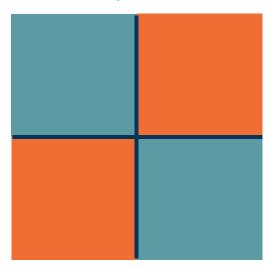
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Class 1:

number of pixels > 0 odd

Class 2:

number of pixels > 0 even



Class 1:

1 < = L2 norm < = 2

Class 2:

Everything else

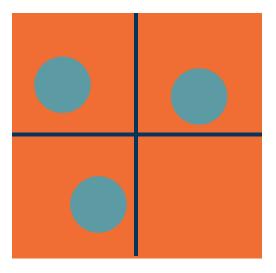


Class 1:

Three modes

Class 2:

Everything else

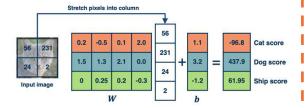






Algebraic Viewpoint

$$f(x, W) = Wx$$



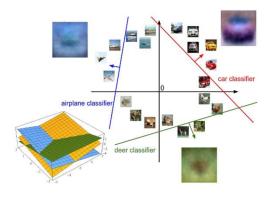
Visual Viewpoint

One template per class



Geometric Viewpoint

Hyperplanes cutting up space



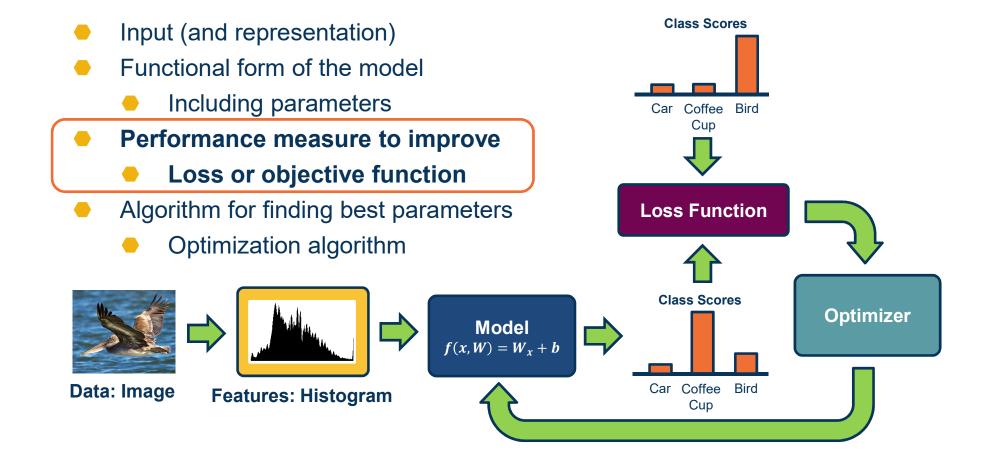
Adapted from slides by Fei-Fei Li, Justin Johnson, Serena Yeung, from CS 231n

Linear Classifier: Three Viewpoints



Performance Measure for a Classifier





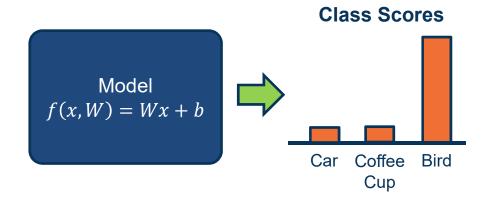
Components of a Parametric Model



- The output of a classifier can be considered a score
- For binary classifier, use rule:

$$y = \begin{cases} 1 & \text{if } f(x, w) > = 0 \\ 0 & \text{otherwise} \end{cases}$$

- Can be used for many classes by considering one class versus all the rest (one versus all)
- For multi-class classifier can take the maximum



Classification using Scores



Several issues with scores:

Not very interpretable (no bounded value)

We often want probabilities

- More interpretable
- Can relate to probabilistic view of machine learning

We use the **softmax** function to convert scores to probabilities

$$s = f(x, W)$$
 Scores

$$P(Y = k | X = x) = \frac{e^{s_k}}{\sum_j e^{s_j}}$$
 Softmax Function

We need a performance measure to **optimize**

- Penalizes model for being wrong
- Allows us to modify the model to reduce this penalty
- Known as an objective or loss function

In machine learning we use **empirical risk minimization**

- Reduce the loss over the training dataset
- We average the loss over the training data

Given a dataset of examples:

$$\{(x_i, y_i)\}_{i=1}^N$$

Where x_i is image and y_i is (integer) label

Loss over the dataset is a sum of loss over examples:

$$L = \frac{1}{N} \sum L_1(f(x_i, W), y_i)$$

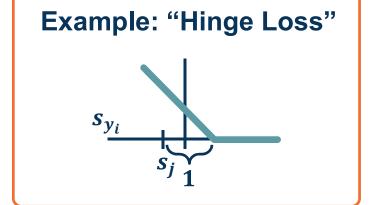
Given an example (x_i, y_i) where x_i is the image and where y_i is the (integer) label,



and using the shorthand for the scores vector: $s = f(x_i, W)$

the SVM loss has the form:

$$L_{i} = \sum_{j \neq y_{i}} \begin{cases} 0 & \text{if } s_{y_{i}} \geq s_{j} + 1 \\ s_{j} - s_{y_{i}} + 1 & \text{otherwise} \end{cases}$$
$$= \sum_{j \neq y_{i}} max(0, s_{j} - s_{y_{i}} + 1)$$



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Given an example $(x_{i,}y_{i})$ where x_{i} is the image and where y_{i} is the (integer) label,

and using the shorthand for the scores vector: $s = f(x_i, W)$

the SVM loss has the form:

$$L_i = \sum_{j \neq y_i} max(0, s_j - s_{y_i} + 1)$$

 $= \max(0, 5.1 - 3.2 + 1)$ $+ \max(0, -1.7 - 3.2 + 1)$

 $= \max(0, 2.9) + \max(0, -3.9)$

= 2.9 + 0

= 2.9

Suppose: 3 training examples, 3 classes. With some W the scores f(x,W)=Wx are:







cat

car

frog

Losses:

3.2

5.1

-1.7

2.9

1.3

4.9

2.0

2.2

2.5

-3.1

Adapted from slides by Fei-Fei Li, Justin Johnson, Serena Yeung, from CS 231n

SVM Loss Example



Given an example (x_i, y_i) where x_i is the image and where y_i is the (integer) label,

and using the shorthand for the scores vector: $s = f(x_i, W)$

the SVM loss has the form:

$$L_i = \sum_{j \neq y_i} max(0, s_j - s_{y_i} + 1)$$

 $= \max(0, 1.3 - 4.9 + 1)$ $+ \max(0, 2.0 - 4.9 + 1)$

= max(0, -2.6) + max(0, -1.9)

= 0 + 0

= 0

Suppose: 3 training examples, 3 classes. With some W the scores f(x,W)=Wx are:







cat

car

frog

3.2

5.1

-1.7

Losses:

1.3

4.9

2.0

0.0

2.2

2.5

-3.1

Adapted from slides by Fei-Fei Li, Justin Johnson, Serena Yeung, from CS 231n

SVM Loss Example



Given an example $(x_i y_i)$ where x_i is the image and where y_i is the (integer) label,

and using the shorthand for the scores vector: $s = f(x_i, W)$

the SVM loss has the form:

$$L_i = \sum_{j \neq y_i} max(0, s_j - s_{y_i} + 1)$$

$$L = (2.9 + 0 + 12.9)/3$$

= **5.27**

Suppose: 3 training examples, 3 classes. With some W the scores f(x,W)=Wx are:





1.3



car

Losses:

3.2

-3.1

2.2

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SVM Loss Example



 $L_i = \sum_{j \neq y_i} max(0, s_j - s_{y_i} + 1)$

Q: What happens to loss if car image scores change a bit?

No change for small values

Suppose: 3 training examples, 3 classes. With some W the scores f(x,W)=Wx are:







cat	3.2	1.3	2.2
car	5.1	4.9	2.5
frog	-1.7	2.0	-3.1



Suppose: 3 training examples, 3 classes. With some W the scores f(x,W)=Wx are:

$$L_i = \sum_{j \neq y_i} max(0, s_j - s_{y_i} + 1)$$

Q: What is min/max of loss value?

[0,inf]

		4	
6			
	0	9	





cat	3.2	1.3	2.2
car	5.1	4.9	2.5
frog	-1.7	2.0	-3.1



Suppose: 3 training examples, 3 classes. With some W the scores f(x,W)=Wx are:

$$L_i = \sum_{j \neq y_i} max(0, s_j - s_{y_i} + 1)$$

Q: At initialization W is small so all s ≈ 0. What is the loss?

C-1

00	





cat	3.2	1.3	2.2
car	5.1	4.9	2.5
froa	-1.7	2.0	-3.1



Suppose: 3 training examples, 3 classes. With some W the scores f(x,W)=Wx are:

$L_i = \sum_{i \neq v_i}$	$max(0, s_j -$	s_{y_i} +	1)
—			

Q: What if the sum was over all classes? (including j = y_i)

No difference (add constant 1)

O	0





cat	3.2	1.3	2.2
car	5.1	4.9	2.5
frog	-1.7	2.0	-3.1



Suppose: 3 training examples, 3 classes. With some W the scores f(x,W)=Wx are:

$L_i = \frac{1}{2}$	$\sum_{i\neq v_i}$	$max(0, s_j -$	s_{y_i} +	1)
- ι	$\angle_{j\neq y_i}$	110010 (0,5)	y_i	

Q: What if we used mean instead of sum?

No difference Scaling by constant







cat	3.2	1.3	2.2
car	5.1	4.9	2.5
frog	-1.7	2.0	-3.1



$$egin{aligned} f(x,W) &= Wx \ L &= rac{1}{N} \sum_{i=1}^N \sum_{j
eq y_i} \max(0,f(x_i;W)_j - f(x_i;W)_{y_i} + 1) \end{aligned}$$

E.g. Suppose that we found a W such that L = 0.

Q: Is this W unique?

No 2W also has L=0



- If we use the softmax function to convert scores to probabilities, the right loss function to use is cross-entropy
- Can be derived by looking at the distance between two probability distributions (output of model and ground truth)
- Can also be derived from a maximum likelihood estimation perspective

$$L_i = -\log P(Y = y_i | X = x_i)$$

Maximize log-prob of correct class =

Maximize the log likelihood

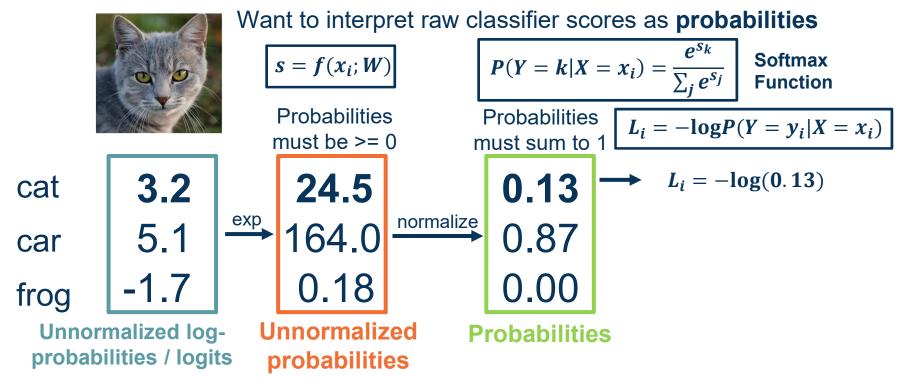
= Minimize the negative log likelihood



 If we use the softmax function to convert scores to probabilities, the right loss function to use is cross-entropy



Softmax Classifier (Multinomial Logistic Regression)





Softmax Classifier (Multinomial Logistic Regression)



Want to interpret raw classifier scores as probabilities

$$s = f(x_i; W)$$

Probabilities must be >= 0

$$P(Y = k|X = x_i) = \frac{e^{s_k}}{\sum_j e^{s_j}}$$
 Softmax Function

Probabilities must sum to 1 $L_i = -\log P(Y = y_i | X = x_i)$

$$L_i = -\log(0.13)$$

Q: What is the min/max of possible loss L_i?

Infimum is 0, max is unbounded (inf)



Softmax Classifier (Multinomial Logistic Regression)



Want to interpret raw classifier scores as **probabilities**

$$s = f(x_i; W)$$

Probabilities must be >= 0

$$P(Y = k | X = x_i) = \frac{e^{s_k}}{\sum_j e^{s_j}}$$
 Softmax Function

Probabilities must sum to 1 $L_i = -\log P(Y = y_i | X = x_i)$

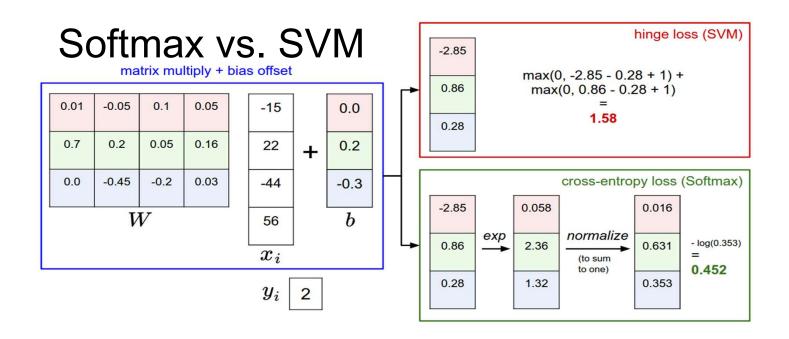
$$L_i = -\log(0.13)$$

Q: At initialization all s will be approximately equal; what is the loss?

Log(C), e.g. $log(10) \approx 2$

Adapted from slides by Fei-Fei Li, Justin Johnson, Serena Yeung, from CS 231n





Adapted from slides by Fei-Fei Li, Justin Johnson, Serena Yeung, from CS 231n



If we are performing regression, we can directly optimize to match the

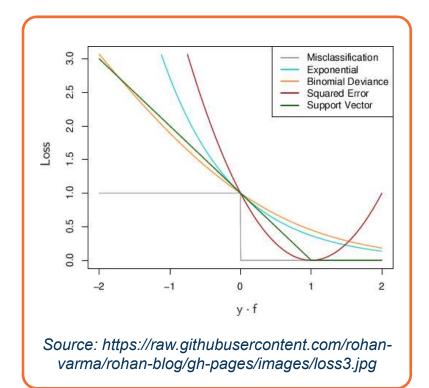
ground truth value

Example: House price prediction

$$L_i = |y - Wx_i| \qquad \text{L1}$$

$$L_i = |y - Wx_i|^2 \qquad \text{L2}$$

For probabilities $L_i = |y - Wx_i| = rac{e^{s_k}}{\sum_j e^{s_j}}$ Logistic



Often, we add a regularization term to the loss function

L1 Regularization

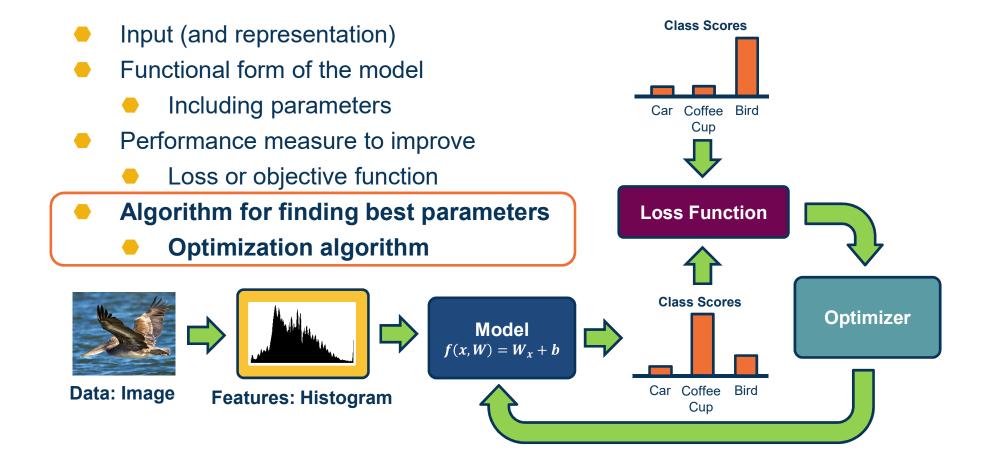
$$L_i = |y - Wx_i|^2 + |W|$$

Example regularizations:

L1/L2 on weights (encourage small values)

Gradient Descent





Components of a Parametric Model



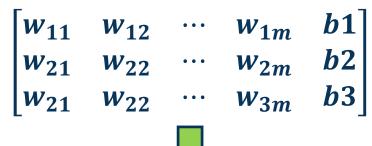
Given a model and loss function, finding the best set of weights is a **search problem**

 Find the best combination of weights that minimizes our loss function

Several classes of methods:

- Random search
- Genetic algorithms (population-based search)
- Gradient-based optimization

In deep learning, **gradient-based methods are dominant** although not the only approach possible





Loss

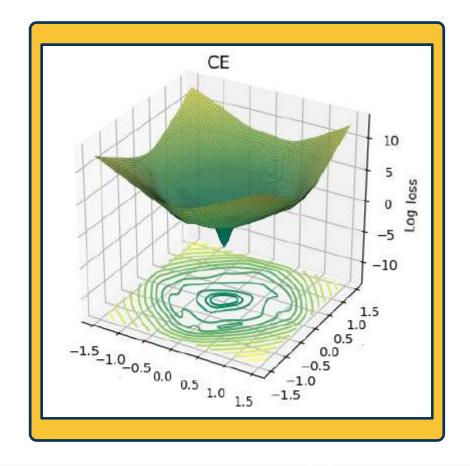
Optimization



As weights change, the loss changes as well

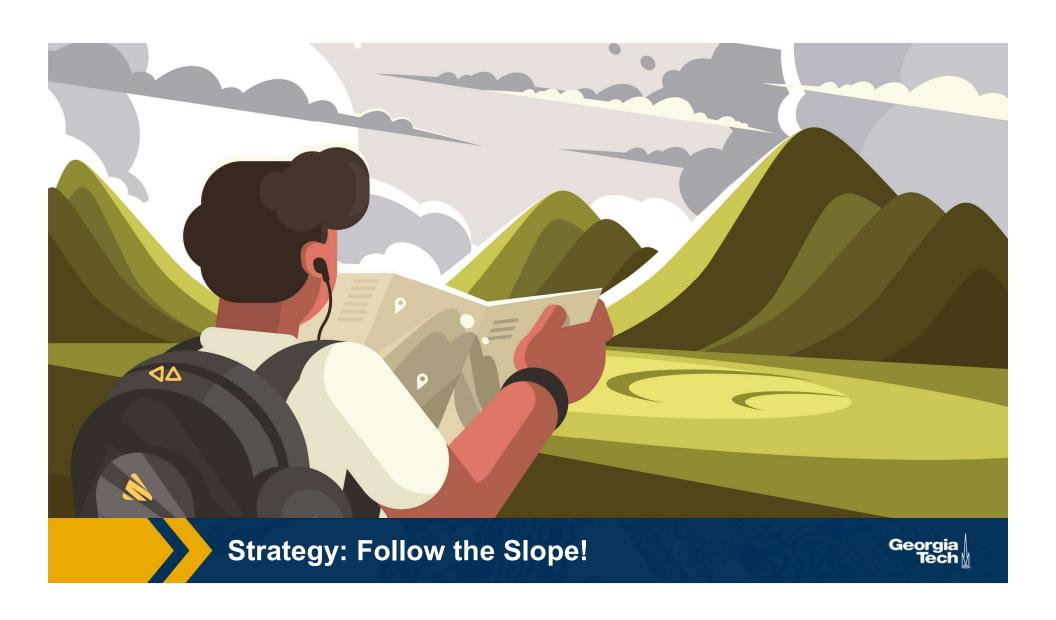
 This is often somewhatsmooth locally, so small changes in weights produce small changes in the loss

We can therefore think about iterative algorithms that take current values of weights and modify them a bit



Loss Surfaces

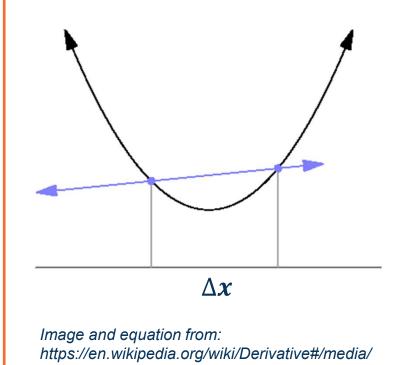




We can find the steepest descent direction by computing the derivative (gradient):

$$f'(a) = \lim_{h \to 0} \frac{f(a+h) - f(a)}{h}$$

- Steepest descent direction is the **negative** gradient
- **Intuitively:** Measures how the function changes as the argument a changes by a small step size
 - As step size goes to zero
- In Machine Learning: Want to know how the loss function changes as weights are varied
 - Can consider each parameter separately by taking partial derivative of loss function with respect to that parameter



File:Tangent animation.gif

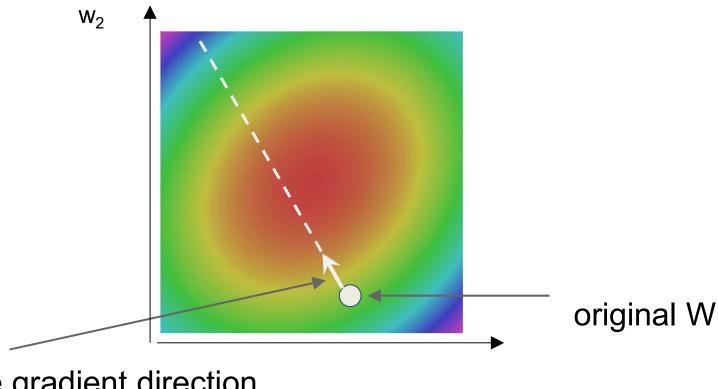
Derivatives



This idea can be turned into an algorithm (gradient descent)

- Choose a model: f(x, W) = Wx
- Choose loss function: $L_i = |y Wx_i|^2$
- Calculate partial derivative for each parameter: $\frac{\partial L}{\partial w_i}$
- Update the parameters: $w_i = w_i \frac{\partial L}{\partial w_i}$
- Add learning rate to prevent too big of a step: $w_i = w_i \alpha \frac{\partial L}{\partial w_i}$
- Repeat (from Step 3)

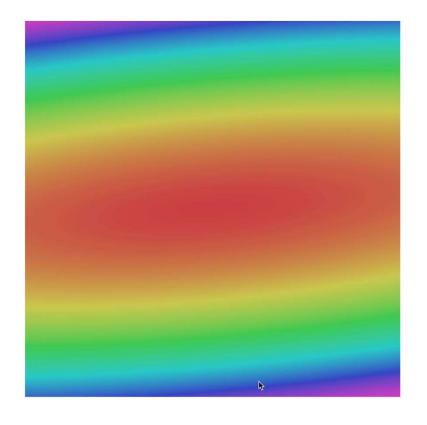
http://demonstrations.wolfram.com/VisualizingTheGradientVector/

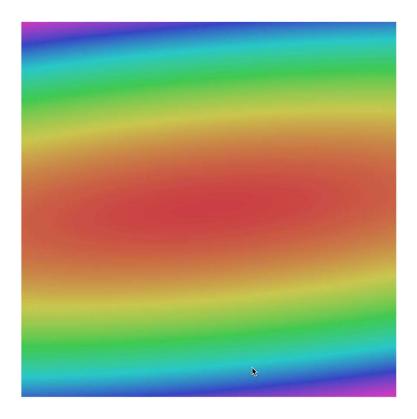


negative gradient direction

 W_1







Often, we only compute the gradients across a small subset of data

Full Batch Gradient Descent
$$L = \frac{1}{N} \sum L(f(x_i, W), y_i)$$

- Mini-Batch Gradient Descent $L = \frac{1}{M} \sum L(f(x_i, W), y_i)$
 - Where M is a subset of data
- We iterate over mini-batches:
 - Get mini-batch, compute loss, compute derivatives, and take a set

Gradient descent is guaranteed to converge under some conditions

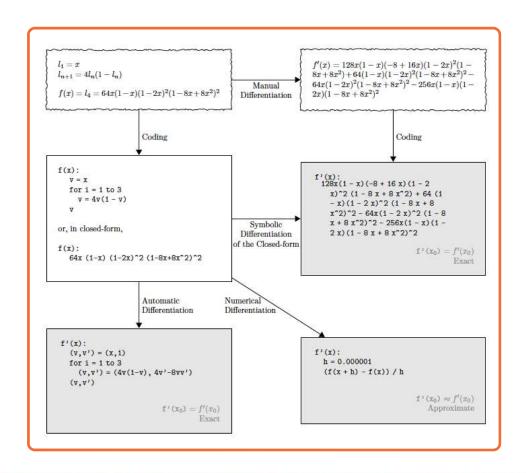
- For example, learning rate has to be appropriately reduced throughout training
- It will converge to a local minima
 - Small changes in weights would not decrease the loss
- It turns out that some of the local minima that it finds in practice (if trained well) are still pretty good!



We know how to compute the model output and loss function

Several ways to compute $\frac{\partial L}{\partial w_i}$

- Manual differentiation
- Symbolic differentiation
- Numerical differentiation
- Automatic differentiation



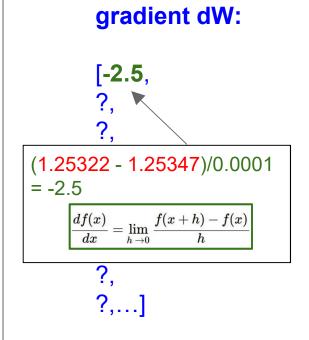
Computing Gradients



current W: gradient dW: [0.34, [?, -1.11, ?, 0.78, ?, 0.12, ?, 0.55, ?, 2.81, ?, -3.1, ?, -1.5, ?, 0.33,...] ?,...]

current W: W + h (first dim): gradient dW: [0.34 + 0.0001,[0.34, -1.11, -1.11, 0.78, 0.78, 0.12, 0.12, 0.55, 0.55, 2.81, 2.81, -3.1, -1.5, -1.5, 0.33,...] 0.33,...] loss 1.25322 loss 1.25347

W + h (first dim): current W: [0.34 + 0.0001,[0.34, -1.11, -1.11, 0.78, 0.78, 0.12, 0.12, 0.55, 0.55, 2.81, 2.81, -3.1, -3.1, -1.5, -1.5, 0.33,...] 0.33,...] loss 1.25347 loss 1.25322

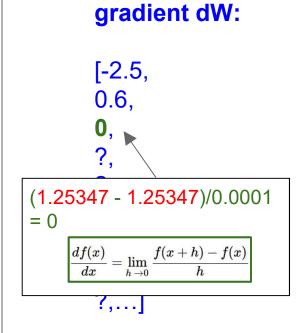


W + h (second dim): current W: gradient dW: [0.34, [0.34, [-2.5, -1.11, -1.11 + **0.0001**, 0.78, 0.78, 0.12, 0.12, 0.55, 0.55, 2.81, 2.81, -3.1, -1.5, 0.33,...] 0.33,...] loss 1.25347 loss 1.25353

W + h (second dim): current W: gradient dW: [0.34, [0.34,[-2.5, -1.11 + **0.0001**, -1.11, 0.78, 0.78, 0.12, 0.12, 0.55, 0.55, (1.25353 - 1.25347)/0.0001 2.81, 2.81, = 0.6-3.1, -3.1, $\dfrac{df(x)}{dx} = \lim_{h o 0} \dfrac{f(x+h) - f(x)}{h}$ -1.5, -1.5, 0.33,...] 0.33,...] ?,...] loss 1.25347 | loss 1.25353

W + h (third dim): current W: gradient dW: [0.34, [0.34, [-2.5, -1.11, -1.11, 0.6, 0.78, 0.78 + 0.0001, 0.12, 0.12, 0.55, 0.55, 2.81, 2.81, -3.1, -1.5, -1.5, 0.33,...] 0.33,...] loss 1.25347 loss 1.25347

W + h (third dim): current W: [0.34, [0.34, -1.11, -1.11, 0.78, 0.78 + 0.0001, 0.12, 0.12, 0.55, 0.55, 2.81, 2.81, -3.1, -1.5, -1.5, 0.33,...] 0.33,...] loss 1.25347 loss 1.25347



Numerical vs Analytic Gradients

$$rac{df(x)}{dx} = \lim_{h o 0} rac{f(x+h) - f(x)}{h}$$

Numerical gradient: slow:(, approximate:(, easy to write:)
Analytic gradient: fast:), exact:), error-prone:(

In practice: Derive analytic gradient, check your implementation with numerical gradient.
This is called a **gradient check**.

For some functions, we can analytically derive the partial derivative

Example:

Derivation of Update Rule

Function Loss
$$f(w, x_i) = w^T x_i \qquad (y_i - w^T x_i)^2$$

(Assume w and x_i are column vectors, so same as $w \cdot x_i$)

Update Rule

$$w_j \leftarrow w_j + 2\eta \sum_{k=1}^N \delta_k x_{kj}$$

For some functions, we can analytically derive the partial derivative

Example:

Function

Loss

$$f(w, x_i) = w^T x_i \qquad (y_i - w^T x_i)^2$$

(Assume w and x_i are column vectors, so same as $w \cdot x_i$)

Update Rule

$$w_j \leftarrow w_j + 2\eta \sum_{k=1}^N \delta_k x_{kj}$$

Derivation of Update Rule

$$\mathsf{L} = \sum_{k=1}^{N} (y_k - w^T x_k)^2$$

Gradient descent tells us we should update w as follows to minimize *L*:

$$w_j \leftarrow w_j - \eta \frac{\partial L}{\partial w_j}$$

So what's
$$\frac{\partial L}{\partial w_j}$$
?

L=
$$\sum_{k=1}^{N} (y_k - w^T x_k)^2$$
 $\frac{\partial L}{\partial w_j} = \sum_{k=1}^{N} \frac{\partial}{\partial w_j} (y_k - w^T x_k)^2$

= $\sum_{k=1}^{N} 2(y_k - w^T x_k) \frac{\partial}{\partial w_j} (y_k - w^T x_k)$

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= $\sum_{k=1}^{N} 2(y_k - w^T x_k) \frac{\partial}{\partial w_j} (y_k - w^T x_k)$

If we add a non-linearity (sigmoid), derivation is more complex

$$\sigma(x) = \frac{1}{1 + e^{-x}}$$

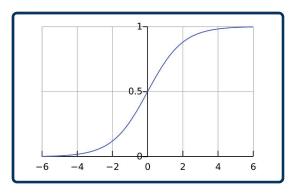
First, one can derive that: $\sigma'^{(x)} = \sigma(x)(1 - \sigma(x))$

where $\delta_i = y_i - f(x_i)$ $d_i = \sum w_k x_{ik}$

$$f(x) = \sigma\left(\sum_{k} w_{k} x_{k}\right)$$

$$L = \sum_{i} \left(y_i - \sigma \left(\sum_{k} w_k x_{ik} \right) \right)^2$$

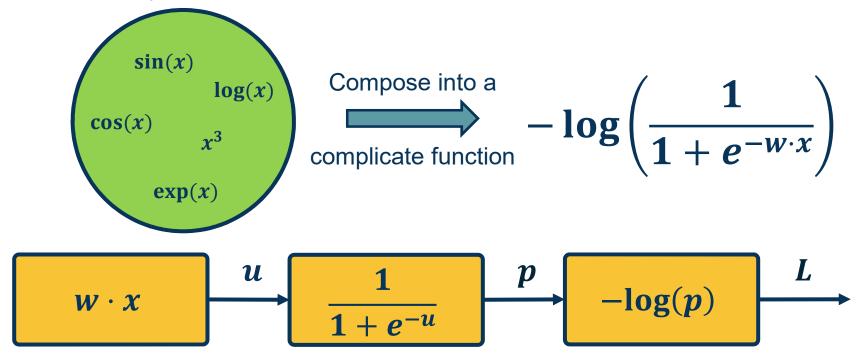
$$\frac{\partial L}{\partial w_j} = \sum_{i} 2 \left(y_i - \sigma \left(\sum_{k} w_k x_{ik} \right) \right) \left(-\frac{\partial}{\partial w_j} \sigma \left(\sum_{k} w_k x_{ik} \right) \right) \\
= \sum_{i} -2 \left(y_i - \sigma \left(\sum_{k} w_k x_{ik} \right) \right) \sigma' \left(\sum_{k} w_k x_{ik} \right) \frac{\partial}{\partial w_j} \sum_{k} w_k x_{ik} \\
= \sum_{i} -2 \delta_i \sigma(\mathbf{d}_i) (1 - \sigma(\mathbf{d}_i)) x_{ij}$$



The sigmoid perception update rule:

$$w_j \leftarrow w_j + 2\eta \sum_{k=1}^N \delta_i \sigma_i (1-\sigma_i) x_{ij}$$
 where $\sigma_i = \sigma \Biggl(\sum_{j=1}^m w_j x_{ij}\Biggr)$ $\delta_i = y_i - \sigma_i$

Given a library of simple functions



Adapted from slides by: Marc'Aurelio Ranzato, Yann LeCun

Linear
Algebra
View:
Vector and
Matrix Sizes



$$\begin{bmatrix} w_{11} & w_{12} & \cdots & w_{1m} & b1 \\ w_{21} & w_{22} & \cdots & w_{2m} & b2 \\ w_{31} & w_{32} & \cdots & w_{3m} & b3 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_m \\ 1 \end{bmatrix}$$

$$\boldsymbol{W}$$
 \boldsymbol{x}

Sizes:
$$[c \times (d + 1)]$$
 $[(d + 1) \times 1]$

Where c is number of classes

d is dimensionality of input

Georgia Tech <u>\</u>

Conventions:

- Size of derivatives for scalars, vectors, and matrices: Assume we have scalar $s \in \mathbb{R}^1$, vector $v \in \mathbb{R}^m$, i.e. $v = [v_1, v_2, ..., v_m]^T$ and matrix $M \in \mathbb{R}^{k \times \ell}$ $\frac{\partial v_1}{\partial s} \\
 \frac{\partial v_2}{\partial s} \\
 \vdots \\
 \partial v_m$
- What is the size of $\frac{\partial v}{\partial s}$? $\mathbb{R}^{m \times 1}$ (column vector of size m)
- What is the size of $\frac{\partial s}{\partial v}$? $\mathbb{R}^{1 \times m}$ (row vector of size m)

$$\left[\frac{\partial s}{\partial v_1} \frac{\partial s}{\partial v_1} \cdots \frac{\partial s}{\partial v_m}\right]$$

Conventions:

• What is the size of $\frac{\partial v^1}{\partial v^2}$? A matrix:

$$\begin{bmatrix} \frac{\partial v_1^1}{\partial v_1^2} & \dots & \dots & \dots \\ \frac{\partial v_1^1}{\partial v_j^2} & \dots & \dots & \dots \\ \dots & \frac{\partial v_i^1}{\partial v_j^2} & \dots & \dots \end{bmatrix}$$

Row i

This matrix of partial derivatives is called a Jacobian

(Note this is slightly different convention than on Wikipedia)

Conventions:

• What is the size of $\frac{\partial s}{\partial M}$? A matrix:

$$egin{bmatrix} rac{\partial s}{\partial m_{[1,1]}} & \cdots & \cdots & \cdots \\ & \cdots & & rac{\partial s}{\partial m_{[i,j]}} & \cdots & \cdots \\ & \cdots & & \cdots & \cdots \\ \end{pmatrix}$$

- What is the size of $\frac{\partial L}{\partial W}$?
 - Remember that loss is a scalar and W is a matrix:

$$\begin{bmatrix} w_{11} & w_{12} & \cdots & w_{1m} & b1 \\ w_{21} & w_{22} & \cdots & w_{2m} & b2 \\ w_{31} & w_{32} & \cdots & w_{3m} & b3 \end{bmatrix}$$

Jacobian is also a matrix:

$$\begin{bmatrix} \frac{\partial L}{\partial w_{11}} & \frac{\partial L}{\partial w_{12}} & \cdots & \frac{\partial L}{\partial w_{1m}} & \frac{\partial L}{\partial b_1} \\ \frac{\partial L}{\partial w_{21}} & \cdots & \cdots & \frac{\partial L}{\partial w_{2m}} & \frac{\partial L}{\partial b_2} \\ \cdots & \cdots & \cdots & \frac{\partial L}{\partial w_{3m}} & \frac{\partial L}{\partial b_3} \end{bmatrix}$$

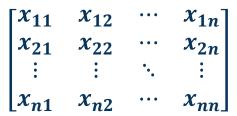
Batches of data are **matrices** or **tensors** (multi-dimensional matrices)

Examples:

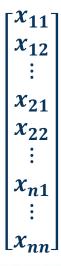
- Each instance is a vector of size m, our batch is of size $[B \times m]$
- Each instance is a matrix (e.g. grayscale image) of size $W \times H$, our batch is $[B \times W \times H]$
- Each instance is a multi-channel matrix (e.g. color image with R,B,G channels) of size C × W × H, our batch is [B × C × W × H]

Jacobians become tensors which is complicated

- Instead, flatten input to a vector and get a vector of derivatives!
- This can also be done for partial derivatives between two vectors, two matrices, or two tensors







Jacobians of Batches

